

**DP-50 Vet/DP-70 Vet/DP-50 Exp Vet**

**Digital Ultrasonic Diagnostic  
Imaging System**

**Operator's Manual**

**[Basic Volume]**



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## IMPORTANT!

**The system is veterinary use only.**

The following label applies to U.S.A. only.

### CAUTION

**U.S.A. Federal law restricts this device to sale by or on the order of a veterinarian.**

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Mindray is responsible for the effects on safety, reliability and performance of this product, only if:

- all installation operations, expansions, changes, modifications and repairs of this product are conducted by Mindray authorized personnel;
- the electrical installation of the relevant room complies with the applicable national and local requirements; and
- the product is used in accordance with the instructions for use.



**Note**

This equipment must be operated by skilled/trained clinical professionals.



**Warning**

It is important for the hospital or organization that employs this equipment to carry out a reasonable service/maintenance plan. Neglect of this may result in machine breakdown or personal injury.

## Warranty

THIS WARRANTY IS EXCLUSIVE AND IS IN LIEU OF ALL OTHER WARRANTIES, EXPRESSED OR IMPLIED, INCLUDING WARRANTIES OF MERCHANTABILITY OR FITNESS FOR ANY PARTICULAR PURPOSE.

### Exemptions

Mindray's obligation or liability under this warranty does not include any transportation or other charges or liability for direct, indirect or consequential damages or delay resulting from the improper use or application of the product or the use of parts or accessories not approved by Mindray or repairs by people other than Mindray authorized personnel.

**This warranty shall not extend to:**

- **Malfunction or damage caused by improper use or man-made failure.**
- **Malfunction or damage caused by unstable or out-of-range power input.**
- **Malfunction or damage caused by force majeure such as fire and earthquake.**
- **Malfunction or damage caused by improper operation or repair by unqualified or unauthorized service people.**
- **Malfunction of the instrument or part whose serial number is not legible enough.**
- **Others not caused by instrument or part itself.**

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# Important Information


1. It is the customer's responsibility to maintain and manage the system after delivery.
2. The warranty does not cover the following items, even during the warranty period:
  - (1) Damage or loss due to misuse or abuse.
  - (2) Damage or loss caused by Acts of God such as fires, earthquakes, floods, lightning, etc.
  - (3) Damage or loss caused by failure to meet the specified conditions for this system, such as inadequate power supply, improper installation or environmental conditions.
  - (4) Damage or loss due to use of the system outside the region where the system was originally sold.
  - (5) Damage or loss involving the system purchased from a source other than Mindray or its authorized agents.
3. This system shall not be used by persons other than fully qualified and certified medical personnel.
4. Do not make changes or modifications to the software or hardware of this system.
5. In no event shall Mindray be liable for problems, damage, or loss caused by relocation, modification, or repair performed by personnel other than those designated by Mindray.
6. The purpose of this system is to provide physicians with data for clinical diagnosis. It is the physician's responsibility for diagnostic procedures. Mindray shall not be liable for the results of diagnostic procedures.
7. Important data must be backed up on external memory media.
8. Mindray shall not be liable for loss of data stored in the memory of this system caused by operator error or accidents.
9. This manual contains warnings regarding foreseeable potential dangers, but you shall always be alert to dangers other than those indicated as well. Mindray shall not be liable for damage or loss that results from negligence or from ignoring the precautions and operating instructions described in this operator's manual.
10. If the manager for this system is changed, be sure to hand over this operator's manual to the new manager.

# About This Manual

This operator's manual describes the operating procedures for this diagnostic ultrasound system DP-50 Vet/DP-70 Vet/DP-50 Exp Vet and the compatible probes. To ensure safe and correct operations, carefully read and understand the manual before operating the system.

## Notation Conventions

In this operator's manual, the following words are used besides the safety precautions (refer to "Safety Precautions"). Please read this operator's manual before using the system.

 <b>CAUTION:</b>	<ol style="list-style-type: none"><li>1. <b>The diagnostic ultrasound system is not intended for ophthalmic use. Its use in this clinical specialty is contraindicated.</b></li><li>2. <b>United States federal law restricts this device to be sale by or on the order of a physician.</b></li></ol>
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## Operator's Manuals

Please read the operator's manuals carefully before operating the system.

The content of the operator manual, such as screens, menus or descriptions, may be different from what you see in your system. The content varies depending upon the software version, options and configuration of the system.

## Manuals on Paper

- Operator's Manual [Basic Volume]: Describes the basic functions and operations of the system, safety precautions, exam modes, imaging modes, preset, maintenance and acoustic output, etc.
- Operator's Manual [Advanced Volume]: Describes measurement preset, measurements and calculations, etc.
- Operation Note: Contains quick guide for basic operations of the system.

<b>NOTE:</b> The accompanying manuals may vary depending upon the specific system you purchased. Please refer to the packing list.
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## Software Interfaces in this Manual

Depending on the software version, preset settings and optional configuration, the actual interfaces may be different from those in this manual.

# Conventions

In this manual, these conventions are used to describe the buttons on the control panel, the items in menu, buttons in dialog box and some basic operations:

- <Buttons>: The angular bracket indicates buttons, knobs and other controls on control panel.
- [Items in menu and buttons in dialog box]: The square bracket indicates items in menu or buttons in dialog box.
- Click [Items or Button]: Move the cursor to the item or button and press <Set>, or click it on the menu.
- [Items in Menu]→[Items in Submenu]: Selects a submenu item following the path.
- [Dyn Rng (Value)]: Indicates menu items with parameter, (value) shows the current value of the item.

# Product Differences

	B-Profile	B-Hist	Double Dist	Trace Length
DP-50 Vet	√	√	√	√
DP-70 Vet	×	√	√	√
DP-50 Exp Vet	√	×	√	√

NOTE: DP-70 Vet and DP-50 Exp Vet are not available in FDA region.



# 1 Safety Precautions

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## 1.1 Safety Classification





- According to the type of protection against electric shock:  
Externally Powered Class I Equipment + Internally powered equipment
- According to the degree of protection against electric shock:  
Type-BF applied part
- According to the degree of protection against harmful ingress of water:  
Main unit: IPX0  
Probes: IPX7  
Footswitch: IP68
- According to the degree of safety of application in the presence of a FLAMMABLE ANESTHETIC MIXTURE WITH AIR or WITH OXYGEN OR NITROUS OXIDE:  
EQUIPMENT not suitable for use at the presence of a FLAMMABLE ANESTHETIC MIXTURE WITH AIR or WITH OXYGEN OR NITROUS OXIDE
- According to the mode of operation:  
CONTINUOUS OPERATION
- According to the installation and use:  
PORTABLE EQUIPMENT  
MOBILE EQUIPMENT

## 1.2 Meaning of Signal Words

In this manual, the signal words "**⚠️ DANGER**", "**⚠️ WARNING**", "**⚠️ CAUTION**", "**NOTE**" and "Tips" are used regarding safety and other important instructions. The signal words and their meanings are defined as follows. Please understand their meanings clearly before reading this manual.

Signal word	Meaning
<b>⚠️ DANGER</b>	Indicates an imminently hazardous situation that, if not avoided, will result in death or serious injury.
<b>⚠️ WARNING</b>	Indicates a potentially hazardous situation that, if not avoided, could result in death or serious injury.
<b>⚠️ CAUTION</b>	Indicates a potentially hazardous situation that, if not avoided, may result in minor or moderate injury.
<b>NOTE</b>	Indicates a potentially hazardous situation that, if not avoided, may result in property damage.
Tips	Important information that helps you to operate the system more effectively.

## 1.3 Meaning of Safety Symbols

Symbol	Description
	Type-BF applied part. The ultrasound probes connected to this system are type-BF applied parts.
	General warning, caution, risk of danger.
	Animal/user infection due to contaminated equipment. Be careful when performing the cleaning, disinfection and sterilization.
	Animal injury or tissue damage from ultrasound radiation. It is required to practice ALARA when operating ultrasound system.

## 1.4 Safety Precautions

Please observe the following precautions to ensure animal and operator's safety when using this system.



### **DANGER:**

**DO NOT use flammable gasses, such as anesthetic gas or hydrogen, or flammable liquids such as ethanol, near this system, because there is danger of explosion.**



### **WARNING:**

- 1. Do not connect the power plug of this system and power plugs of the peripherals to wall receptacles that meet the ratings indicated on the rating nameplate. Using a multifunctional receptacle may affect the system protective grounding performance, and cause the leakage current to exceed safety requirements.**  
**Use the cable provided with this system to connect the printer. Other cables may result in electric shock.**  
**You must use the power adapter provided with the system; otherwise electric shock may result.**  
**You can only adopt the power supply method provided by Mindray, other power supply modes (e.g. using a UPS) may result in electric shock.**
- 2. Connect the protective grounding conductor before turning ON the system. Disconnect the grounding cable after turning OFF the system. Otherwise, electric shock may result.**
- 3. For the connection of power and grounding, follow the appropriate procedures described in this operator's manual. Otherwise, there is risk of electric shock. DO NOT connect the grounding cable to a gas pipe or water pipe; otherwise, improper grounding may result or a gas explosion may occur.**
- 4. Before cleaning the system, disconnect the power cord from the outlet. System failure and electric shock may result.**
- 5. This system is not water-proof designed. Do Not use this system in any place where water or any liquid leakage may occur. If any water is sprayed on or into the system, electric shock or device malfunction may result. If water is accidentally sprayed on or into the system, contact Mindray Customer Service Department or sales representative.**
- 6. Do not use a transducer that has a damaged, scratched surface, or exposed wiring of any kind. Immediately stop using the transducer and contact Mindray Customer Service Department or sales representative. There is risk of electric shock if using a damaged or scratched transducer.**

- 7. DO NOT allow the animal to contact the live parts of the ultrasound system or other devices, e.g. signal I / O ports. Electric shock may occur.**
- 8. DO NOT touch the Signal I/O ports if in contact with the animal; otherwise animal injury may result.**
- 9. Do not use an aftermarket probe other than those specified by Mindray. The probes may damage the system causing a profound failure, e.g. a fire in the worst case.**
- 10. Do not subject the transducers to knocks or drops. Use of a defective transducer may cause an electric shock.**
- 11. Do not open the covers and front panel of the system. Short circuit or electric shock may result when the system hardware is exposed and powered on.**
- 12. Do not use this system when any digital device such as a high-frequency electrotome, high-frequency therapeutic device or defibrillator is applied already. Otherwise, there is a risk of electric shock to the animal.**
- 13. When moving the system, you should first fold the keyboard, disconnect the system from other devices (including probes) and disconnect the system from the power supply.**
- 14. Accessory equipment connected to the analog and digital interfaces must comply with the relevant IEC standards (e.g., IEC 60950 information technology equipment safety standard and IEC 60601-1 medical equipment standard). Furthermore, all configurations must comply with the standard IEC 60601-1. It is the responsibility of the person, who connects additional equipment to the signal input or output ports and configures a medical system, to verify that the system complies with the requirements of IEC 60601-1. If you have any questions regarding these requirements, consult your sales representative.**
- 15. Prolonged and repeated use of keyboards may result in hand or arm nerve disorders for some individuals. Observe the local safety or health regulations concerning the use of keyboards.**
- 16. When using intra-cavity transducers, do not activate the transducer outside the animal's body.**
- 17. The operator SHOULD NOT touch SIP/SOP and the animal at the same time.**
- 18. If the battery cannot be automatically maintained in a fully usable condition, please conduct periodic checking of the battery.**

- 19 The ultrasound system use a mains plug as isolation means to the mains power supply. Please do not set the ultrasound system in a place difficult to operate the mains plug.**
- 20 Do not modify this equipment without authorization of the manufacture.**

**CAUTION:**

1. **Precautions concerning clinical examination techniques:**
  - This system must be used only by qualified medical professionals.
  - This operator's manual does not describe clinical examination techniques. The clinician should select the proper examination techniques based on specialized training and clinical experience.
2. **Malfunctions due to radio wave:**
  - If a radio wave emitting device is used in the proximity of this system, it may interfere with operations. Do not bring or use devices that generate radio waves, such as cellular telephones, transceivers, and radio controlled toys, in the room where the system is installed.
  - If a person brings a device that generates radio waves near the system, ask him / her to immediately turn OFF the device.
3. **Precautions concerning movement of the system:**
  - When you place the system on the mobile trolley and move them together, you must secure all objects on the mobile trolley to prevent them from falling. Otherwise you should separate the system from the mobile trolley and move them individually.  
When you have to move the system with the mobile trolley upward or downward the stairs, you must separate them first and then move them individually.
  - Object placed on the monitor may fall and injure an individual when moving.
  - Fasten and fully secure any peripheral device before moving the system. A loose peripheral device may fall and injure an individual.
4. **DO NOT expose the system to excessive vibration through transportation. Mechanical damage may result.**
5. **Do not connect this system to outlets with the same circuit breakers and fuses that control the current of devices such as life-support systems. If this system malfunctions and generates overcurrent, or when there is an instantaneous current at power ON, the circuit breakers and fuses of the building's supply circuit may be tripped.**
6. **Always keep the system dry. Avoid transporting this system quickly from a cold place to a warm place; otherwise condensation or water droplets may form allowing a short circuit and possible electric shock.**
7. **If the circuit protector is tripped, it indicates that the system or a peripheral device was improperly shut down and the system is unstable. You cannot repair the system under this circumstance and must call the Mindray Customer Service Department or sales representative.**

8. **There is no risk of high-temperature burns during normal ultrasound examinations. It is possible for the surface temperature of the transducer to exceed the body temperature of an animal due to environmental temperature and exam type combinations. Do not apply the transducer to the same region on the animal for a long time. Apply the transducer only for a period of time required for the purpose of diagnosis.**
9. **The system and its accessories are not disinfected or sterilized prior to delivery. The operator is responsible for the cleaning and disinfection of transducers and sterilization of biopsy brackets according to the manuals, prior to the use. All items must be thoroughly processed to completely remove harmful residual chemicals, which will not only be harmful to the human body, but also damage the accessory.**
10. **It is necessary to press [End Exam] to end the current scan that is in progress and clear the current Animal Information field. Otherwise, new animal data may be combined with the previous animal data.**
11. **DO NOT connect or disconnect the system's power cord or its accessories (e.g., a printer) without turning OFF the power first. This may damage the system and its accessories or cause electric shock.**
12. **If the system is powered off improperly during operation, it may result in data damage of the system's hard disk or system failure.**
13. **Do not use the system to examine a fetus for a long period of time.**
14. **Do not use a USB memory device (e.g., a USB flash drive, removable hard disk) which has unsafe data. Otherwise, system damage may result.**
15. **It is recommended to only use the video devices specified in this manual.**
16. **Do not use gel, disinfectant, probes, probe sheath or needle-guided brackets that are not compatible with the system.**
17. **Read the Acoustic Output Principle in the operation manual carefully before operate this system on clinical examination.**
18. **Please use the ultrasound gel compliant with the relevant local regulations.**
19. **The ultrasound system can be powered by connecting to mains power supply or powered by internal battery, if you have any doubt with stability of mains power protective grounding, please use internal battery.**

- NOTE:**
1. DO NOT use the system in the vicinity of strong electromagnetic field (such as a transformer), which may affect the performance of the system.
  2. DO NOT use the system in the vicinity of high-frequency radiation source, which may affect the performance of the system or even lead to failure.
  3. When using or placing the system, keep the system horizontal to avoid disbalance.
  4. To avoid damaging the system, DO NOT use it in following environment:
    - (1) Locations exposed to direct sunlight;
    - (2) Locations subject to sudden changes in environmental temperature;
    - (3) Dusty locations;
    - (4) Locations subject to vibration;
    - (5) Locations near heat generators;
    - (6) Locations with high humidity.
  5. Turn ON the system only after the power has been turned OFF for a while. If the system is turned ON immediately after being turned OFF, the system may not be rebooted properly and could malfunction.
  6. Remove ultrasound gel from the face of a probe when the examination is complete. Water in the gel may enter the acoustic lens and adversely affect the performance and safety of the transducer.
  7. You should properly back up the system to a secure external storage media, including system configuration, settings and animal data. Data stored to the system's hard drive may be lost due to system failure, improper operation or accident.
  8. Do not apply external force to the control panel, otherwise, the system may be damaged.
  9. If the system is used in a small room, the room temperature may rise. Please provide proper ventilation and free air exchange.
  10. To dispose of the system or any part, contact Mindray Customer Service Department or sales representative. Mindray is not responsible for any system content or accessories that have been discarded improperly. Mindray is not responsible for any system content or accessories that have been discarded improperly.
  11. Electrical and mechanical performance may be degraded due to long usage (such as current leakage or distortion and abrasion), the image sensitivity and precision may become worse too. To ensure optimal system operations, it is recommended that you maintain the system under a Mindray service agreement.
  12. Ensure that the current exam date and time are the same as the system date and time.
  13. DO NOT turn OFF the power supply of the system during printing, file storage or invoking other system operations. An interrupted process may not be completed, and can become lost or corrupted.
  14. The system should be powered by battery when the integrality and reliability of the protective grounding of external power supply is indeterminate.
  15. The replaceable fuse is inside the chassis. Refer replacing job to Mindray service engineers or engineers authorized by Mindray only.



Please read the following precautions carefully to ensure the safety of the animal and the operator when using the probes.

 **WARNING:**

1. The ultrasonic probe is only for use with the specified ultrasonic diagnostic system. Please refer to the “2.5.2 Probes Available” to select the proper probe.
2. The ultrasonic probe must be used only by qualified professionals.
3. Confirm that the probe and cable are normal before and after each examination. Electrical shock may result from a defective probe.
4. Do not subject the probe to shock. A defective probe may cause electric shock to the animal.
5. Do not disassemble the probe to avoid the possibility of electric shock.
6. Never immerse the probe connector into liquids such as water or disinfectant because the connector is not waterproof. Immersion may cause electric shock or malfunction.
7. A probe sheath must be installed over the probe before performing intra-cavity or biopsy examination.

 **CAUTION:**

1. When using the probe, wear sterile gloves to prevent infection.
2. Be sure to use ultrasound sterile gel. Please use the ultrasound gel compliant with the relevant local regulations. And manage the ultrasound gel properly to ensure that it does not become a source of infection.
3. In normal diagnostic ultrasound mode, there is no danger of a normal-temperature burn; however, keeping the probe on the same region of the animal for a long time may cause such a burn.
4. Do not use the carrying case for storing the transducer. If the carrying case is used for storage, it may become a source of infection.
5. It is required to practice ALARA when operating ultrasound system. Minimize the acoustic power without compromising the quality of images.
6. The probe and accessories supplied with it are not delivered disinfected or sterilized. Sterilization (or high-level disinfect) before use is required.
7. Disposable components are packaged sterile and are single-use only. Do not use if integrity of packaging violated or if expiration date has passed. Please use the disposable components compliant with the relevant local regulations.

8. **Please use the disinfection or sterilization solution that recommended in this operator's manual, otherwise Mindray will not be liable for damage caused by other solutions. If you have any questions, please contact Mindray Customer Service Department or sales representative.**
9. **The probe sheath contains natural rubber that can cause allergic reactions in some individuals.**
10. **Do not use pre-lubricated condoms as a sheath. Lubricant may not be compatible with the transducer material and damage may result.**
11. **Transducer damage may be caused by inappropriate gel, detergent or cleanser:**  
**Do not soak or saturate transducers with solutions containing alcohol, bleach, ammonium chloride compounds, acetone or formaldehyde.**  
**Avoid contact with solutions or coupling gels containing mineral oil or lanolin.**

**NOTE:** Read the following precautions to prevent the probe from malfunction:

- Clean and disinfect the transducer before and after each examination.
- After the examination, wipe off the ultrasound gel thoroughly. Otherwise, the ultrasound gel may solidify and the image quality would be degraded.
- After an examination, wipe the ultrasound gel off thoroughly. Failure to do so may result in the ultrasound gel solidifying and the image quality being degraded.

To prevent the probe from being damaged, do not use it where it will be exposed to:

- Direct sunlight or X-rays
- Sudden changes in temperature
- Dust
- Excessive vibration
- Heat generators

Repeated disinfection will eventually damage the probe. Check the probe's performance periodically.

**NOTE:** 1. The following definition of the WEEE label applies to EU member states only: The use of this symbol indicates that this system should not be treated as household waste. By ensuring that this system is disposed of correctly, you will help prevent bringing potential negative consequences to the environment and human health. For more detailed information with regard to returning and recycling this system, please consult the distributor from whom you purchased the system.



2. For system products, this label may be attached to the main unit only.


## 1.5 Latex Alert

When choosing a probe sheath, it is recommended that you directly contact CIVCO for obtaining probe sheath, pricing information, samples and local distribution information. For CIVCO information, please contact the following:

CIVCO Medical Instruments

Tel: 1-800-445-6741

WWW.civco.com



 <b>WARNING:</b> Allergic reactions in latex (natural rubber) sensitive animals may range from mild skin reactions (irritation) to fatal anaphylactic shock, and may include difficulty in breathing (wheezing), dizziness, shock, swelling of the face, hives, sneezing or itching of the eyes (FDA Medical Alert on latex products, "Allergic Reactions to Latex-containing Medical Devices", issued on March 29, 1991).
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# 1.6 Warning Labels

The warning labels are attached to this system in order to call your attention to potential hazards.

The warning labels use the same signal words as those used in the operator's manual. Read operator's manual carefully before using the system.

The name, pattern and meaning of each warning label are described as follows:

No.	Warning Labels	Meaning
1		Please carefully read this manual before use device.
2	<p>The following label is available when the system works with the mobile trolley.</p>  <p>a</p> <p>b</p> <p>c</p>	<p>a. Do not place the device on a sloped surface. Otherwise the device may slide, resulting in personal injury or the device malfunction. Two persons are required to move the device over a sloped surface.</p> <p>b. Do not sit on the device.</p> <p>c. DO NOT push the device when the casters are locked.</p>

# 2 System Overview

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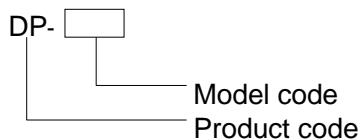
## 2.1 Intended Use

The Digital Ultrasonic Diagnostic Imaging System is intended for veterinary use in ultrasound examination and diagnosis.

## 2.2 Contraindication

None.

## 2.3 Product and Model Code



**NOTE:** The functions described in the operator's manual may vary depending upon the specific system you purchased.

## 2.4 Product Specifications

### 2.4.1 Imaging Mode

<b>B Mode</b>	B
<b>M Mode</b>	M Anatomical M
<b>C Mode</b>	Color Power
<b>D Mode</b>	PW Doppler iScape Smart 3D

## 2.4.2 Power supply

Voltage 100-240V~

Frequency 50/60Hz

Input Power 1.5-0.8A

## 2.4.3 Environmental Conditions

	Operational Conditions	Storage and Transportation Conditions
Ambient temperature	0°C-40°C	-20°C-55°C
Relative humidity	30%-85% (no condensation)	30%-95% (no condensation)
Atmospheric pressure	700hPa-1060hPa	700hPa-1060hPa

 **WARNING:** Do not use this system in the conditions other than those specified.

## 2.4.4 Size and weights

- Size:  
147±5mm×361±5mm×358±5mm (Depth×Width×Height)
- Net Weight: 8.1±0.5kg (without battery, two probe ports)

## 2.5 System Configuration

### 2.5.1 Standard Configuration

- Main unit
- System software
- Accessories
  - Operator's manual
  - Ultrasound gel (Standard configuration in the FDA region)
  - Cables
  - Multilingual controls overlay
  - Probe holder
  - Dust-proof cover

### 2.5.2 Probes Available

No.	Probe Model	Category	Region Applied
1.	35C50EA	Convex	Body surface

No.	Probe Model	Category	Region Applied
2.	65C15EA	Convex	Body surface
3.	65EB10EA	Convex	Transrectal
4.	75L38EA	Linear array	Body surface
5.	75L53EA	Linear array	Body surface
6.	10L24EA	Linear array	Body surface
7.	35C20EA	Convex	Body surface
8.	65EC10ED	Convex	Transrectal
9.	75LT38EA	Linear	Body surface
10.	65EL60EA	Linear	Transrectal
11.	50L60EAV	Linear array	Transrectal, body surface
12.	75L50EAV	Linear array	Transrectal, body surface

Some of the probes have matched needle-guided brackets for biopsy, the available probes and the corresponding needle-guided brackets are listed as follows:

Probe Model	Needle-guided Bracket Model	Biopsy Angle/ Depth ( $\pm 1^\circ$ )	Applicable Biopsy Needle
35C50EA	NGB-001 Metal/needle detachable; metal/needle un-detachable	25°, 35°, 45°	13G, 15G, 16G, 18G, 20G 14G, 16G, 18G, 20G, 22G
75L38EA	NGB-002 metal/needle un-detachable	40° , 50° , 60°	13G, 15G, 16G, 18G, 20G
35C20EA	NGB-003 Metal/needle un-detachable Metal/needle detachable	11°, 23°	20G, 18G, 16G, 15G, 13G 22G, 20G, 18G, 16G, 14G
65EB10EA	NGB-004 metal/needle un-detachable	/	16G, 17G, 18G
65EC10ED			
65C15EA	NGB-005 metal/needle un-detachable	12.7°, 24.2°	13G, 15G, 16G, 18G, 20G

Probe Model	Needle-guided Bracket Model	Biopsy Angle/ Depth ( $\pm 1^\circ$ )	Applicable Biopsy Needle
75L53EA	NGB-007 Plastic/needle detachable; Metal/needle detachable	40°, 50°, 60°	Metal: 14G, 16G, 18G, 20G, 22G Plastic: 13G, 15G, 16G, 18G, 20G
65EL60EA	NGB-009 Metal/needle detachable	0°	20G, 18G, 16G, 15G, 13G
75LT38EA	NGB-010 Metal/needle detachable	30°, 40°, 50°	13G, 15G, 16G, 18G, 20G
10L24EA	NGB-016 Metal/needle detachable	30°, 40°, 50°	14G, 16G, 18G, 20G, 22G

## 2.5.3 Options

No.	Item	
1	IMT	
2	DICOM Module	DICOM basic (including: Connection Verification, Task Management, DICOM storage, DICOM print, DICOM storage commitment, DICOM media storage (including DICOM DIR) and etc.)
3		DICOM worklist (the DICOM Basic function should be installed first)
4		DICOM MPPS (the DICOM Basic function should be installed first)
5		DICOM Query/Retrieve (the DICOM Basic function should be installed first)
6	Footswitch	
7	Battery	
8	Mobile Trolley (UMT-150, UMT-160 or UMT-170)	
9	DVD Drive (only for FDA region)	
10	Pack	
11	Network accessory package (only for CE region)	
12	PW	
13	Smart 3D	
14	iNeedle	
15	Free Xros M	
16	iScape View	



No.	Item
17	Color
18	Power
19	Ultrasound gel (optional configuration in the CE region)

## 2.5.4 Peripherals Supported

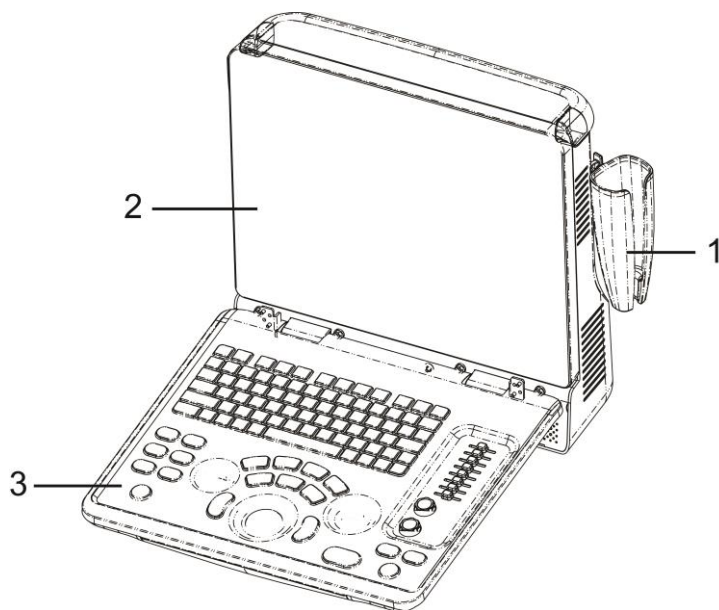
No.	Item	Model	
1.	Graph / text printer	HP OFFICEJET PRO 8100	
2.	Digital Color Video Printer	SONY UP-D25MD	
3.	Black and White Video Printer	Analog	MITSUBISHI P93W-Z SONY UP-X898MD
4.	Footswitch (1-pedal (not for CE region); 2-pedal; 3-pedal)		
5.	LAN Accessory	LPA11 (only for CE region)	

**⚠ WARNING:** This system complies with IEC60601-1-2: 2014, and its RF emission meets the requirements of CISPR11 Class B. In a domestic environment, the customer or the user should guarantee to connect the system with Class B peripheral devices; otherwise RF interference may result and the customer or the user must take adequate measures accordingly.

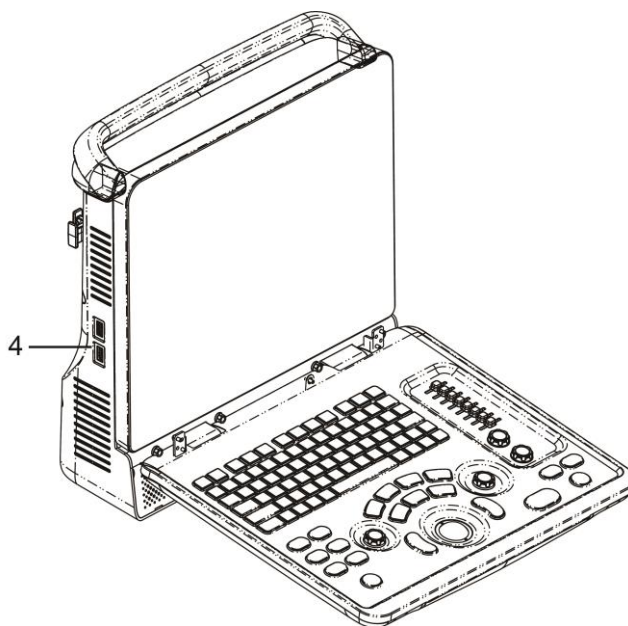
**NOTE:** If the ultrasound system cannot recognize the SONY UP-X898MD printer automatically, you may need to change the settings on the printer: push <PUSH ENTER> to enter the main menu and select [DIGITAL]->[DRIVER], and select [897].

## 2.6 Introduction of Each Unit

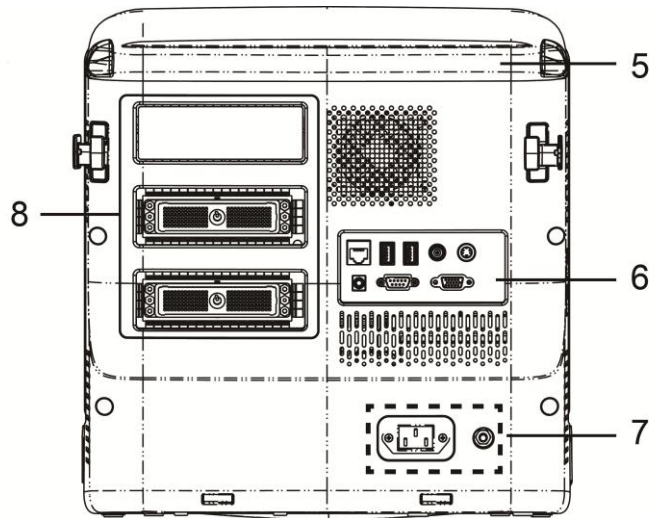
### ■ Right View



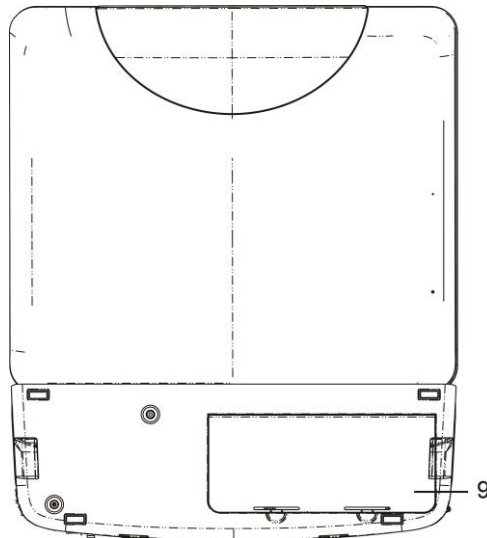
### ■ Left View



■ Rear View

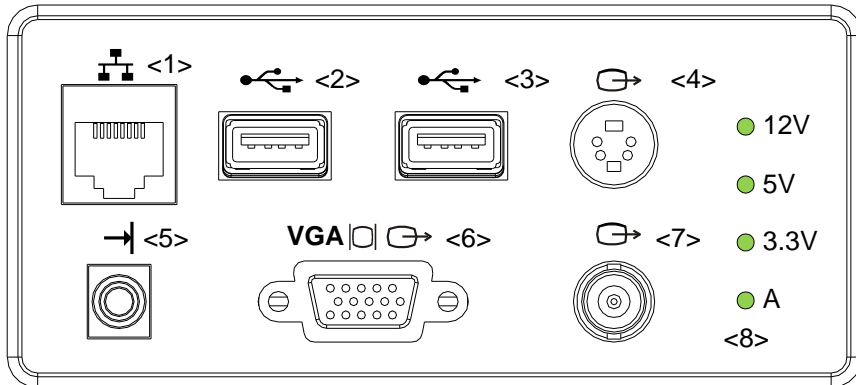








■ Bottom View



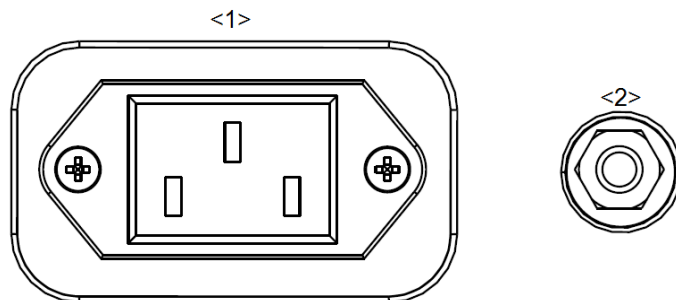
No.	Name	Function
1	Probe holder	Used to place the probe
2	Display	Displays the image and parameters during scanning
3	Control Panel	Refer to 2.6.3 Control Panel
4	USB ports	Used to connect USB devices
5	Handle	Used to carry the machine
6	I/O Panel	Interface panel used for inputting and outputting signals, refer to 2.6.1 I/O Panel.
7	Power supply panel	Electrical port panel, refer to 2.6.2 Power Supply Panel.
8	Probe ports	Used to connect the probe
9	Battery cover	Used to hold the battery

## 2.6.1 I/O Panel



No.	Symbol	Function
1		Network port
2		USB ports
3		
4		Separate video output, connecting video printer or LCD
5		Remote control port
6		VGA signal output
7		Composite video output
8	/	Power indicator

## 2.6.2 Power Supply Panel



No.	Name	Function
1	Power inlet	AC power inlet
2	Equipotential terminal	Used for equipotential connection, that balances the protective earth potentials between the system and other electrical equipment.






















No.	Name	Description	Function
9	iStation	/	Press to enter or exit the animal information management system.
10	F1	User-defined key	You can assign a function to the key.
11	Biopsy	/	Press to show or hide the biopsy guide line.
12	Setup	/	Press to open/close the setup menu.
13	Del	/	Press to delete the comment, etc.
14	/	Alphanumeric keys	Same as on PC
15	Dual	Dual-split screen	Press to enter Dual mode from non-Dual mode; Press to switch between windows in Dual mode.
16	Quad	Quad-split screen	Press to enter Quad mode from non-quad mode; Press to switch between windows in Quad mode.
17	Steer	/	Press to activate the steer function for linear probe.
18	/	Direction key	To adjust LCD brightness or contrast when pressing with <Fn> key.
19	Cine	/	Press to enter or exit the cine review status.
20	Body Mark	/	Press to enter or exit the Body Mark status.
21	Arrow	/	Press to enter or exit the arrow comment status.
22	Clear	/	Press to clear the comments or measurement calipers on the screen.
23	Scale	/	Press to adjust image parameter of Scale.
24	Baseline	/	Press to adjust image parameter of Baseline.
25	Menu Nav.	/	Multifunction button
26	/	/	To adjust the image parameter combed with the key of Scale/Baseline/Nav.Rot
27	3D/4D	/	Press to enter or exit the 3D status.
28	Cursor	/	Press to show the cursor.
29	/	Trackball	Roll the trackball to change the cursor position.
30	Set	/	Press to confirm an operation, same as the left-button of a mouse.
31	PW	/	Press to enter PW mode
32	Color	/	Press to enter Color mode
33	M	/	Press to enter M mode
34	B	/	Press to enter B mode
35	Measure	/	Press to enter/ exit Application Measurement


No.	Name	Description	Function
36	Update	/	Measurement status: press to switch between the fixed and active end of the caliper; Multi-imaging mode: press to change the currently active window. iScale: press to start/stop image acquisition.
37	Caliper	/	Press to enter/ exit General Measurement
38	Gain/ iTouch	/	Rotate: to adjust the gain Press: to enter/ exit iTouch
39	TGC	/	Move to adjust time gain compensation.
40	Focus Freq./THI	/	Press: to switch between Focus and Freq./THI; Rotate: to adjust corresponding parameter
41	Depth Zoom	/	Press: to switch between Depth and Zoom; Rotate: to adjust corresponding parameter
42	Save 1	/	Press to save, user-defined key
43	Save 2	/	Press to save, user-defined key
44	Freeze	/	Press to freeze or unfreeze the image.
45	Print	/	Press to print, user-defined key.
46	/	Indicator 1	AC indicator AC supply: light green; Battery supply: light off.
47	/	Indicator 2	Battery status indicator Charging: light in orange Full: light in green Discharge (electricity >20%): light in green Discharge (electricity <20%): blinking in orange Discharge (electricity <5%): blinking in orange rapidly Non-charge/ discharge: light off
48	/	Indicator 3	Standby indicator Standby: blinking in orange Other status: light off
49	/	Indicator 4	HDD status indicator Read/ write: blinking in green Other status: light off NOTE: DO NOT move the machine when the indicator blinking in green. Otherwise the HDD may be damaged by sudden shake.
50	comment	/	Press to enter or exit the comment status.

## 2.7 Symbols

This system uses the symbols listed in the following table, and their meanings are explained as well.

Symbol	Description
	Type-BF applied part
	Caution
	Dangerous voltage
	Equipotentiality
	Power button
	Network port
	USB ports
	Video output
	Remote control port
<b>VGA</b> 	VGA signal output
	AC (Alternating current)
	Battery Status Indicator
	Standby indicator
	Hard disk indicator
 A	Probe port A
 B	Probe port B
	Product serial number
	Manufacture date
	Authorized representative in the European Community.



Symbol	Description
	The device is fully in conformance with the low voltage directive 2014/35/EU and the EMC directive 2014/30/EU




# 3 System Preparation

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## 3.1 Moving / Positioning the System

Please read and understand the safety precautions before placing the system to ensure safety for both operator and devices.

1. Switch off the power, and pull out the plug.
2. Disconnect the system from all peripherals.
3. Place the system in a desired location by holding the handle.
4. Leave at least 20cm at the back and both sides of the system.

 **CAUTION:** Maintain enough space around the back and both sides of the system for plugging/ unplugging the power cord freely, as well as avoiding system failure resulted due to increased system operating temperature.

## 3.2 Power Supply

This system can work normally only when it is connected to the external power supply or the battery capacity is sufficient.

### 3.2.1 Connecting External Power Supply

A three-wire power cord is used to connect the system with the external power supply.

The external power supply system must meet the following requirements:

Voltage: 100-240V ~

Frequency: 50/60Hz

Input current: 1.5- 0.8 A

### 3.2.2 Powered by Battery

When connected to the external power supply, the system is powered by the external power. The lithium ion battery inside it is in charging status. When disconnected from the external power supply, the system is powered by the lithium ion batteries.

Refer to “13 Battery” for the detailed operations and precautions.

## 3.3 Powering ON/ OFF

### 3.3.1 Powering ON

**⚠ CAUTION:** To ensure safe and effective system operation, you must perform daily maintenance and checks. If the system begins to function improperly – immediately stop scanning. If the system continues to function improperly – fully shut down the system and contact Mindray Customer Service Department or sales representative. If you use the system in a persistently improper functioning state – you may harm the animal or damage the equipment.

■ Checking before Power-on

To check the system before turning on the system:

No.	Check Item
<1>	The temperature, relative humidity and atmospheric pressure shall meet the requirements of operating conditions. See "2.4.3 Environmental Conditions" for details.
<2>	There shall be no condensation.
<3>	There shall be no distortion, damage or dirt on the system and peripheral devices. If any dirt is found, cleaning shall be performed as defined in section "16.1.1 Cleaning the System".
<4>	There shall be no loose screws on the LCD or control panel.
<5>	There shall be no cable damage (e.g. power cord). Maintaining secure connections to the system at all times.
<6>	The probes and probe cables shall be free of damage or stains. See "12.1.5 Probes Cleaning and Disinfection" for details on probe cleaning and disinfection.
<7>	No miscellaneous odds and ends are allowed to be attached or affixed to the control panel.
<8>	Ensure that all connections are free from damage and remain clear of foreign object blockages. There shall be no obstacles around the system and its air vent.
<9>	Probe cleaning and disinfection.
<10>	The overall scanning environment and field must be clean.

■ Checking after it is turned on

Press the power button in the upper right corner on the control panel.

To check the system after the system is turned on:

No.	Check Item
<1>	There shall be no unusual sounds or smells indicating possible overheating.
<2>	There shall be no persistently displayed system error message.
<3>	There shall be no evident excessive noise, discontinuous, absent or black artifacts in the B Mode image.
<4>	Check if there is abnormal heat on the surface of the probe during an ultrasound procedure.
<5>	The control panel keys and knobs are fully functional.
<6>	The exam date and time are the same as the system date and time, and are displayed correctly.

<p><b>⚠ WARNING:</b></p>	<ol style="list-style-type: none"> <li>1. <b>If you use a probe giving off excessive heat, it may burn the animal.</b></li> <li>2. <b>If you find anything not functioning properly, this may indicate that the system is defective. In this case, shut down the system immediately and contact Mindray Customer Service Department or sales representative.</b></li> </ol>
--------------------------	---

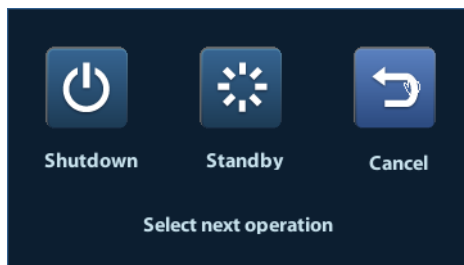
<p><b>NOTE:</b></p>	<p>When you start the system or switch between probes, you will hear clicking sounds – this is expected behavior.</p>
---------------------	---

### 3.3.2 Powering OFF

You need to follow the correct procedures to power off the system. In addition, after you upgrade the software or when the system is down, you need to power off and restart it. If you will not use the system for a long period of time, after powering off the system, you shall disconnect the external power supply; turn off powers of all peripherals connected to the system.

■ To power off your system normally:

Gently press the power button once on the upper right corner of the control panel. The [Shutdown Confirm] screen appears. See the figure below.



- Shut down: To power off the system normally.

- Standby: To enter the standby status.
- Cancel: To cancel the operation.
- To shut down the system in a direct way if you cannot do it normally:

Press and hold the power button for a long time and the system will power off without displaying the [Shutdown Confirm] screen. Shutting down the system this way may destroy the data.

- NOTE:**
1. DO NOT rush shutdown of the system in a direct way. It may destroy the data.
  2. After the software upgrade, please shut down the system in the normal way (using “Shut down” method) so as to guarantee a fully update.

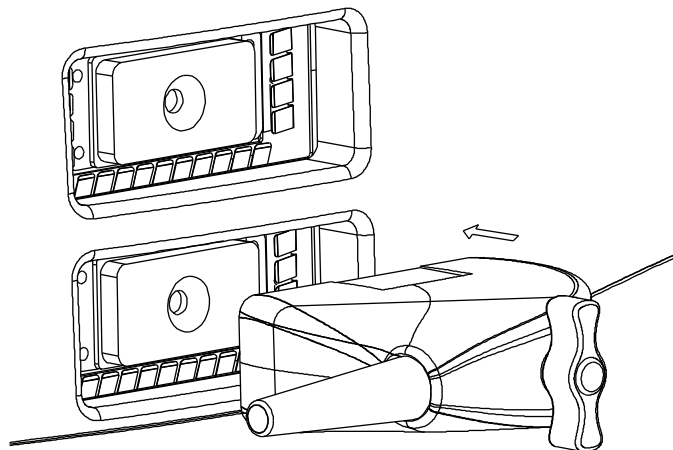
## 3.4 Connecting / Disconnecting a Probe

- ⚠ CAUTION:**
1. When connecting or disconnecting a probe, place it in a proper position, to prevent the probe from falling off or becoming damaged.
  2. Only use the probes provided by Mindray. Aftermarket probes may result in damage or cause a fire.

### 3.4.1 Connecting a Probe

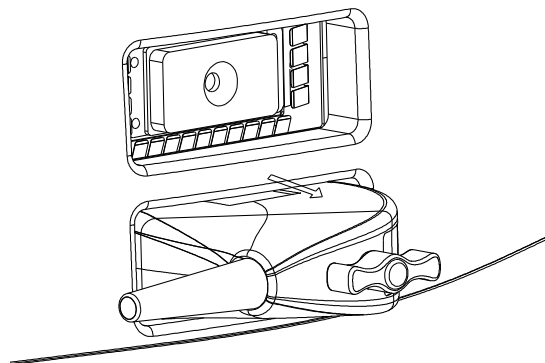
- ⚠ WARNING:** Before connecting to the system, check if the probes, cables and connectors are in proper operating order and free from surface defects, cracks and peeling. Using a defective probe may cause electric shock.

1. Check if the locking lever on the probe is locked, or unlock it by turning it counterclockwise to horizontal.
2. Insert the probe connector into the port with the probe cable pointing to the holder.
3. Lock the lever by turning it clockwise.
4. Place the cable properly to avoid being treaded or wrapping with other devices. DO NOT allow the probe head to hang free.



### 3.4.2 Disconnecting a Probe

1. Turn the probe lock lever counterclockwise to release the connector.
2. Pull the connector straight out.
3. Keep the probe in safety and care.





## 3.5 Connecting the Footswitch

Connect the footswitch to the main unit via a USB port.

Set the functions of the footswitch in the [Key Config] page. Refer to "11.1.5 Key Config" for details.

## 3.6 Connecting/ Removing a USB Storage Device

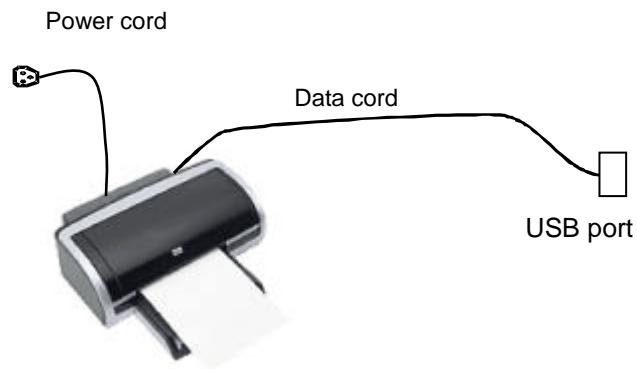
**⚠ WARNING:** DO NOT detach an USB storage device directly; otherwise, the ultrasound system or the USB device and/ or data stored in the device may be damaged.

- When connecting a USB storage device to the ultrasound system, you can see the symbol  in the lower right corner of the screen.
- To remove the USB storage device: Click  to open the [Remove USB Device] screen. Select the device to be removed. Click [OK].

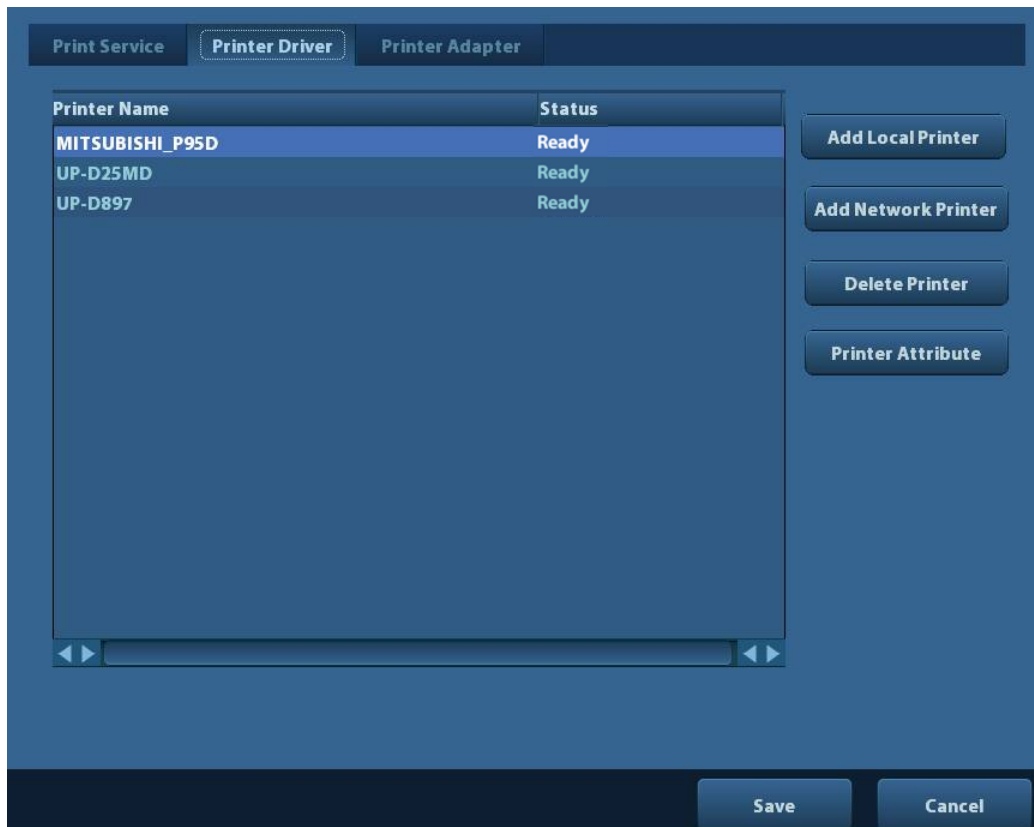
## 3.7 Graph/ Text Printer

- Connecting a local printer

As shown in the figure below, a graph / text printer has a power cord and data cable. The power cord shall be directly connected to a wall receptacle as required.

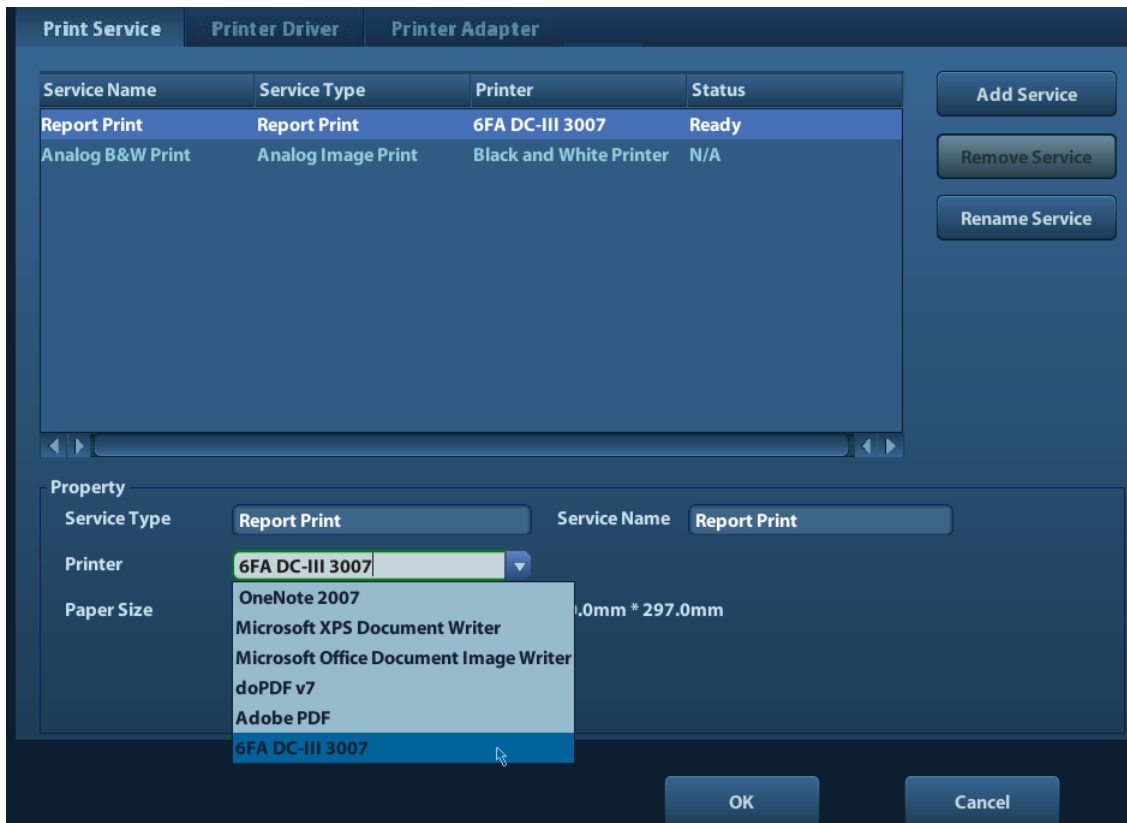


1. Connect the data cable with the USB port on the ultrasound system.
2. Plug the other end power plug into an appropriate outlet.
3. Power on the system and the printer.
4. Check the printer status:
  - Enter [Setup]-> [Print Preset]->“Printer Driver” page, printers that are installed automatically will be displayed in the list with the “Status” of “Ready”.



5. Return to “Print Service” page, and select “Report Print” in the list, and set attributes in the Property box under the screen:
  - Select the printer model from the drop-down list right to the “Printer”;
  - Set Paper Size.





6. Click [Save] to finish the installation.

Tips: Click [Printer Driver]->[Printer Supported] to view the drivers of some popular printers that have already been integrated in the system. These drivers will be installed automatically. You need to check the following information to check if the auto-installation fails:

- Model of the connected printer is not displayed in the “Printer Driver” list;
- Click “Printer Driver”->[Add Local Printer], the system will prompts you to update the ppd file.

At this time, you need to install the printer driver manually as described in the following:

- a) Download the ppd file from the printer manufacturer’s official website (contact service engineer if necessary), and copy the ppd file to the storage device (USB disk as an example).
- b) Connect the USB disk to the ultrasound system, click [Setup]->[Print Preset]->”Printer Driver”->[Add Local Printer] to run the ppd file and finish the installation.

**NOTE:** All printer drivers integrated in the ultrasound system come from official website of each printer manufacturer (you can check models in the [Setup]->[Print Preset]->”Printer Driver”->[Supported Printer List]).Printer drivers may not be updated in time due to software version and region limitation, consult printer manufacturer for details.

■ Add network printer

1. Make sure the target network printer and the ultrasound system are both connected into the same LAN.
2. Check the IP address of the network printer (for details, please refer to the accompanying documents of the printer).
3. Enter [Setup]->[Print Preset]->”Printer Driver” page, click [Add Network Printer] to enter the screen, type in the IP address of the network printer. (Port is 9100 in default).

4. Click [Verify Net Printer], the IP address, name and port information of the network printer will be displayed under the “Port” box. Change the port to match the verified printer information if necessary.
  5. Click [OK] to enter the ppd installing screen:
    - Select PPD file from media: select the path from the external media and install.
    - Select PPD file from database: select the ppd. file integrated in the ultrasound system.
  6. After the ppd. file is installed completely, enter the printer name to finish the installation.
- After installation succeeds, the system returns to the “Printer Driver” page and displays the added network printer. iStorage UltraAssist Print

The system supports printing by iStorage function. Before using this function, please make sure that the iStorage server has configured a defaulted printer, and the ultrasound system has configured an iStorage server. For details, please refer to “”.

1. Enter [Setup]->[Print Preset]->”Printer Driver” and check iStorage printer status, which should be AssistPrinter@IP address with “Ready” status.
2. Click “Print Service” to enter the screen, and select AssistPrinter@IP address to be the printer for the Report Print service.
3. Click [Save] .

■ Print Service

You can use a graph/ text printer to print report or images.

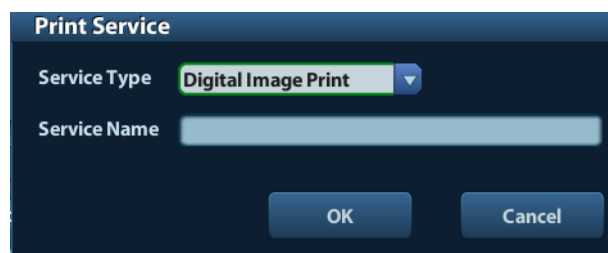
- To set the default report printer and its attribute:  
In "[Setup]-> [Print Preset]" screen, select the "Print Service", select “Report Print” column in the service list, set the items in the "Property" box.
- Report print:  
Click [Print] in the report dialog box to print a report; or, use the user-defined key to print, see "11.1.5 Key Config" for details. Please refer to the accompanying manuals

of the printers for more details.

## 3.8 Digital Video Printer

■ Install a local printer

1. Put the printer in a proper place.
2. Connect the printer (VIDEO IN port) and the ultrasound system (USB port) with the data cable.
3. Load a paper roll, and turn on the system and printer.
4. Install the printer driver (steps are the same as of graph/text printer, please refer to “3.7 Graph/ Text Printer” for details). And you need not install the driver of the printer listed in section “2.5.4 Peripherals Supported”.
5. Add a print service:
  - (1) Open [Setup]-> [Print Preset]->[Print Service].
  - (2) Click [Add Service] to enter the following page.



- (3) Select the service type as "Digital Image Print" and enter the service name manually.
- (4) Click OK to return to the Printer Service page.
- (5) Set the items in the Property box and click [Save] to save the settings.

■ Image print

For DICOM image printing, refer to "10 DICOM".

- Modify print service:
  - a) Select an existed printer service in the list.
  - b) Select the printer type in the Property box.
  - c) Set the attribute: paper size, orientation, etc.
  - d) Click [OK] to confirm.
- Image print
  - Select the image to be printed on the iStation or Review screen, and click [Send To] to select the printer to print.

Please refer to the accompanying manuals of the printers for more details.

## 3.9 Analog Video Printer

1. Connect the printer (VIDEO IN port) and the ultrasound system (S-Video on IO panel) with the signal cable;
2. Connect the Remote cable on printer to the Remote port on the ultrasound system.
3. Connect the power cord to a power supply receptacle that is well grounded.
4. Install the printer driver (steps are the same as of graph/text printer, please refer to "3.7 Graph/ Text Printer" for details). And you need not install the driver of the printer listed in section "2.5.4 Peripherals Supported".
5. Add a print service. Please refer to "3.8 Digital Video Printer".

## 3.10 External DVD

1. Connect the USB cable of the DVD recorder to the USB port on the ultrasound system (all USB ports available).
2. Connect the power adapter of the DVD on the power supply.

## 3.11 Basic Screen and Operation

### 3.11.1 Basic Screen

The following diagram maps out the different areas in the screen:

Logo	Hospital name		Animal Information	Accession#	Freeze icon
	Operator			Exam time	
	Probe	Acoustic power, MI/TI			
Menu area	Image area			Product Mode	
				Exam Mode	
				Image Parameters	
Thumbnail preview & zoom window	Cine Review Area				
	Bodymark & Comment				
Thumbnail Area of Images Saved					
Help information area			System status icon		

#### ■ Information Area

The information area displays manufacturer logo, hospital name, exam date & time, acoustic power & MI/TI, freeze icon, animal information, probe model, current exam mode, and accession #, etc. It can be preset whether to display the operator, animal gender, age, ID, name etc. via [Setup]-> [System Preset]-> [General]. See “11.1.2 General” for detailed preset procedures.

- Manufacturer logo  
Manufacturer logo, displayed in the upper left corner of the screen.
- Hospital name  
Displays the hospital name. Hospital name can be set via [Setup]-> [System Preset]-> [Region].
- Exam time  
Displays the exam time, including date and time. Exam time can be set via [Setup]-> [System Preset]-> [Region]. Exam time will be frozen with the frozen image.
- Acoustic power & MI/TI  
Displays the acoustic power. Including the acoustic power, MI (Mechanical Index) and TI (Thermal Index).
- Freeze icon

The freeze icon  means the image is frozen.

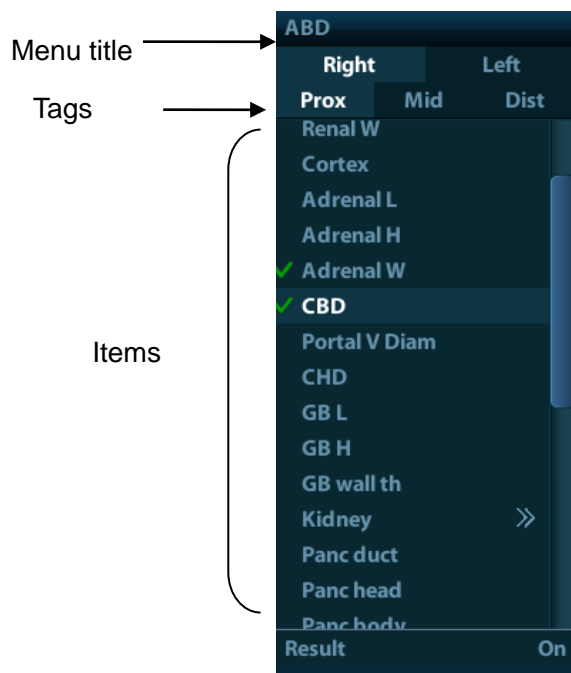
- Animal Information  
Displays animal name, ID, gender and age etc. Enter the animal information through the "Animal Info" screen. Or, import the saved animal data from iStation or the DICOM Worklist server.
- Probe model  
Display the currently-used probe model, or the default model.
- Exam Mode  
Displays the currently used exam type, e.g. Abdomen, is displayed.
- Operator  
Displays the operator's name on the screen. This information is entered through the [Animal Info] screen.
- Accession#  
The accession # indicates exam number used in hospital information system. It can be imported via DICOM or input manually.

■ Menu area

Include image menu, measurement menu, comment menu, bodymark menu and so on. Use the trackball or the multifunctional knob to operate on the menu.

To show or hide the image menu, press <Menu> key on the control panel.

The menu area consists of menu title, menu items. As shown in figure below.



- Menu title  
Displays the menu name.
- Tags  
Attribute tags of the item.
- Items  
Refers to the items on a menu. For item that is applicable for more than one mode, the item appears as universal item in the certain mode. Items of image modes and measurement can be preset (refer to "11 Setup" for details).
- Return to previous menu  
Click [Return] to return to the previous menu from the sub menu.

The multifunction knob can be used to operate the menu. Press the knob to open the menu; rotate the knob to navigate through the items one by one.


Depending on the item types, the multifunction knob can:

- For a commanding item or command optional item: press the knob to directly activate the item.
- For a parameter item or ON/OFF item: press the knob to lock and select the item, then rotate the knob to switch among the available values; press the knob again to release and deselect the item.
- For an item with sub-menu: press the knob to extend the sub-menu, and the cursor navigates to the first sub-item. At the same time, you can exit from the sub-menu to the previous item by clicking [Return] in the sub-menu.
- For tag items in the menu: e.g. the “Right” and “Left” tag in the measurement menu. Rotate the multifunctional knob to navigate the tag, and press the knob to select the tag.

#### ■ Parameter area

Displays the image parameters for the activating window. If there are more than one imaging modes, the parameters are displayed by each mode. For detailed parameters displayed in this area, please refer to the corresponding imaging mode (s).

#### ■ Image area

The image area displays the ultrasound images, probe mark (or activating window mark), time line (in M mode), coordinate axis (including depth, time, velocity/frequency), focus position (located at depth axis in the form of ) , besides, the annotation, bodymark, measurement calipers, grayscale bar are also displayed here.

#### ■ Thumbnail preview & Zoom Window (image-in-image)

In the zoom status, this area displays the thumbnail of a complete image, and a rectangular frame is used to highlight the currently magnified area. This feature is called image-in-image.

#### ■ Help information area

The help information area displays various help information or progress bar in the current status.





Besides, the system can provide help for each key. Press [Help] to enter key-help status, you can see the cursor changes into an arrow with a question mark on it. Press any key on the control panel, the screen displays the key-relevant information, meanwhile, the system exits the key-help status.

Tips: in terms of help information, “TB” refers to “Trackball”, “Knob refers to Multifunction knob.

#### ■ Thumbnail area of images stored

Displays the thumbnail images stored under the current animal.

#### ■ Image manage area

- Page-turning: when there are more than one page images have been stored, you can turn to the next or preview page by  or  respectively.
- Delete: select a thumbnail image, and click  to delete it.
- Send to: select a thumbnail image, and click  to send it to other devices.

#### ■ System status icon

This area displays the relevant system icons, such as USB memory device, printer, network, Chinese / English entry, and current system time, etc.

■ None-fixing Area

Position of areas illustrated here are not fixed, you can move them by the trackball within a certain area on the display.

- Result window

The measurement result window displays the results of recently performed measurements.

To move the result window:

- Place the cursor on the title of result window (you can see the cursor changes into  $\leftrightarrow$ ).
- Press <Set> and move the trackball, the window moves together with the cursor.
- Move the cursor to the target position, press [Set] again to anchor the result window in the target position.

- Comment area

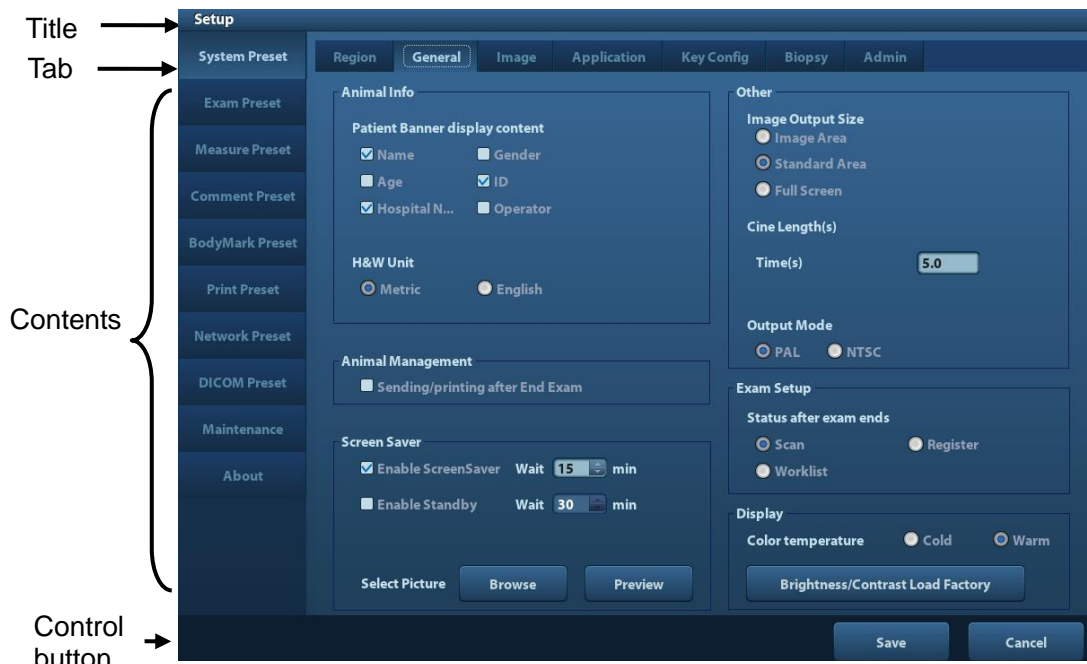
For details, please refer to “8 Comments and Body Marks”.

- Body mark area

For details, please refer to “8 Comments and Body Marks”.

### 3.11.2 Basic Operations of Screens


A screen consists of title, page tabs, contents and buttons, as shown in the following figure:



Composition	Description
Title Bar	The title bar is used to give a description for the content and function of the screen.
Page Tab	For some screens, contents are distributed across several pages. Use the selection pointer and <Set> key to open/close the available pages. Use the selection pointer and [Set] key to open / close the available pages.

Composition	Description
Content	<ul style="list-style-type: none"> <li>■ Radio button: click to select the item.</li> <li>■ Check box: click to check or uncheck the item.</li> <li>■ Entry box: enter characters manually via the keyboard. Position the cursor into the box, and then enter the letters or characters.</li> <li>■ Drop-down list box: click [▼] to show the list and select an item.</li> </ul>
[Save] and [Cancel]	When the operation of a screen is complete, press the [Save] or [Cancel] button to save or cancel the operation, and close the screen.

To reposition a dialogue box:

1. Roll the trackball to move the cursor onto the title bar of the dialogue box. At this time the cursor becomes a ; press the [Set] key.
2. Roll the trackball and reposition the rectangular graphic to the new desired location.
3. Press the <Set> key, and the dialogue box is moved to the desired position.



# 4 Exam Preparation

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 **CAUTION:** Before examining a new animal, press <End Exam> to end the exam of the previous animal, update the animal ID and information, to avoid mixing data of the next new animal.

## 4.1 Start an Exam

You can start an animal exam in the following situations:

- New animal information: to start a new animal exam, enter the animal information first, for details, please refer to "4.2.1 New Animal Information".
- New exam: to start a new exam for an already recorded animal, the recorded information can be obtained either through iStation or Worklist, refer to "4.2.2.1 iStation" and "4.2.2.2 DICOM Worklist" for details.
- Activate an exam: select an exam that is ended within 24 hours, and continue the exam with the imported animal information and exam data. For details, please refer to "4.5 Activate& Continue an Exam".
- Continue an exam: select an exam that is paused within 24 hours, and continue the exam with the imported animal information and exam data. For details, please refer to "4.5 Activate& Continue an Exam".

General procedure for an exam: enter the animal information-> select an exam mode and probe -> choose an imaging mode -> start the exam.

To start a new animal exam, it is better to enter the detailed animal information. The system will set up a unique information database for each animal based on the animal information entered, so that the information of one animal will not be confused with that of another animal.

## 4.2 Animal Information

- To enter the "Animal Info" screen
  - Press <Patient>, or,
  - Move the cursor onto the animal information area on the display and press <Set> to open the screen.
- To exit the "Animal Info" screen
  - Click OK on the "Animal Info" screen; or, press <Patient> on the control panel again, to save the settings and exit the screen.
  - Click [Cancel] or press <Esc> to exit the screen without saving any of the entered animal data.
  - Press <B> or <Freeze> to return to the current exam mode with the entered information being saved.

- Click [Quick Register] on the screen to save the animal information quickly and return to the main screen.

## 4.2.1 New Animal Information

The Animal Info page is shown as below:

Place the cursor onto the targeted box. The field box is highlighted and a flashing cursor appears. Information can be entered or selected from the options.

You can also change the cursor position by <Tab>, <Enter> or up/down controls.

The screenshot shows the 'Animal Info' form with the following sections and fields:

- 1 (General Information):** Animal ID (20180708-230055-056D), Gender (Unknown), Animal (Canine), Last Name, First Name, M.I., DOB (DD/MM/YYYY), Age (Years), No., Host.
- 2 (Exam Information):** ABD, REP, CARD, VAS, SMP tabs; Study Description, CPT4 Code, CPT4 Description, Height (cm), Weight (kg), BSA (m<sup>2</sup>), Ref.Physician, Diagnostician, Operator, Accession #, Comment.
- 3 (Animal data in):** iStation, Quick Register buttons.
- 4 (Action Buttons):** New Animal, New Exam, Pause Exam, OK, Cancel.

Information includes:

### 1. General information

- Name

Enter animal name through the keyboard. Characters of A through Z and 0 through 9 and "." are allowed. "\", " ", "=", and "," are not permitted.

- Animal ID

Animal ID is generated automatically by the system after starting a new animal, and can be modified manually. Once you enter the ID and confirm it, you are not allowed to change it.

**NOTE:**

1. "\" is not permitted.
2. If enter an ID that is already existed in the system, a warning "The ID existed, load data" prompts, and you can import the animal data. The animal data can be edited after importing.

- Animal


Select animal type.

- No.

Input the animal serial number.

- Host

Information of the animal used for other information like insurance ID.owner.

- Gender  
Select Male, Female or Unknown for animal gender in the drop down list.
- DOB (Date of birth):
  - You can either enter the birth date of an animal manually;
  - Or, click  to select the date, and click [Save] to confirm.
- Age
  - Auto generated age: once the DOB is gotten, the system can display an auto-generated age in the field box, the unit can be “Years”, “Months” or “Days”. If the age is less than one year, the system will automatically calculate the age in months or days.
  - Also, you can manually enter the age.

**NOTE:** When you enter the date manually, please enter it in the format as that of the system.

2. Exam Type

- Exam application type  
You can select among: ABD (Abdomen), REP (reproduction), CARD (Cardiac), VAS (Vascular), and SMP (Small Part).

Select the exam type tab to enter the exam-specific information.

- General information:
  - Study description:** to enter description for each exam.
  - Primary indications:** to enter the primary indications (reason to perform the exam.)
  - Secondary indications:** to enter the secondary indications.
  - CPT4 code:** to enter the CPT4 code.
  - CPT4 description:** to enter the CPT4 description.
- Exam specified information:

Exam Type	Information	Description
ABD (Abdomen)	Height	/
	Weight	/
	BSA (body surface area)	After the height and weight are inputted, the system will automatically calculate the BSA based on the formula which is set via [Setup]-> [System Preset]-> [General].

Exam Type	Information	Description
REP (reproduction)	Calculation index	<p>Calculate gestation age (GA) and estimated delivery date (EDD) based on last menstrual period (LMP), in vitro fertilization (IVF), basic body temperature (BBT), previous exam date (PRV). Select LMP, IVF, PRV, BBT, or EDD from the drop-down list; or, calculates GA and LMP according to the EDD and entered date.</p> <ul style="list-style-type: none"> <li>● LMP: After you enter LMP, the system will calculate and display GA and EDD.</li> <li>● IVF: After you enter IVF, the system will calculate GA and EDD.</li> <li>● PRV: input the date and GA of the last exam, the system will calculate a new GA and EDD.</li> <li>● BBT: input BBT, the system will calculate the GA and EDD.</li> <li>● EDD: after you enter EDD, the system will calculate and display GA and LMP.</li> </ul>
	Gravida	Times of pregnancy.
	Ectopic	Times of abnormal pregnancy. e.g. extrauterine pregnancy
	Gestations	Number of embryos (1, 2, 3; 1 is default)
	Para	Times of delivery
	Aborta	Times of abortion
CARD (Cardiac)	Height	/
	Weight	/
	BSA (body surface area)	After the height and weight are inputted, the system will automatically calculate the BSA based on the formula which is set via [Setup] -> [System Preset] ->[General].
	BP	Blood pressure.
	HR	/
	RA Press	Right Atrium Pressure
VAS (Vascular)	BP(L)	Input left blood pressure.
	BP(R)	Input right blood pressure.
SMP (Small Parts)	None	/

### 3. Operating Information

- Ref. Physician: the people who requires the operator to do the ultrasound operation. “\”, “^”, “=” and “,” are not permitted.
- Diagnostician: people who is responsible for exam. “\”, “^”, “=” and “,” are not permitted.
- Operator: people who is responsible for images collection and scanning. “\”, “^”, “=” and “,” are not permitted.
- Accession #: exam number used in DICOM, “\” is not permitted.
- Comment: exam-specific explanation or remarks.

### 4. Functional key

- [New Animal]: click to clear the current animal information in the animal information screen in order to input new animal information.

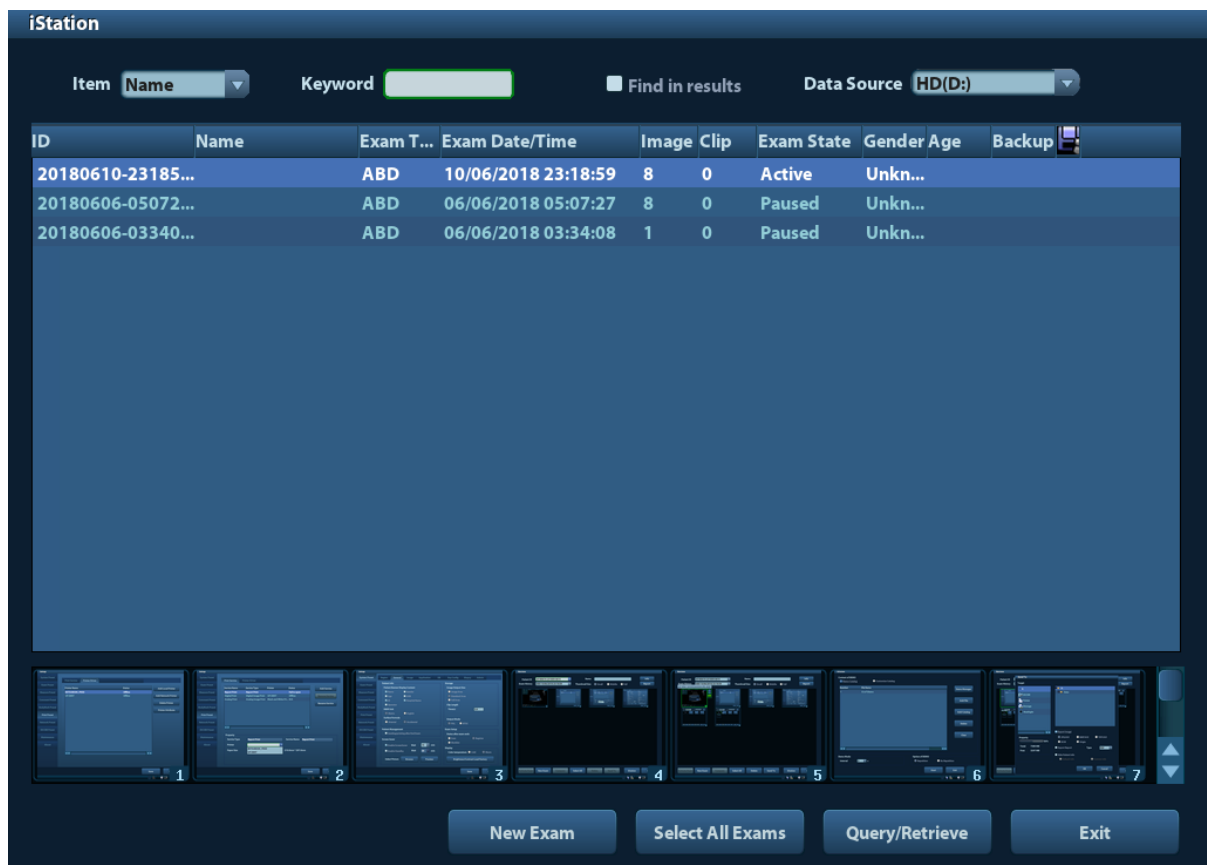
- [New Exam]: click to clear the current exam information in order to create a new exam for the current animal.
- [Pause Exam]: to pause the current exam.
- [Cancel Exam]: to cancel the current exam.
- [OK]: click to save the animal data entered and exit the screen.
- [Cancel]: click to cancel the animal data entered and exit the screen.

## 4.2.2 Retrieve Animal Information

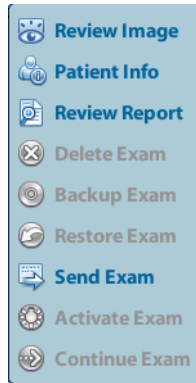
### 4.2.2.1 iStation










The animal data can be obtained in iStation from the system hardware or USB memory device. You can enter the searching conditions for the animal.

1. To enter iStation screen (the screen is shown as follows):
  - Press <iStation> on the control panel; or,
  - Click [iStation] in the "Animal Info" screen; or
  - Press the <Review> key on the control panel and click [iStation] in the screen.



2. Select the data source:  
Select the data source in the drop-down list of "Data Source".
3. Input the searching condition:  
Item: including Name, ID, DOB and Exam Date, the default one is name; then enter a keyword in accordance with the Item selected.
  - Select "Find in results", the system will search the keyword based on the existed searched results.
4. Select the desired animal information in the list. The following menu pops up:



Button	Function	Description
	Review Image	Click to enter the Review screen.
	Animal Info	Click to enter the Animal Info screen.
	Review Report	Click to enter the Diagnostic Report screen.
	Delete Exam	Click to delete the selected record.
	Backup Exam	Click to export the selected animal data to media supported.
	Restore Exam	Click to import the animal data from an external media.
	Send Exam	Click to send the selected animal data to external device, DICOM storage server or DICOM printer.
	Active Exam	Click to continue an exam finished within 24 hours.
	Continue Exam	Click to continue an unfinished exam carried out within 24 hours.

Other buttons:

- [New Exam]: Click to enter Animal Info screen, meanwhile, the corresponding animal information is also imported to the new exam. After you edit the animal information in the Animal Info screen, select [OK] to start a new exam.
- [Select All Exams]: Click to select all records.
- Query/Retrieve: click to enter DICOM Query/Retrieve.
- [Exit]: click to exit iStation.

#### 4.2.2.2 DICOM Worklist


When the DICOM basic package is configured and the Worklist server has been set, click [Worklist] in the "Animal Info" screen to query or import the animal data. (For the setting of Worklist server, please refer to "10 DICOM".)

Procedure:

1. Select data source: choose a worklist server in the drop-down list of "Worklist Server", and then all the animal exam records in the server are listed out.
2. Input the searching condition:

- Select exam date period, click [Query] to search the animal data in the period.
  - Enter animal ID, animal name, accession #, the system affords the result in real-time.
  - Or select the keyword type, enter the keywords and then click [Query] to search.
  - To reset the criteria, click [Clear] button.
3. Select the desired animal from the list.
    - Click [Start Exam], the animal information is imported into the system and then an exam is started.
    - Click [Transfer], the animal information is imported into the Animal Info screen. Edit the animal information in the Animal Info screen, and select [OK] to start a new exam.
    - Click [Show Detail] to see details of animal data.
  4. Click [Exit] to exit the Worklist.

## 4.3 Select Exam Mode and Probe

 <b>CAUTION:</b> If the exam mode is changed during a measurement, all measurement calipers on the image will be cleared. The data of general measurements will be lost, but the data of application measurements will be stored in the reports.
---

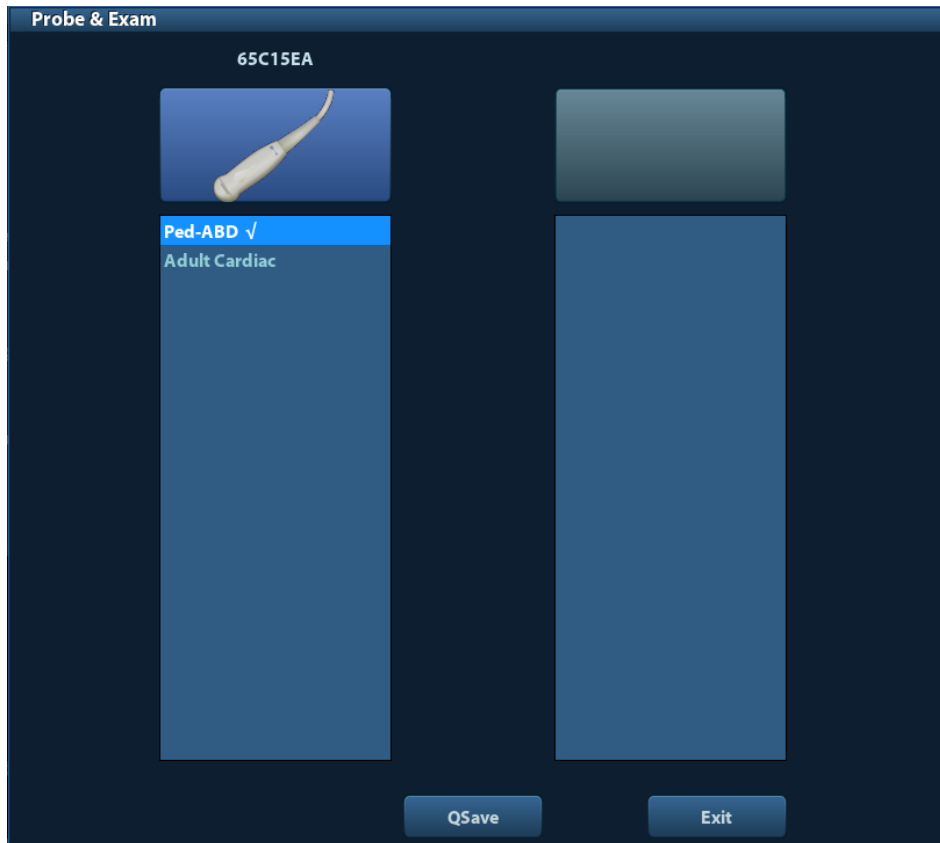
### 4.3.1 Supported Exam Modes

The system supports to preset application type, measurements, comments, body marks, image parameters for each exam mode (including user-defined exam modes). For details, please refer to “11.2 Exam Preset”.

You can select exam modes for the probes. For details, please refer to “11.2 Exam Preset”.

### 4.3.2 Selecting Exam Mode and Probe

- Select Probe and Exam Mode
  - (1) Press <Probe> to open the following dialog box.



(2) Roll the trackball and press <Set> to select the exam mode, and use the direction keys to turn pages of the exam modes.

- To save the image parameters for the current exam mode quickly:

Click [QSave] in the Probe & Exam page or click the user-defined key for QSave to save the image parameters in the current image mode as presets. A dialogue box pops up to prompt you the operation will cover the current image preset data.

- Exit:

Click [Exit] or press <Probe> to exit, press <B>, <Freeze> or <ESC> can also exit the screen.

### 4.3.3 Dual Probe Switching

You can preset user-defined key to implement switching probes between single B and 2B mode. The function is only available to the probes of the same exam mode.

- In single B mode: press the user-defined key to switch the current window between two probes (with Cine Memory in [Image Preset] is set to "Split")
- In Dual B mode: press the user-defined key to switch two windows between two probes.

Preset the user-defined key via [Setup] (by pressing <Setup>)-> [System Preset]-> [Key Config].

1. Select the user-defined key in the Key Function page on the left (Print, Save1, Save2, F1); or, select the key of footswitch.
2. Select "Dual Probe" in the page of Advanced Features on the right.
3. Click [Save] to confirm the setting and exit the dialog box.
4. After returning the preset, the setting will take effect.



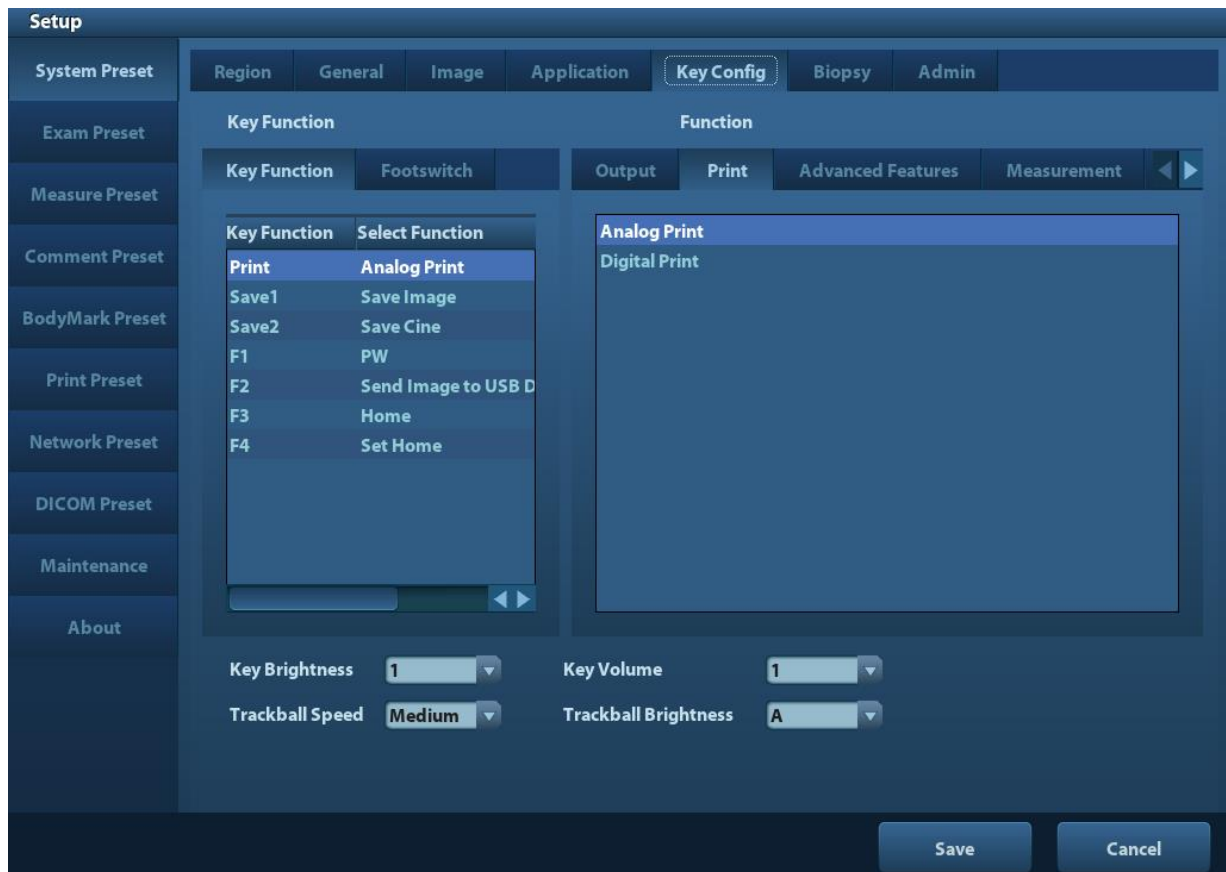
### 4.3.4 Bi-plane Endocavity Probe (65EB10EA)

■ Selecting Exam Mode

1. Connect 65EB10EA to the ultrasound system.
2. Press <Probe> on the control panel to enter the exam mode selecting screen. Roll the trackball and press <Set> to switch the S or T plane of the probe, or select the exam mode of the S/T plane of 65EB10EA probe.

■ Dual Probe Function (user-defined key)

1. Connect 65EB10EA to the ultrasound system.
2. Press <Setup> to enter the setup screen, select [System Preset] -> [Key Config] to enter the page.
3. Select the user-defined key in the Key Function page on the left; or, select the key of footswitch.
4. Select [Dual Probe] in the page of Advanced Features on the right.



5. Click [Save] to confirm the setting and exit the dialog box.
6. Press the defined key on the control panel for [Dual Probe] function, both the S plane and T plane image of the probe will be displayed on the screen. Press the user-defined key to switch between the two windows to activate the current window.


## 4.4 Selecting Imaging Mode

Use the corresponding key in the control panel to enter the imaging modes.

For the detailed operations in each imaging mode, please refer to “5 Image Optimization”.

## 4.5 Activate & Continue an Exam


### 4.5.1 Activate an Exam

Select an exam finished within 24 hours, select the exam record, click  from the menu popped up; or, click [Active Exam] in “iStation” or “Review” screen to activate the exam.

Note:

- The system can automatically load the animal information and exam data to continue the exam.
- If you want to continue an exam which data lies in an external memory database, you have to first allow the system to load the animal data to the system’s animal database.

### 4.5.2 Continue an Exam

Select an exam paused within 24 hours, select the exam record in iStation screen, click  from the menu popped up to continue the exam.

If you want to continue an exam which data lies in an external memory database, you have to first allow the system to load the animal data to the system’s animal database.

## 4.6 Pause & End an Exam

### 4.6.1 Pause and Exam

■ Sometimes, you have to stop an uncompleted exam due to some special causes. When the exam is paused, the system can begin other exams.

1. Press <Patient> to enter "Animal Info" screen.
2. Click [Pause Exam].

■ If the system is powered off during scanning, the exam status turns "paused" after the system restart.

Only one exam can be paused every time.

When an exam is paused, the system will:

1. Saves the exam-related images, reports and measurement data, modifies the status as “Paused”.
2. Save the exam information, including report, imaging mode, exam mode, image parameters, operation mode, imaging / measurement data and so on.

## 4.6.2 End an Exam

Before examining a new animal, press <End Exam> to end the exam of the previous animal, update the animal ID and information, to avoid mixing data of the next new animal.

To end an exam, you can do one of the following:

- Press <End Exam> on the control panel.
- Click [New Animal] on the Animal Info screen to end the last animal exam and clear the animal information.
- Click [New Exam] on the Animal Info screen (or iStation screen, or Review screen) to end the last exam and clear the exam data.



# 5 Image Optimization



## **WARNING:**

1. The images displayed in this system are only reference for diagnosis. Mindray is not responsible for the correctness of diagnostic results. It is the responsibility of the clinician, who performs the exam, to capture the correct diagnostic results.
2. In Dual-B imaging mode, the measurement results of the merged image may be inaccurate. Therefore, the results are provided for reference only, not for confirming a diagnosis.

## 5.1 Switching Between Image Modes

Switch the image modes. For details, refer to 2.6.3 Control Panel.

## 5.2 Basic Operations

Before optimizing the image by adjusting image parameters, adjust the brightness and contrast of the display to the best.

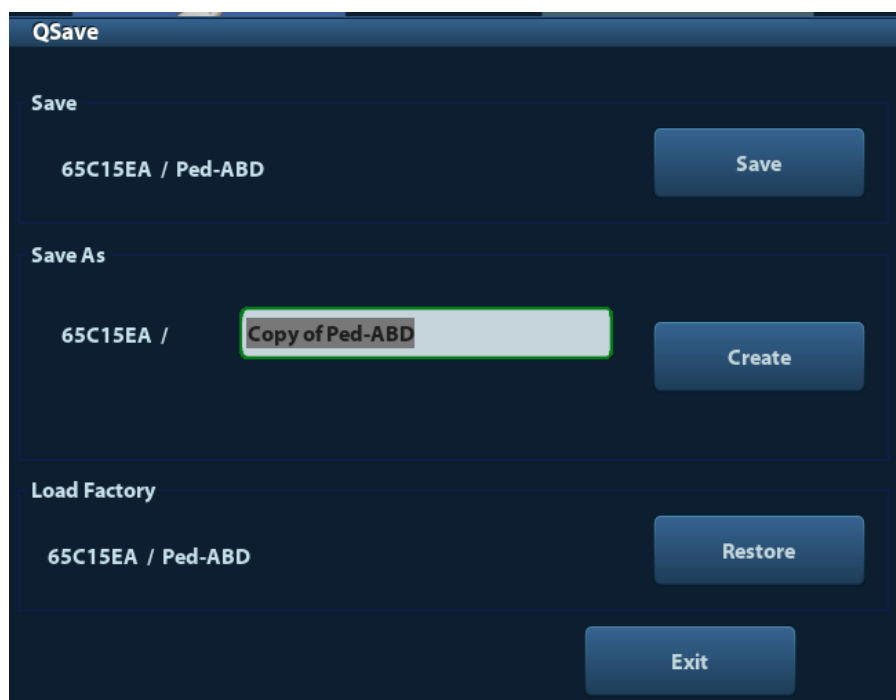
Requirement	Available Operations
To modify the brightness	Adjust [Gain]. Adjust TGC Adjust [Acoustic Power] (try adjusting gain before increasing the acoustic power)
To modify gray scale image effect	Adjust [Dynamic Range] Adjust [Map] Adjust [Persistence] Adjust [iClear]
To increase frame rate	Decrease [Depth] Decrease the [Focus Number] Decrease the [FOV] Decrease [Line Density] Turn on [High FR] in harmonic mode

- Adjusting through Image Menu:  
Press <Menu> or multifunctional knob to open the menu; use the trackball and <Set> or the multifunctional knob to adjust.
- Adjusting through control panel:  
Trackball, control panel key, knob or sliders.

## 5.3 Quickly Saving Image Setting (QSave)

To enter image parameter saving screen:

- Press <Probe> and click [QSave], or;
- Press the user-defined key for QSave function (for details about user-defined key setting, please refer to “11.1.5 Key Config” chapter).



- Save image parameter adjustment:  
Click [Save] to save the current image values for the current exam mode of the certain probe.
- Create a new exam data (using current image parameter setting):  
Enter the name in the box after the “Save As” to assign a name for a user-defined exam mode, and click [Create] to save the current image parameters, measurements, comments, body mark settings to the exam mode.
- Restore factory setting:  
Settings of the current exam mode and the probe can be restored to factory data by clicking [Restore].

## 5.4 B Mode

B mode is the basic imaging mode that displays real-time images of anatomical tissues and organs.

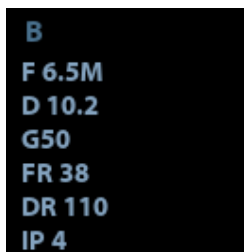
### 5.4.1 B Mode Exam Protocol

1. Enter the animal information, and select the appropriate probe and exam mode.
2. Press <B> on the control panel to enter B mode.
3. Adjust parameters to optimize the image.
4. Perform other operations (e.g. measurement and calculation) if necessary.

In real-time scanning of all image modes, press <B> on the control panel to return to B mode.

## 5.4.2 B Mode Parameters

In B mode scanning, the image parameter area in the upper left corner of the screen displays the real-time parameter values as follows:



Display	F	D	G	FR	IP	DR
Parameter	Frequency	Depth	Gain	Frame Rate	B IP	B Dynamic Range

## 5.4.3 B Mode Image Optimization

### Gain

**Description** To adjust the gain of the whole receiving information in B mode. The real-time gain value is displayed in the image parameter area in the upper left corner of the screen.

**Operation** Rotate the <Gain/iTouch> knob clockwise to increase the gain, and anticlockwise to decrease.  
The adjusting range is 0-100.

**Effects** Increasing the gain will brighten the image and you can see more received signals. However, noise may also be increased.

### Depth

**Description** This function is used to adjust the display depth of sampling, the real-time value of which is displayed on the image parameter area in the upper left corner of the screen.

**Operation** Use the <Depth/Zoom> knob to adjust the depth.  
The adjustable depth values vary depending upon the probe types.

**Effects** Increase the depth to see tissue in deeper locations, while decrease the depth to see tissue in shallower locations.

**Impacts** Depth increase will cause a decrease in the frame rate.

## TGC

- Description** The system compensates the signals from deeper tissue by segments to optimize the image.  
There are 8-segment TGC sliders on the control panel corresponding to the areas in the image.
- Operation** To increase the gain compensation at an area of interest, move the TGC slider to the right. To decrease the gain compensation at the corresponding area of interest, move the TGC slider to the left.  
About 1.5s after the adjustment is finished, the TGC curve disappears.
- Effects** Adjust the signal gain for the certain image area to get a balanced image.

## Frequency

- Description** This function is used to select the operating frequency of the current probe, the real-time value of which is displayed in the image parameter area in the upper left corner of the screen, where "F" represents B mode frequency, and "FH" represents harmonic frequency.
- Operation** Adjust it through [Frequency] on the image menu, wherein "H" means the harmonic frequency.  
Values of frequency vary depending upon the probe types. Select the frequency according to the detection depth and current tissue characteristics.
- Effects** The higher the frequency the better the near field resolution but the worse the force of penetration.  
Harmonic imaging enhances near field resolution and reduces low-frequency and large amplitude noise, so as to improve small parts imaging.

## A. power

- Description** Refers to the power of ultrasonic wave transmitted by the probe, the real-time value of which is displayed in the image parameter area in the upper left corner of the screen.
- Operation** Adjust through the [Acoustic Power] item in the image menu;  
The adjusting range is 0%-100% and the adjusting level is 32.
- Effects** Generally, increasing the acoustic power will increase the brightness and contrast of the image as well as the force of penetration.
- Impacts** You should perform exams according to actual situation and follow the ALARA Principle.

## Focus

- Description** Refers to adjustment of focus of the ultrasonic beams, symbols as "◀" of which will be displayed on the right of the image.
- Operation** Adjust the focus number through the [Focus Number] in the menu;  
Adjust the focus position through the [Focus Position] in the menu;  
In B Mode, focus number can be switched among 1-4.
- Effects** The area that is focused will be of a higher contrast and resolution to provide a much clearer image.
- Impacts** The greater the number of focus, the slower the frame rate to image.



## Imaging Display Adjustment

**Description** More information can be obtained without moving the probe or changing the sampling position.

**FOV (Field of View)**

1. To change the scan range, click [FOV] on the image menu to enter the FOV range and FOV position adjustment status.
2. Press <Set> to switch between adjusting FOV position and FOV range.
3. Rotate the trackball to adjust FOV position or the FOV range.

When the scan range is adjusted to the widest, the FOV position cannot be changed.

The FOV position/range is available only for the convex probe.

**ExFov** Click [ExFov] on the image menu to turn on/off the function.  
For linear probes, the ExFOv function displays as trapezoid imaging.  
For convex probes, the ExFOv function displays as extending the scanning angle.

**Impacts** You can get a much larger field of view when selecting a larger FOV, but the frame rate will decrease.  
You can define user-defined key for trapezoid or ExFov functions via [Setup]-> [System Preset]-> [Key Config].

**B Steer** This function is to steer the beam transmitted by the probe.  
Steer the transmitting beam through the [B Steer] item in the menu;  
The steering angles provided are: -6, 0, 6.

**Impacts** The B Steer function is available only for linear probes.

## Line Density

**Description** The function determines the quality and information of the image.

**Operation** Adjust through the [Line Density] item in the menu;  
Levels: UH/ H/ M/ L.

**Effects** The higher the line density, the higher the resolution, and the lower the frame rate.

## Dynamic Range

**Description** This function is used to adjust the B image resolution to compress or expand the gray display range.  
The real-time dynamic range value is displayed on the image parameter area in the upper left corner of the screen.

**Operation** Adjust through the [Dyn Ra.] item in the menu.  
The adjusting range is 30-220dB in increments of 5dB.

**Effects** The more the dynamic range, the more specific the information, and the lower the contrast with more noise.

## iClear

**Description** This function is used to increase image profile, so as to distinguish the image boundary.

**Operation** Adjust through the [iClear] item in the menu;  
The system provides 5 levels of iClear effects adjustment, off represents no iClear is turned on, and the bigger the value the stronger the effect.

**Effects** The bigger the value the clearer the profile of the image.

### Smooth

**Description** Rejects image noise and makes images smooth.

**Operation** Adjust through the [Smooth] item in the menu;  
The system provides 4 levels of smooth function, the bigger the value the higher the smooth adjustment.

### Persistence

**Description** This function is used to superimpose and average adjacent B images, so as to optimize the image and remove noises.

**Operation** Adjust through the [Persistence] item in the menu;  
The system provides 8 level of frame average adjustment, the bigger the value the stronger the effect.

**Effects** Persistence can remove image noise to make details to be clearer.

**Impacts** Persistence increase may lead to signal missing.

### Rotation/ Invert

**Description** This function provides a better observation for image display.

**Invert** To invert the image horizontally or vertically.  
Click [L/R Flip] or [U/D Flip] in the menu to invert the image.

**Rotation** Rotate the image through the [Rotation] item in the menu.  
Image can be rotated by the manners in angle of 0°, 90°, 180°, 270°.  
When the image is rotated in the angle of 90° or 270°, the depth scale is displayed on the upper part of the screen.

When you flip or rotate an image, the "M" mark will change its position on the screen; the M mark is located in the upper left corner of the imaging area by default.

**Impacts** The function is available in real-time imaging, freeze or cine review status.

### iBeam

**Description** This function is used to superimpose and average images of different steer angles to obtain image optimization.

**Operation** Adjust through the [iBeam] item in the menu;  
Off: no iBeam  
On: maximum iBeam optimization

**Effects** Images after iBeam processing can be optimized with less spot noise and higher resolution, so that more details for the structure are revealed.

**Impacts** iBeam is not available when trapezoid function is turned on.

## Auto Merge

**Description** In the Dual-split mode, when the images of the two windows use the same probe type, depth, invert status, rotation status and magnification factor, the system will merge the two images so as to extend the field of vision.

**Operation** Turn on/ off the function through the [Auto Merge] item in the menu;

**Impacts** Available only for linear probes.  
The function is available in real-time imaging, freeze or cine review status.

## Gray Map

**Description** Adjusting grayscale contrast to optimize the image.

**Operation** Select among the maps through the [Gray Map] item in the menu.  
The adjusting range is 1-25.

**Impacts** The function is available in real-time imaging, freeze or cine review status.

## IP

**Description** IP is a combination of several image processing parameters, which is used for a fast image optimization, the real-time group of which is displayed in the image parameter area in the upper left corner of the screen.  
The IP combination parameters include dynamic range, iClear, persistence, and smooth.

**Operation** Select among the IP groups through the [IP] item in the menu.  
The system provides 8 groups of IP combinations, and the specific value of each parameter can be preset.

## Colorize and Colorize Map

**Description** Colorize function provides an imaging process based on color difference rather than gray distinction.

**Operation** Turn on/ off the function through the [Colorize] item in the menu ;  
Select the colorize map through the [Colorize Map] item in the menu;  
The adjusting range are off, and 1-25.

**Impacts** The function is available in real-time imaging, freeze or cine review status.

## TSI

**Description** The TSI function is used to optimize the image by selecting acoustic speed according to tissue characteristics.

**Operation** Select among the TSI modes through the [TSI] item in the menu;  
The system provided 4 ways of optimization for specific tissues: general, muscle, fluid and fat.

## iTouch

**Description** To optimize image parameters as per the current tissue characteristics for a better image effect.

**Operation** Press <Gain/ iTouch> on the control panel, the iTouch symbol will display in the image parameter area.  
Click [iTouch] on the image menu to adjust gain in iTouch status among -12 through 12dB.

### Gray Rejection

**Description** This function is to reject image signals less than a certain gray scale, then the rejected signal corresponding area turns black.

**Operation** Click [Gray Rejection] in the menu to adjust.  
The adjusting range is 0-5.

### Curve

**Description** To manually enhance or restrain the signal in the certain scale.

**Operation** Click [Curve] in the menu to open the dialogue box to adjust.  
Drag the curve node to increase or decrease the gray scale information: drag the node up to increase the information and down to decrease.

### Y

**Description** The  $\gamma$  correction is used to correct non-linear distortion of images.

**Operation** Click [ $\gamma$ ] on the image menu to adjust.  
The adjusting range is 0-3, increase the value, the image turns dark.

### Gray Invert

**Description** Reverse the polarity of the image.

**Operation** Click [Gray Invert] to turn on or off the image inversion.

**Impacts** The gray rejection, curve,  $\gamma$  and gray invert functions are available in real-time imaging, freeze or cine review status.  
These post process adjustments will not influence the cine review.

### High FR

**Description** Increases the frame rate when being turned on in THI mode.

**Operation** In single B mode when THI is turned on, click the [High FR] item in the menu to obtain images with high frame rates.

### H Scale

**Description** Display or hide the width scale (horizontal scale).  
The scale of the horizontal scale is the same as that of vertical scale (depth), they change together in zoom mode, or when the number of the image window changes. The H Scale will be inverted when image is turned up/down.

**Operation** Click [H Scale] on the menu to display or hide the scale.

### Middle Line:

**Description** "Middle Line" is used to locate the focus point of lithotripsy wave during lithotripsy treatment. For details, please refer to 12.3 Middle Line

**Operation** Click [Middle Line] in the image menu at the left side of the screen to turn on the lithotripsy.

### LGC

**Description** Adjust the gain of scan lines to increase the image lateral resolution.

**Operation** Click [LGC] to access the adjusting dialog box.

The 8 LGC items displayed on the screen indicate the corresponding image areas on the image screen.

Click corresponding [LGC1-8] to adjust the gain. The higher the value, the higher the gain.

The system also provides several preset parameters for imaging.

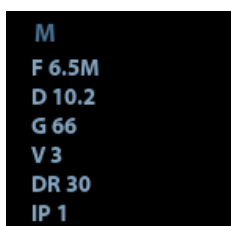
## 5.5 M Mode

### 5.5.1 M Mode Exam Protocol

1. Select a high-quality image during B mode scanning, and adjust to place the area of interest in the center of the B mode image.
2. Press <M> on the control panel, and roll the trackball to adjust the sampling line.
3. Press <M> on the control panel again or <Update> to enter M mode, then you can observe the tissue motion along with anatomical images of B mode.
4. During the scanning process, you can also adjust the sampling line accordingly when necessary.
5. Adjust the image parameters to obtain optimized images.
6. Perform other operations (e.g. measurement and calculation) if necessary.

### 5.5.2 M Mode Parameters

- In M mode scanning, the image parameter area in the upper left corner of the screen displays the real-time parameter values as follows:



```
M
F 6.5M
D 10.2
G 66
V 3
DR 30
IP 1
```

Display	V	IP	DR	G
Parameter	M Speed	M IP	M Dynamic Range	M Gain

- During M mode imaging, you can switch between B and M menu from the menu title.
- During M Mode scanning, frequency and acoustic power of the transducer are synchronous with that of B Mode.
- Adjustment of the depth or TGC to the B Mode image will lead to corresponding changes in M Mode image.

### 5.5.3 M Mode Image Optimization

#### Gain

**Description** To adjust the gain of M mode image. The real-time gain value is displayed in the image parameter area in the upper left corner of the screen.

**Operation** Rotate the <Gain/ iTouch> knob clockwise to increase the gain, and anti-clockwise to decrease.

The adjusting range is 0-100.

**Effects** Increasing the gain will brighten the image and you can see more received signals. However, noise may also be increased.

#### Depth

**Description** This function is used to adjust the display depth of sampling, the real-time value of which is displayed on the image parameter area in the upper left corner of the screen.

**Operation** Use the <Depth/Zoom> knob to adjust the depth.

The adjustable depth values vary depending upon the probe types.

**Effects** Increase the depth to see tissue in deeper locations, while decrease the depth to see tissue in shallower locations.

**Impacts** Depth increase will cause a decrease in the frame rate.

#### Frequency

**Description** This function is used to select the operating frequency of the current probe, the real-time value of which is displayed in the image parameter area in the upper left corner of the screen, where “F” represents B mode frequency, and “FH” represents harmonic frequency.

**Operation** Adjust it through [Frequency] on the image menu, wherein “H” means the harmonic frequency.

Values of frequency vary depending upon the probe types. Select the frequency according to the detection depth and current tissue characteristics.

**Effects** The higher the frequency the better the near field resolution but the worse the force of penetration.

Harmonic imaging enhances near field resolution and reduces low-frequency and large amplitude noise, so as to improve small parts imaging.

#### A. power

**Description** Refers to the power of ultrasonic wave transmitted by the probe, the real-time value of which is displayed in the image parameter area in the upper left corner of the screen.

- Operation** Adjust through the [Acoustic Power] item in the image menu;  
The adjusting range is 0%-100% and the adjusting level is 32.
- Effects** Generally, increasing the acoustic power will increase the brightness and contrast of the image as well as the force of penetration.
- Impacts** You should perform exams according to actual situation and follow the ALARA Principle.

### Focus Position

- Description** To change the focus position in M mode, symbols as "◀" of which are displayed on the right of the image.
- Operation** Adjust the focus position through the [Focus Position] item in the menu. the adjusting level of the focus position is 16

### Time Mark

- Description** To show the time mark in M mode image.
- Operation** Turn on or off the function through [Time Mark] item in the menu.
- Effects** When time mark is displayed on the M mode image, it's much easier to identify the cardiac cycles and detect more details.
- Impacts** The function is available in real-time imaging, freeze or cine review status.

### Display Format

- Description** To set the display format of M mode image with B mode image.
- Operation** Adjust through the [Display Format] item in the menu;  
There are 4 formats available for the images display: V2/1, V1:1, V1:2, Full.
- Effects** Adjust according to the actual situation and obtain a desired analysis through comparison.

### Speed

- Description** This function is used to set the scanning speed of M mode imaging, and the real-time speed value is displayed in the image parameter area in the upper left corner of the screen.
- Operation** Change the speed through the [Speed] item in the menu.  
There are 6 levels of scan speed available, the smaller the value the faster the speed.
- Effects** Speed changing makes it easier to identify disorders in cardiac cycles.

### IP

- Description** IP is a combination of several image processing parameters, which is used for a convenient image optimization. The IP combination number is displayed on the image parameter area on the right part of the screen.  
The M IP combination parameters include dynamic range and M soften.
- Operation** Select among the IP groups through the [IP] item in the menu.  
The system provides 8 groups of IP combinations, and the specific value of each parameter can be preset.

## Colorize and Colorize Map

- Description** Colorize function provides an imaging process based on color difference rather than gray distinction.
- Operation** Turn on or off the function through the [Colorize] item in the menu;  
Select the colorize map through the [Colorize Map] item in the menu;  
The adjusting range are off, and 1-25.
- Impacts** The function is available in real-time imaging, freeze or cine review status.

## Gray Rejection

- Description** This function is to reject image signals less than a certain gray scale, then the rejected signal corresponding area turns black.
- Operation** Click [Gray Rejection] on the image menu to adjust.  
The adjusting range is 0-5.

## Curve

- Description** To manually enhance or restrain the signal in the certain scale.
- Operation** Click [Curve] in the menu to open the dialogue box to adjust.  
Drag the curve node to increase or decrease the gray scale information: drag the node up to increase the information and down to decrease.

## Y

- Description** The  $\gamma$  correction is used to correct non-linear distortion of images.
- Operation** Click [ $\gamma$ ] on the image menu to adjust.  
The adjusting range is 0-3.

## Gray Invert

- Description** Reverse the polarity of the image.
- Operation** Click [Gray Invert] to turn on or off the image inversion.
- Impacts** The gray rejection, curve,  $\gamma$  and gray invert functions are available in real-time imaging, freeze or cine review status.  
These post process adjustment will not influence the cine review.

## Gray Map

- Description** Adjusting grayscale contrast to optimize the image.
- Operation** Select among the maps through the [Gray Map] item in the menu.  
The adjusting range is 1-25.
- Impacts** The function is available in real-time imaging, freeze or cine review status.

## Edge Enhance

- Description** This function is used to increase image profile, so as to distinguish the image boundary.



**Operation** Adjust through the [Edge Enhance] item in the menu;  
The edge enhance adjustment range is 0-14, the bigger the value the stronger the effect.

**Impacts** Larger edge enhance may lead to noise increasing.

### **Dynamic Range**

**Description** Adjusts contrast resolution of an image, compresses or expands gray display range. The real-time dynamic range value is displayed on the image parameter area in the upper left corner of the screen.

**Operation** Adjust through the [Dyn Ra.] item in the menu.  
The adjusting range is 30-220dB in increments of 5dB.

**Effects** The more the dynamic range, the more specific the information, and the lower the contrast with more noise.

### **M Soften**

**Description** This feature is used to process the scan lines of M images to reject noise, making the image details to be clearer.

**Operation** Adjust through the [M Soften] item in the menu;  
The M Soften adjustment range is 0-14, the bigger the value the stronger the effect.

## 5.6 Color Mode Image Optimization

The Color mode is used to detect color flow information, and the color is designed to judge the direction and speed of blood flow.

Generally, the color above the color bar indicates the flow towards the probe, while the color below the color bar indicates the flow away from the probe; the brighter the color, the faster the flow speed, while the darker the color, the slower the flow speed.

### 5.6.1 Color Mode Exam Protocol

1. Select a high-quality image during B mode scanning, and adjust to place the area of interest in the center of the image.
2. Press <Color> to enter B+Color mode. Use the trackball and <Set> to change position and size of the Region of Interest (ROI).
3. Adjust the image parameters during scanning to obtain optimized images.
4. Perform other operations (e.g. measurement and calculation) if necessary.

### 5.6.2 Color Mode Image Optimization

- In PW/ Color mode scanning, the image parameter area in the upper left corner of the screen displays the real-time parameter values as follows:

Parameter	F	G	PRF	WF
Meaning	Frequency	Color Gain	Pulse Repetition Frequency (PRF)	Color Wall Filter

- In Color Mode, acoustic power is synchronous with that of B Mode. Adjustment of the depth or zoom to the B Mode image will lead to corresponding changes in Color Mode image.

### 5.6.3 Color Mode Image Optimization

#### Frequency

**Description** Refers to the operating frequency in Color mode of the probe, the real-time value of which is displayed in the image parameter area in the upper corner of the screen.

**Operation** Adjust it through [Frequency] on the image menu or rotate the <Focus/ Freq./ THI> knob on the control panel.

Values of frequency vary by probe. Select the frequency value according to the need of the detection depth and the current tissue characteristics.

**Effects** The higher the frequency, the worse the axial resolution, and the better the force of penetration.

#### Color Gain

**Description** Refers to the overall sensitivity to flow signals, and this function is used to adjust the gain in Color mode. The real-time gain value is displayed in the image parameter area in the upper right corner of the screen.

<b>Operations</b>	Rotate the <Gain/iTouch> knob clockwise to increase the gain, and anticlockwise to decrease. The adjusting range is 0-100.
<b>Effects</b>	Increasing the gain will increase the flow signal presented as well as noise, while the signals may be missing when the gain is adjusted too low.
<b>Steer</b>	
<b>Description</b>	The feature is used to adjust the ROI of color flow of different angles with immobility of the linear probe.
<b>Operations</b>	Adjust through the <Steer> key on control panel or [Steer] item on image menu.
<b>Effects</b>	This function is used to adjust the scan angle of linear probes, so as to change the angle between the transmitting beam and flow direction.
<b>Impacts</b>	Steer is valid only for linear probes.
<b>Scale</b>	
<b>Description</b>	This function is used to adjust the speed range of color flow, which is adjusted through PRF in the system. The real-time PRF value is displayed in the image parameter area in the upper right corner of the screen.
<b>Operations</b>	Press the <Scale> key on the control panel and rotate the Multifunctional Knob on the left to adjust. The adjusting range varies by frequency, probe and depth; adjust according to the actual situation.
<b>Effects</b>	To provide a much clearer color flow image. Use low PRF to observe low-velocity flows, and high PRF to observe high-velocity flows.
<b>Impacts</b>	Aliasing may occur if low velocity scale is used and high velocities are encountered. Low velocities may not be identified when a high velocity scale is used.
<b>Baseline</b>	
<b>Description</b>	Refers to the area where the velocity is zero in the scale. Adjust according to the actual situation so as to get an optimum flow display.
<b>Operations</b>	Press the <Baseline> key on the control panel and rotate the Multifunctional Knob on the left to adjust. Positive value means to increase the signals above the baseline, and negative value means to increase the signals below the baseline.
<b>Invert</b>	
<b>Description</b>	To set the display mode of color flow and the color scale will be inverted when the function is turned on.
<b>Operations</b>	Turn on or off the function through the [Invert] item on the image menu. Select "Auto Invert" in the "[Setup] → [System Preset] → [Image]", then the color bar can automatically invert when the color flow is steered to a certain angle to accommodate operator's habit of distinguishing flow direction.

## Priority

**Description** This function is used to set levels of the flow display, to display the grayscale signal or color signal.

**Operations** Click the [Priority] item on the image menu to select the value.  
The adjusting range of the priority is 0-100%.  
The higher the value, color signals are prior to be displayed; while the lower the value, grayscale signals are prior to be displayed.

## Packet Size

**Description** This function is an indication of the ability to detect flow, which is used to adjust the accuracy of color flow.

**Operations** Click the [Packet Size] item on the image menu to adjust the value.  
There are 0-3 levels of packet size available, 0 represents no packet size control and the bigger the value the higher the sensitivity.

**Effects** The higher the packet size, the more sensitive indication for low-velocity flow.

**Impacts** Adjusting the packet size may lead to frame rate changing.

## Persistence

**Description** This function is to adjust the temporal smooth in Color mode to optimize the image.

**Operations** Click the [Persistence] item on the image menu.  
The system provides 0-4 levels of persistence adjustment, 0 represents no persistence and the bigger the value the stronger the effect.

## WF (Wall Filter)

**Description** It filters out low-velocity signals to provide effective information, and this function is used to adjust the filtered frequency. The real-time value is displayed in the image parameter area in the upper right corner of the screen.

**Operations** Click the [WF] item on the image menu.  
There are 0-7 levels of wall filter function available, and adjust according to the actual situation.

**Impacts** Flow signals may be missing.

## Map

**Description** This function is a combination of several image parameters, which indicates the display effect of color image.

**Operations** Click the [Map] item on the image menu to select among the maps.  
The system provides 21 different maps to be selected among, where the V group provides 11 ordinary maps and the VV group provides 10 2D maps.

## **B/C Align**

- Description** To set and constrain the maximum width of the B mode image to that of the Color ROI.
- Operations** Turn on or off the function through the [B/C Align] item on the image menu.
- Impacts** Frame rate increases when the function is turned on.

## **Dual Live**

- Description** This function is used to display B image and Color image synchronously.
- Operations** Turn on or off the function through the [Dual Live] item on the image menu.  
When the function is turned on, the window will be automatically switched to the dual windows (one for B image, and the other for Color image).

## **Line Density**

- Description** Line density determines the quality and information of the image.
- Operations** Adjust through the [Line Density] item on the image menu.  
There are 4 levels of line density provided: H, L, UH, M.
- Effects** The higher the line density, the higher the resolution.
- Impacts** The higher the line density, the lower the frame rate.

## **ROI Adjustment**

- Description** This function is to adjust the width and position of ROI in Color mode.
- Operations** When the ROI box is dotted line, roll the trackball to change the size.  
When the ROI box is solid line, roll the trackball to change the position.  
Press <Set> to switch between the solid line and the dotted line.
- Impacts** The larger the ROI box, the lower the frame rate, and the lower the resolution and color sensitivity.

## **Smooth**

- Description** This feature is used to reject noise and smooth the image.
- Operations** Adjust through the [Smooth] item on the image menu.  
The system provides 0-4 levels of smooth function, the bigger the value the higher the smooth.

# **5.7 Power Mode Image Optimization**

Power mode provides a non-directional display of blood flow in the form of intensity as opposed to flow velocity.

DirPower (Directional Power mode) provides additional information of flow direction towards or away from the probe.

## 5.7.1 Basic Procedures for Power Mode Imaging

1. Select a high-quality image during B + Color scanning, and adjust to place the area of interest in the center of the image.
2. Click [Power] on image menu to enter B + Power mode. Roll the trackball to change position of the Region of Interest (ROI) and press the <Set> key to set. Roll the trackball to change the size and position of ROI.
3. Adjust the image parameters during B + Power mode scanning to obtain optimized image.
4. Perform other operations (e.g. measurement and calculation) if necessary.

## 5.7.2 Power Mode Image Parameters

- In Power mode scanning, the image parameter area in the upper right corner of the screen displays the real-time parameter values as follows:

Parameter	F	G	PRF	WF
Meaning	Frequency	Power Gain	Pulse Repetition Frequency (PRF)	Power Wall Filter

- In Power mode, acoustic power is synchronous with that of B mode. Adjustment of the depth to the B mode image will lead to corresponding changes in Power mode image.

Parameters consistent with those in Color mode and B mode are not to be introduced, please refer to relevant sections of the Color mode and B mode, while special items of the Power mode are introduced in the following.

## 5.7.3 Power Mode Image Optimization

### Power Gain

**Description** Refers to the overall sensitivity to flow signals, and this function is used to adjust the gain in Power mode.  
The real-time gain value is displayed in the image parameter area in the upper right corner of the screen.

**Operations** Rotate the <Gain/iTouch> knob to adjust the gain.  
The adjusting range is 0-100.

**Effects** Increasing the gain will increase the flow signal presented as well as noise, while the signals may be missing when the gain is adjusted too low.

### Power Map

**Description** This feature indicates the display effect of Power image.  
The maps in the Power mode image are grouped into two categories: Power maps and Directional Power maps.

**Operations** To select among the maps, turn the knob under [Map] on the image menu.  
 There are 8 kinds of maps provided: P0-P3 belong to Power mode maps, while dP0-dP3 belong to Directional Power mode maps.  
 The Power maps provide information of blood flow, which are highly sensitive to the low-velocity flows.  
 The Directional Power maps provide information of flow direction.

### Dynamic Range

**Description** This function is to adjust the transformation of echo intensity into color signal.

**Operations** Click the [Dynamic Range] item on the image menu to adjust the dynamic range.  
 The adjusting range is 10-70dB in increments of 5dB.

**Effects** Increasing dynamic range will lead to higher sensitivity to low-power signals, thus enhances the range of signals to display.

## 5.8 PW Doppler Mode

PW (Pulsed Wave Doppler) mode is used to provide blood flow velocity and direction utilizing a real-time spectral display. The horizontal axis represents time, while the vertical axis represents Doppler frequency shift.

PW mode provides a function to examine flow at one specific site for its velocity, direction and features.

PW is optional.

### 5.8.1 Basic Procedures for PW Mode Exam

1. Select a high-quality image during B mode scanning.
2. Press the user-defined key for the PW mode to adjust the sampling line,
  - The sampling status will be displayed in the image parameter area in the upper right corner of the screen as follows:

PW Sampling Line Adjustment	SV
	Angle
	SVD

3. Set the position of the sample line by moving the trackball left and right, and set the SVD by moving the trackball up and down, adjust the angle and SV size according to the actual situation.

4. Press the user-defined key for the PW mode or <Update> to enter PW mode again and perform the examination. You can also adjust the SV size, angle and depth in real-time scanning.
5. Adjust the image parameters during PW mode scanning to obtain optimized image.
6. Perform other operations (e.g. measurement and calculation) if necessary.

## 5.8.2 PW Mode Image Parameters

In PW mode scanning, the image parameter area in the upper right corner of the screen displays the real-time parameter values as follows:

Parameter	F	G	PRF	WF	SVD	SV	Angle
Meaning	Frequency	Gain	PRF	Wall Filter	SV Position	SV Size	Angle

- When you adjust the depth of the B mode image, related changes will occur in PW mode image as well.

## 5.8.3 PW Mode Image Optimization

### Gain

**Description** This function is intended to adjust the gain of spectrum map. The real-time gain value is displayed in the image parameter area in the upper right corner of the screen.

**Operations** Rotate the [Gain/iTouch] knob to adjust the gain.  
The adjusting range is 0-100.

**Effects** Increasing the gain will brighten the image and you can see more received signals. However, noise may also be increased.

### Frequency

**Description** Refers to the operating frequency in PW mode of the probe, the real-time value of which is displayed in the image parameter area in the upper left corner of the screen.

**Operation** Select the frequency value through the [Frequency] item in the image menu or rotate the <Focus/Freq./THI> knob on the control panel.

Values of frequency vary depending upon the probe types.

Select the frequency according to the detection depth and current tissue characteristics.

**Effects** The higher the frequency, the better the resolution and sensitivity, and the worse the force of penetration.

### A. power

**Description** Refers to the power of ultrasonic wave transmitted by the probe, the real-time value of which is displayed in the image parameter area in the upper left corner of the screen.

**Operation** Adjust through the [Acoustic Power] item in the image menu;  
The adjusting range is 0%-100% and the adjusting level is 32.



**Effects** Generally, increasing the acoustic power will increase the brightness and contrast of the image as well as the force of penetration.

**Impacts** You should perform exams according to actual situation and follow the ALARA Principle.

### **Baseline**

**Description** Refers to the area where the velocity is zero in the spectrum.

**Operations** Press the <Baseline> key on the control panel and rotate the Multifunctional Knob on the left to adjust. The adjustment range is -4 to 4.

**Effects** To change the range of flow velocity to optimize the image.

### **PW Steer**

**Description** This function provides adjustment on angles for sampling line.

**Operations** Adjust through the [Steer] item on image menu.

**Effects** This feature is used to steer the direction of the beam so as to change the angle between the beam and flow direction with immobility of the linear probe. Values of steer angles vary by probe. Steer is available only for linear probes

### **Invert**

**Description** This function is used to set the display manner of spectrum.

**Operations** Turn on or off the function through the [Invert] item on the image menu.

### **Scale**

**Description** This function is used to adjust the speed range of flow, which is adjusted through PRF in the system. The real-time PRF value is displayed in the image parameter area in the upper right corner of the screen.

**Operations** Press the <Scale> key on the control panel and rotate the Multifunctional Knob on the left to adjust.

**Effects** To provide a much clearer color flow image. Use low PRF to observe low-velocity flows, and use high PRF to observe high-velocity flows.

**Impacts** Aliasing may occur if low velocity scale is used and high velocities are encountered. Low velocities may not be identified when a high velocity scale is used.

### **Wall Filter**

**Description** It filters out low-velocity signals to provide effective information, and this function is used to adjust the filtered frequency. The real-time value is displayed in the image parameter area in the upper right corner of the screen.

**Operations** Select through the [WF] item on the image menu. There are 0-6 levels of wall filter function provided.

**Impacts** Signals of low-velocity flow may be missing.

## **T/F Res**

**Description** This function is used to adjust for a balance between time resolution and spatial resolution.

**Operations** Adjust through the [T/F Res] item on the image menu.  
There are 0-4 levels of T/F Res values available.

## **Dynamic Range**

**Description** The dynamic range conveys the information that being transformed from echo intensity to gray scale.

**Operations** Adjust through the [Dynamic Range] item on the image menu.  
The adjusting range is 24-72dB in increments of 2dB.

**Effects** The more the dynamic range, the more specific the information, and the lower the contrast with more noise.

## **Speed**

**Description** This function is used to set the scanning speed of PW mode imaging.

**Operations** Click the [Speed] item on the image menu.  
There are 1-6 levels of scan speed available, the smaller the value the faster the speed.

**Effects** Changing the speed makes it easier to identify the cardiac cycles and to detect more details.

## **Display Format**

**Description** To set the display format of PW mode image with B mode image.

**Operations** Click the [Display format] item on the image menu to adjust.  
Options: V2:1, V1:2, V1:1, Full.

## **Audio**

**Description** This function is used to adjust the output audio in spectrum map.

**Operations** Click the <Audio> item on the image menu to adjust the volume.  
The adjusting range of the audio is 0-100% in increments of 2.

**Effects** Utilizing the output audio helps to identify the feature and status of flow.

## **Gray Map**

**Description** This function applies the gray correction to obtain the optimum images.

**Operations** Click the [Gray Map] item on the image menu.  
There are 1-25 maps available.

## **Colorize and Colorize Map**

**Description** Colorize function provides an imaging process based on color difference rather than gray distinction.

- Operation** Turn on or off the function through the [Colorize] item in the menu;  
Select the colorize map through the [Colorize Map] item in the menu;  
The adjusting range are off, and 1-25.
- Impacts** The function is available in real-time imaging, freeze or cine review status.

### Duplex/ Triplex

- Description** This function is used to set if B image and PW image are displayed synchronously.
- Operations** Click [Duplex/ Triplex] on the image menu to turn on or off the synchronization.

### Auto Calculation

- Description** This function is used to trace the spectrum and calculate parameters of PW image, and the results of which are displayed in the result window.
- Auto Calculation** Turn on or off the auto calculation function through the [Auto Calc] item on the image menu.
- Auto Calculation Parameter** Select parameters in the dialogue box prompted by clicking [Auto Calc Param] on the image menu.
- Auto Calc Cycle** To set the number of heart cycle for auto calculation.  
Click [Auto Calc Cycle] on the image menu to select the cycle number. The adjustment range is 1-5.
- Operations** In real-time scanning, the results displayed are derived from the calculation of latest cardiac cycle;  
In the freeze and cine status, the results displayed are calculated from the current selected area.

### Trace

- Trace Area** To set the trace area of the Doppler wave in the spectrum map, applicable for auto calculation.  
Change the trace area through the [Trace Area] item on the image menu.  
The available selections are: Above, Below, All.

### SV

- Description** To adjust the SV position and size of sampling in PW mode, the real-time value of SV and SVD are displayed in the image parameter area in the upper right corner of the screen.
- SV size** Click the [SV] on the image menu to adjust the SV size.  
Value: 0.5-20mm.
- SVD** Roll the trackball to select the SV depth.
- Effects** The smaller the SV size, the more accurate the result; and more details are obtained when selected large SV size.

## iTouch

**Description** To optimize image parameters as per the current tissue characteristics for a better image effect.

**Operations** Press <Gain/ iTouch> on the control panel to turn on the function.

## Angle

**Description** This function is used to adjust the angle between Doppler vector and flow to make the velocity more accurate.

The real-time adjusting angle value is displayed on the right part of the spectrum map.

**Operations** Click the <Angle> item on the image menu to adjust.

The adjustable angle range is -89~89°, in increments of 1°.

## Quick Angle

**Description** To adjust the angle faster, in increments 60°, and the real-time value of which is displayed on the right part of the spectrum map.

**Operations** Click the [Quick Angle] item on the image menu.

There are 3 angles for quickly adjustment: -60°, 0°, and 60°.

# 5.9 Anatomical M Mode (Free Xros M)



### CAUTION:

**Anatomical M Mode and Color Anatomical M mode images are provided for reference only, not for confirming a diagnosis. Please compare the image with that of other machines, or make diagnosis using none-ultrasound methods.**

For an image in the traditional M mode, the M-mark line goes along the beams transmitted from the probe. Thus it is difficult to obtain a good plane for difficult-to-image patients that cannot be moved easily. However, in the Anatomical M mode, you can manipulate the M-mark line to move to any position at desired angles. The system supports anatomical M scanning (including Free Xros M mode) in 2D imaging modes (B, Color and Power mode).

#### ■ Shortcut key setting

You can preset a user-defined key for entering Free Xros M mode: [Setup] -> [System Preset] -> [Key Config].

#### ■ Free Xros M Imaging Procedures

1. In real-time 2D mode or M mode, adjust the probe and image to obtain the desired plane.

Or select the desired 2D cine files.

2. Click [Free Xros M] on the image menu of the B mode to enter Free Xros M mode, or press the user-defined key.
3. Adjust the M-mark line to obtain optimized images and necessary information.

#### ■ In Dual-split or Quad-split mode, it is the current activated window that enters the Free Xros M mode.

Free Xros M imaging is supported on frozen B image, B+M image and B+Power/Color image.

### 5.9.1.1 Free Xros M Image Parameters

- Parameters consistent with those in M mode are not to be introduced, please refer to relevant section of the M mode, while special items of the Free Xros M mode will be introduced in the following.

#### Display/Hide the M-mark Line

<b>Description</b>	There are 1 M-mark line available.
<b>Display current</b>	Press the current green M-mark line.
<b>Impacts</b>	The one M-mark line on the screen cannot be hidden.

#### Switching between the M-mark Lines

<b>Description</b>	To switch between the M-mark status in Free Xros M mode.
<b>Operations</b>	Press <Set> to hide or show between the M-mark lines and press <Cursor> to show the cursor. The activated M-mark line will be green.

#### Adjustment of the M-mark Line

<b>Description</b>	To adjust the position and angle of the M-mark line.
<b>Operations</b>	<ul style="list-style-type: none"><li>● Position Adjustment When the M-mark line is activated, move the trackball left and right to adjust the position. The direction is recognized by the arrow at the end of the line.</li><li>● Angle Adjustment When the M-mark line is activated, move the trackball to adjust the fulcrum of the line, and adjust through the [Angle] item on the menu. The adjusting angle range is 0-360, in increments of 1.</li></ul>

### 5.9.1.2 Exit Free Xros M

In Free Xros M mode, click [Free Xros M] or press <B> or the user-defined Free Xros M key to exit Free Xros M mode.

## 5.10 Smart 3D

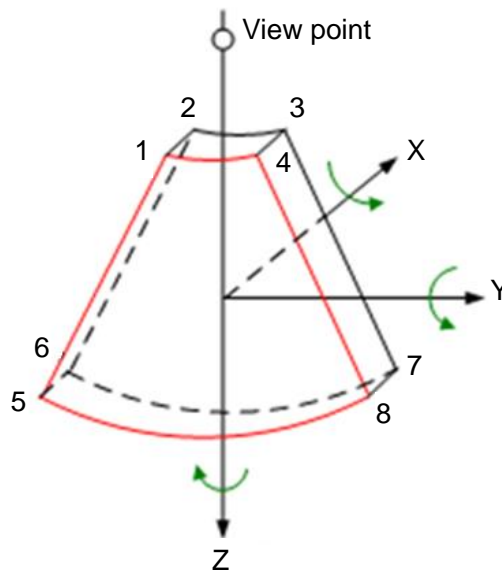
**NOTE:** 3D imaging is largely environment-dependent, so the images obtained are provided for reference only, not for confirming diagnoses.

### 5.10.1 Overview

Ultrasound data based on three-dimensional imaging methods can be used to image any structure where a view cannot be achieved with the standard 2D-mode and to improve the understanding of complex structures.

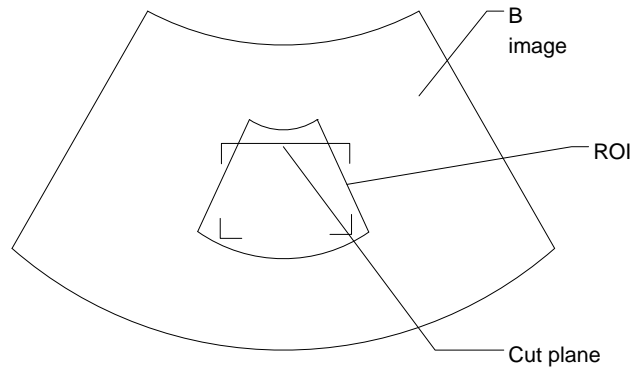
#### ■ Terms

- 3D image Volume Rendering (VR): the image displayed to represent the volume data.
- View point: a position for viewing volume data/3D image.
- MultiPlaner Rendering (MPR): the three sectional planes of the volume acquisition. As shown in the figure below, the XY-parallel plane is the C-section, the XZ-parallel plane is the B-section, and the YZ-parallel plane is the A-section. The probe is moved along the X-axis.
- ROI (Region of Interest): a volume box used to determine the height and width of scanning volume.
- VOI (Volume of Interest): a volume box used to display the 3D image (VR) by adjusting the region of interest in MPR.



#### ■ ROI and VOI

After the system enters 3D imaging, a B image with ROI displays on the screen. A line (shown in the following figure) shows that the upper edge position of the VOI is inside the ROI.



- ROI size and position  
Roll the trackball to change the ROI size and position. Press the <Set> key to toggle between setting the size (dotted line) and position (solid line).
- Curved VOI adjustment  
Roll the trackball to change the curved VOI position. Press the <Set> key to switch between the changing ROI and curved VOI states.

This function changes the curved shape of the nearest VOI section and facilitates observation of the volume data of interest.

When a triangle of control point is displayed on the curved VOI, it can be adjusted in acquisition preparation status.

The orientation and shape (line or dot) of curved VOI vary depending on the view direction:

View	Curved VOI
U/D	At the upper part of curved VOI
D/U	At the lower part of curved VOI
L/R	At the left part of curved VOI
R/L	At the right part of curved VOI
F/B	Displays as a dot
B/F	Displays as a dot

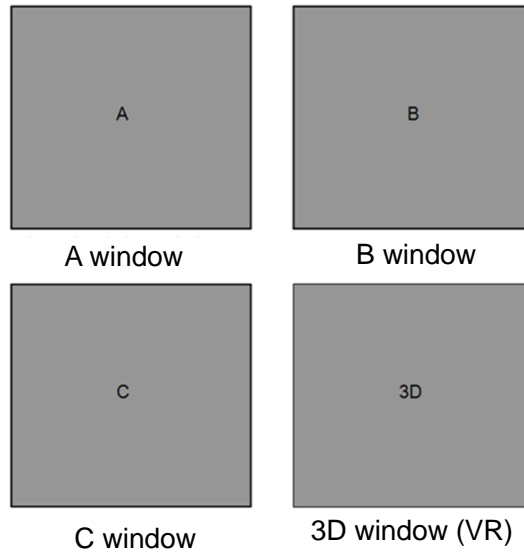
■ About the probes

A 2D imaging probe can be applied for Smart 3D imaging.

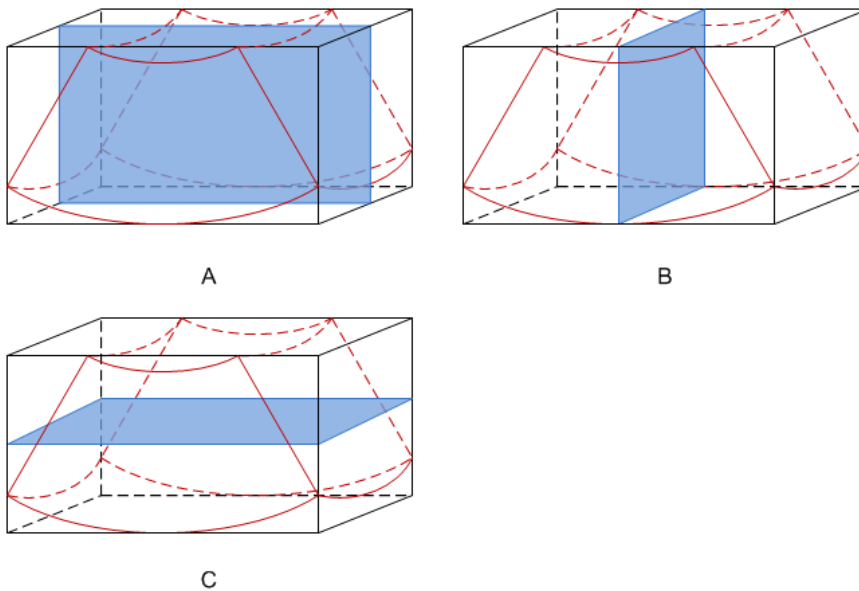
■ MPR

The principle of 3D imaging is to render a 3D image from multiple 2D image information. The following describes the spatial relationship of 3 MPRs (A, B and C) and the 3D image (VR).

In the quad display format view, the screen displays 3 MPRs (A, B and C) and the 3D image.




- On the soft menu, select [Current Window: X] to activate the target window.  
A, B and C sectional images correspond to the following sections of the 3D image.



- Section A: corresponds to the 2D image in B mode. Section A is the sagittal section .
- Section B: is the horizontal section.
- Section C: is the coronal section.

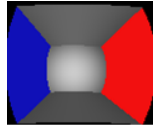
Tip: the upper part of the 3D image in the 3D window corresponds to the orientation mark on the probe. If the posture is head down (toward the mother's feet), and the orientation mark is toward the mother's head, then the fetus posture is head down in the 3D image. The 3D image can be rotated by selecting [Quick Rot.: 180°] on the soft menu to show the fetus head-up.

 **CAUTION:** Ultrasound images are provided for reference only, not for confirming diagnoses. Use caution to avoid misdiagnosis.

- Wire cage  
When viewing a 3D image on the display monitor, it is sometimes difficult to recognize the orientation. To help, the system displays a three-dimensional drawing to illustrate the



orientation. The blue plane shows the image acquisition where started, while the red plane shows the image acquisition where ended. A yellow plane in the wire cage shows the position of the MPR. See the image below:



Wire Cage

## 5.10.2 Note Before Use

### 5.10.2.1 3D Image Quality Conditions

**NOTE:** In accordance with the ALARA (As Low As Reasonably Achievable) principle, try to shorten the sweeping time after a good 3D image is obtained.

■ Angle of a B tangent plane

The optimum tangent plane to the face 3D imaging is the sagittal section of the face. To ensure high image quality, scan the maximum face area and maintain edge continuity.

■ Image quality in B mode (2D image quality)

Before entering 3D capture, optimize the B mode image to ensure:

- High contrast between the desired region and the surrounding AF.
- Clear boundary of the desired region.
- Low noise of the AF area.

■ Scanning technique (only for Smart 3D)

- Stability: the body, arm and wrist must move smoothly, otherwise the restructured 3D image distorts.
- Slowness: move or rotate the probe slowly.
- Evenness: move or rotate the probe at a steady speed or rate.

**NOTE:**

1. A region with a qualified image in B mode may not be optimal for 3D imaging. E.g., adequate AF isolation for one MPR does not mean the whole desired region is isolated by AF.
2. Practice is needed for a high success rate of qualified 3D imaging.

## 5.10.3 Smart 3D

The operator manually moves the probe to change its position/angle when performing the scan. After scanning, the system carries out image rendering automatically, then displays a frame of the 3D image.

Smart 3D is an option.

### 5.10.3.1 Basic Procedures for Smart 3D Imaging

**NOTE:** In Smart 3D image scanning, if the probe orientation mark is oriented to the operator's finger, perform the scan from right to left in linear scan, or rotate the probe from left to right in rocked scanning. Otherwise, the VR direction will be wrong.

To perform Smart 3D imaging:

1. Select the appropriate probe and exam mode. Make sure there is sufficient gel on the probe for scanning.

2. Obtain a 2D image.
3. Press <3D/4D> key or user-defined key for [3D] to enter the Smart 3D imaging preparation status, and define the ROI as well as the curved VOI.
4. Select a render mode.
5. Select an acquisition method, and set the corresponding parameters on the soft menu.  
 Rocked mode: set [Angle] parameter.  
 Linear mode: set [Distance] parameter.
6. Press <Update> on the control panel to start the 3D image acquisition.  
 The system enters the 3D image viewing status when the acquisition is complete. Or, end the acquisition by pressing <Freeze> or <Update> on the control panel.  
 In image viewing status, operations such as VOI setting and image editing can be performed.
7. Exit Smart 3D.  
 Press <Update> or <Freeze> to return to Smart 3D image acquisition preparation. Or, press <B>, <3D/4D> key or user-defined key for [3D] to exit Smart 3D.

### 5.10.3.2 Smart 3D Acquisition Preparation

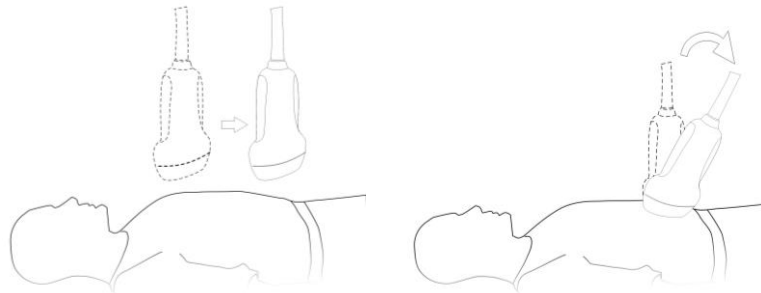
In Smart 3D mode, you need to set the scan method.

■ Method

Capture images using Linear scan or Rocked scan.

● Linear scanning

Move the probe across the surface. See the following figure.



● Rocked scanning

Rotate the probe once from the left to the right side (or from the right to the left) to include the entire desired region. See the figure.

■ Description of parameters:

■ Description of parameters:

Type	Parameter	Description
Parameter adjusting	Angle	Function: to set the angle the probe covered during a fan sweep.
	Quality	Function: to adjust the image quality by changing the line density. Image quality can affect the imaging speed: the better the image quality, the longer the time.
Render Mode	Surface	Function: set Surface as the 3D image rendering mode. This is useful for surface imaging, such as fetus face, hand or foot. Tip: you may have to adjust the threshold to obtain a clear body boundary.

Type	Parameter	Description
	Max.	Function: set Max. as the 3D image rendering mode. Displays the maximum echo intensity in the observation direction. This is useful for viewing bony structures.
	Min.	Function: set Min. as the 3D image rendering mode. Displays the minimum echo intensity in the observation direction. This is useful for viewing vessels and hollow structures.
	X-ray	Function: set X-ray as the 3D image rendering mode. Displays the average value of all gray values in the ROI. X Ray: used for imaging tissues with different internal structures or tissues with tumors.
Method		Function: select the image acquisition method. Selection: Rocked, Linear. Linear mode: during the sweep, the probe must be kept parallel. The scanning speed should be constant. Rocked mode: in this mode, the probe must be moved to a position where you can clearly see a middle cut of the object you want to scan and render. Tilt the probe to about 30 degrees until the object you want to scan disappears. Start the acquisition and tilt the probe over a distance of around 60 degrees until the object disappears again. During the sweep, the probe may not be moved parallel, just tilted. Tip: the speed is related to scanning distance or angle.
Distance		Function: to set the distance the probe covered from one end to the other end during a linear sweep.

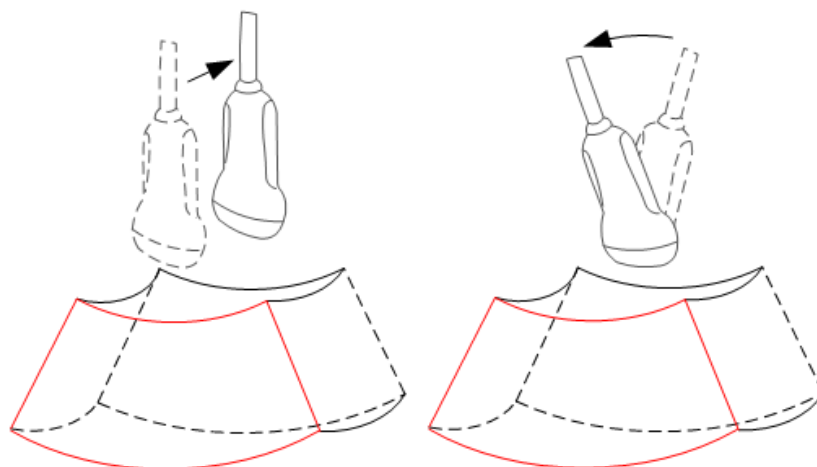
### 5.10.3.3 Smart 3D Image Viewing

In VR viewing, the system supports the following functions:

- Render setting.
- B-mode parameter adjustment.
- Setting the display format.
- Viewing MPR.
- Image zooming.
- Rotation.
- Image editing.
- VR parameter adjustment.
- Scanning plane and probe movement

Move the probe across the body surface.

The arrow in the figure below indicates the movement of the probe (you can move the probe in the opposite direction to the arrow.).



#### Enter/Exit Image Viewing

- To enter image viewing:  
The system enters image viewing when image acquisition is complete.
- Exit  
To return to 3D image acquisition preparation status, press <Update> or <Freeze>.

#### Activate MPR

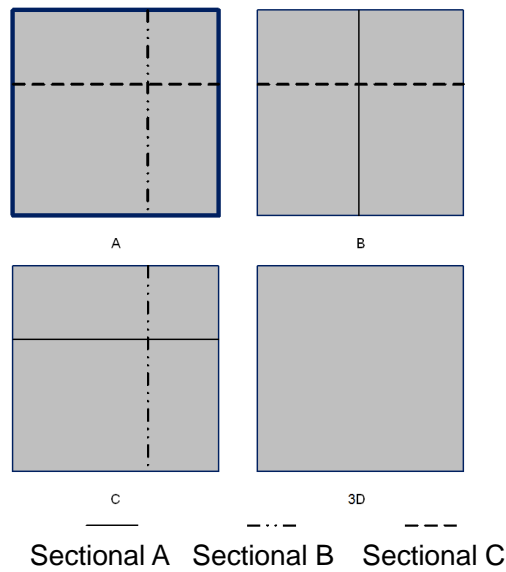
Select [Current Window] to be [A], [B], [C] or [VR] to activate MPR or 3D image (VR).

#### MPR Viewing

In the actual display, different colors for the window box and the section line are used to identify the MPR A, B and C.

- Window A is blue, and the lines (representing MPR A) displayed in the other two windows are also blue.
- Window B is yellow, and the lines (representing MPR B) displayed in the other two windows are also yellow.
- Window C is orange, and the lines (representing MPR C) displayed in the other two windows are also orange.

The positions of the other two MPRs are indicated in the selected plane. You can roll the trackball to change the position.



### Window Display

Press <Dual>/ <Quad> to switch window display.

### Format

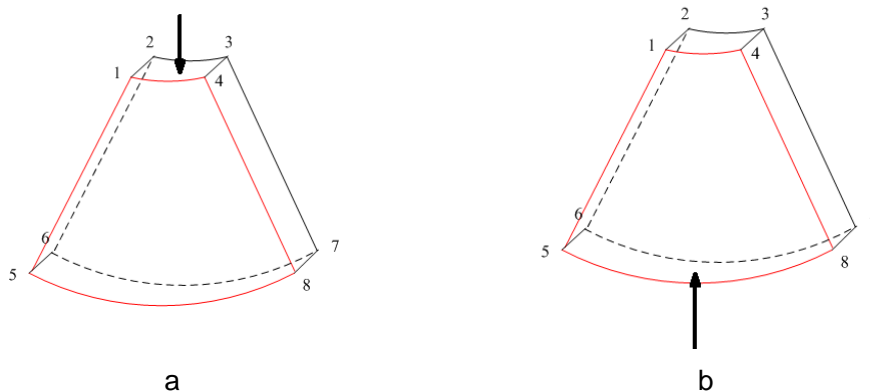
Select [Format]: A4:1, Single, Dual, or Quad.

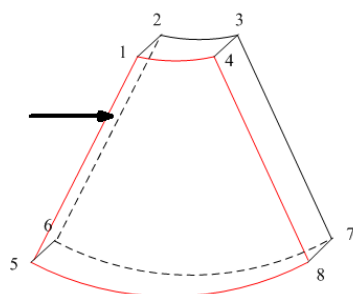
When the Single formate is selected, the system displays the 3D image (VR) only.

### View Direction

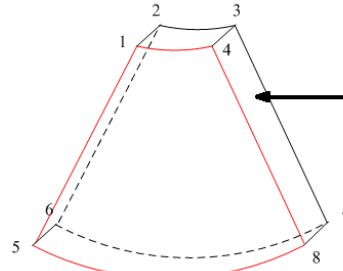
The Region of Interest (ROI), also referred to as the Render Box in rendering, contains the section of the volume you want to render. Therefore, objects that are not inside the box are not included in the render process and are cut out (this is important in surface mode to allow a free line of sight). This may or may not be the entire VOI.

You can adjust the view direction of the ROI.

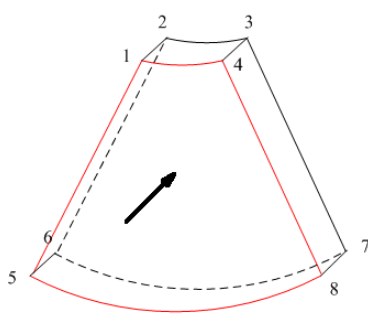




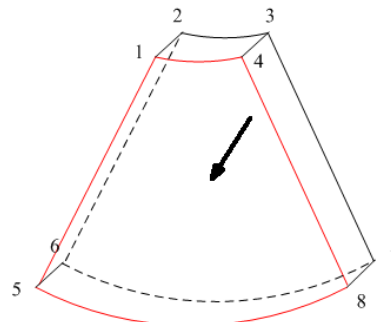
c



d



e



f

View Direction

a. U/D	b. D/U
c. L/R	d. R/L
e. F/B	f. B/F

U: Up

D: Down

L: Left

R: Right

F: Front

B: Back

Select [Direction] to be [U/D], [L/R] or [F/B] on the menu to select the direction of the above Figure a, c and e.

Select [Direction] to be [D/U], [R/L] or [B/F] on the menu to select the direction of the above Figure b, d and f.

### Adjust VOI

#### ■ VOI On

The VR image displays VOI information.

1. In image viewing status, select [VOI] to turn it to "On."
2. Select the desired window by selecting [A], [B] or [C] or [VR].
3. Roll the trackball to adjust the VOI position, size and curved VOI, and press <Set> to switch between the adjusting status.

#### ■ VOI Off

The VR image displays ROI information.

Select [VOI] to turn it to “Off.” The ROI image is displayed on the screen. Roll the trackball to observe the MPR.

■ Accept VOI

1. This function is usually used for MPR observation and to determine the relative position of the MPR to the VR.
2. Select [Accept VOI] to be “Off” on the menu.
3. Select the desired MPR by selecting [Current Window] to be [A], [B] or [C] or [VR].
4. Roll the trackball to view the current active MPR. The other two MPRs change correspondingly.

In Accept VOI status, when the VR is active or the MPR which is perpendicular to the view direction is active, the center point of the VR displays. Adjust the position using the trackball.

### Image Rendering Parameters

In image viewing status, render the image by adjusting the relevant parameters.

Render setting parameters description:

Select [VR/MPR] on the soft menu to select VR or MPR parameter adjustments.

- If [VR] is selected, parameter adjustment is performed on the VR image.
- If [MPR] is selected, parameter adjustment is performed on the MPR.

Adjustable parameters are as follows:

Parameter	Description
Threshold	<p>Function: to set the threshold for VR rendering. The VR is rendered using the signal between the high and low thresholds.</p> <p>When signals are received, from small to large, they are divided into different levels assigned within the range of 0-100%. The threshold is a selected range where the system filters out signals below it and above it to render the VR image.</p> <p>The lower threshold can eliminate lower range noises and echo, which contributes to a clearer and smoother image.</p> <p>Range: 0%-100%.</p> <p>Available in Surface render mode only.</p>
Smooth	<p>Function: to set the smoothness of VR.</p> <p>Selection: 0-10. 0 refers to no smooth effect, 0-10 represent 11 effects in incremental order.</p> <p>Tip: Insufficient smoothness can result in a fuzzy image, while too much smoothness will lead to image distortion.</p>
iClear	<p>Enhances the B mode image profile for better boundary details.</p> <p>Range: Off, 1-4.</p>
Brightness	<p>Function: to set the brightness of VR.</p> <p>Range: 0%-100%. 0% represents the minimum brightness, while 100% represents the maximum.</p>
Contrast	<p>Function: to set the contrast of VR.</p> <p>Range: 0%-100%.</p>
Opacity	<p>Function: to set the transparency value for VR rendering.</p> <p>Range: 0%-100%.</p> <p>The lower the number, the more transparent the grayscale information.</p>

Parameter	Description
Quick Rotation	To quickly rotate the VR. Selection: 0°, 90°, 180°, 270°.
Tint	Switch tint map on/off. Selection: Off, 1-25.

■ Reset Curve

Parameter	Description
Reset Ori.	To reset the volume rotation, shifting and zooming to its original status.
Reset Curve	To reset the curve to its original status.
Reset All	To reset the volume to its original orientation and original parameters.

■ Render Mode

Parameter	Description
Gray/Inversion	Surface Function: set Surface as the VR rendering mode. This is useful for surface imaging, such as fetus face, hand or foot. Tip: you may have to adjust the threshold to obtain a clear body boundary.
	Max. Function: set Max. as the VR rendering mode. Displays the maximum echo intensity in the observation direction. This is useful for viewing bony structures.
	Min. Function: set Min. as the VR rendering mode. Displays the minimum echo intensity in the observation direction. This is useful for viewing vessels and hollow structures.
	X-ray Function: set X-ray as the VR rendering mode. Displays the average value of all gray values in the ROI. X Ray: used for imaging tissues with different internal structures or tissues with tumors.
The above four rendering methods can be applied to both gray and inversion modes. Where inversion means to invert the grayscale of the image, so as to enhance observation for low-echo regions, applicable for vessels, cysts, etc. When the function is turned on, the rendering mode parameters change to the corresponding inverse parameters.	

### Rotate an Image

The system supports the following rotation modes:

■ Auto rotation

- (1) In 3D viewing mode, tap [Auto Rot.] and the system enters the automatic rotation preparation state.
- (2) Select [Direction] to be [Left/Right] or [Up/Down] to set the auto rotation direction.
- (3) Set the Start position and End position:



Start position: roll the trackball to view at a certain position. Press the soft menu control behind [Set Start] function key according to the trackball hint area.

End position: roll the trackball to view at a certain position. Press the trackball "Set End" function key according to the trackball hint area.

**NOTE:** You can view the back of the VR by rotating it 180°. The back view image may not be as vivid as the front. (Here we call the initial view of the VR the "front"). It is recommended to re-capture rather than rotate the VR if a certain desired region is obscured in the VR.

## Image Zooming

To adjust the zoom factor of VR. The sectional images will be zoomed in/out accordingly.

### ■ Operation

Set the VR window as the current window.

- Rotate the <Zoom> knob to increase or decrease the magnification factor.
- Under soft menu mapping mode, zoom the image by pinching the two fingers on the soft menu.

## Sync

This function switches the view direction perpendicular to the current active plane, so as to get a better view of VR.

## Comments and Body Marks

### ■ Function:

Add comments and body marks to the MPR and VR.

### ■ Operation:


The operation is the same as adding comments and body marks in B image mode.

## Image Editing

### ■ Function

Image editing is a more elaborate function than VOI adjusting for optimizing the 3D image by clipping (removing) the obscured part of the region of interest.

Tip:

- In image editing status, no image parameters can be changed. A cutting cursor is displayed , and the system enters "Accept VOI" status.
- The editing function is available only on VR.

### ■ Procedures

1. Enter image editing status by selecting the [Edit] tab.
2. Select an edit/erase tool:
  - Contour
    - a) Press <Set> to position the start point, and roll the trackball to trace the region.
    - b) When the start point and end point coincide, the region is selected, or press <Set> twice to finish tracing.
    - c) Move the cursor to the region you want to cut and press <Set> again to cut.
  - Rectangle
    - a) Press <Set> to fix the rectangle's position, roll the trackball to change the size, and press <Set> again to finish drawing the rectangle
    - b) Move the cursor to the region you want to cut and press <Set> again to cut.

- To undo the last cutting, select [Undo] on the soft menu.
- To undo all cuttings, select [Undo All].

The image cutting parameters are described as follows:

Type	Parameters	Description
Edit Type	Inside/Outside Contour	Allows you to trace the portion of the image you want to cut.
	Inside/Outside Rect.	Displays a box which can be used to define the portion of the image you want to cut.
Other Operations	Undo	To undo the last cut only.
	Undo All	To undo all cuts since you entered image edit mode.

- Section image (MPR) measurement.

2D related measurements can be performed on MPR. For details, see [Advanced Volume].

Measurement is not available in acquisition preparation status.

#### 5.10.3.4 Image Saving and Reviewing in Smart 3D

- Image saving

- In 3D viewing mode, press the single image Save key (Save Image) to save the current image to the animal information management system in the set format and image size.
- Save clip: in 3D viewing mode, press the user-defined Save key (Save Cine (Retrospective)) to save a CIN-format clip to the hard drive.

- Image review

Open an image file to enter the image review mode. In this mode, you can perform the same operations as in VR viewing mode.

## 5.11 iScape

The iScape panoramic imaging feature extends your field of view by piecing together multiple B images into a single, extended B image. Use this feature, for example, to view a complete hand or thyroid.

When scanning, you move the probe linearly and acquire a series of B images, the system pieces these images together into single, extended B image in real time. Besides, the system supports out-and-back image piecing.

After you obtain the extended image, you can rotate it, move it linearly, magnify it, add comments or body marks, or perform measurements on the extended image.

You can perform the iScape panoramic imaging feature on B (power) real time images using all linear, convex, and phased probes.



### **CAUTION:**

**iScape panoramic imaging constructs an extended image from individual image frames. The quality of the resulting image is user-dependent and requires operator skill and additional practice to become fully proficient. Therefore, the measurement results can be inaccurate. Exercise caution when you perform measurements in the iScape mode. Smooth even speed will help produce optimal image results.**

Tips:

- iScape is an optional module.
- The display of the biopsy guideline is not allowed in iScape mode.

### 5.11.1 Basic Procedures for iScape Imaging

To perform iScape imaging:

1. Connect an appropriate iScape-compatible probe. Make sure that there is enough coupling gel along the scan path.
2. Enter iScape:
  - Click the [iScape] item on the image menu or press the user-defined key of iScape on the control panel. (You can preset a user-defined key via [Setup] -> [System Preset] -> [Key Config].)

3. Optimize the B mode image:

In the acquisition preparation status, click the menu title to enter the B mode image optimization. Do measurement or add comment/body mark to the image if necessary.

4. Image acquisition:

Click [iScape] menu title to enter the iScape acquisition preparation status. Click [Start Capture] or press <Update> on the control panel to begin the acquisition. For details, please refer to "5.11.2 Image Acquisition".

The system enters into image viewing status when the acquisition is completed. You can perform operations like parameter adjusting. For details, please refer to "5.11.3 iScape Viewing".

5. Exit iScape:

- Press <Freeze> or <Update> to return to capturing status.

- Press <B> button to return to B mode. **Image Acquisition**

To create an iScape image, you start with an optimized 2D image. The 2D image serves as the mid-line for the resulting iScape image.

1. Press the <Update> key or click [Start Capture] on the image menu to start the iScape image capture.
2. Scan slowly to obtain a single extended field of view image; you can also perform erasing and retracing if the image is not satisfied.
3. End image capture:

To end the image capture:

- Click [Stop Capture] on the image menu; or,
- Press the <Update> key or <Freeze> key; or,
- Wait until the acquisition is finished automatically.

After the acquisition is completed, the panoramic image will be displayed. And the system enters iScape viewing mode.

Tips:

- During the image acquisition, no parameter is adjustable, and functions like measurement, comment and body mark are not available.
- ROI: a green box on the image indicating the boundary between the merged images and the unfinished images.
- Tips about the probe speed: during image slicing, the system gives feedbacks about the probe moving speed in the form of color and words, the relations are listed as follows:

Status	ROI Color	Tips
Speed too low	Blue	Moving speed of the probe is too low.
Appropriate	Green	None.
Speed too high	Red	Moving speed of the probe is too high.

Guidance and precautions for uniform motion:

- Make sure that there is enough coupling gel along the scan path.
- Always move the probe slowly and steadily. Best results are achieved by moving the probe with 1cm/s - 3cm/s).
- Continuous contact is required throughout the length of the extended image. Don't lift the probe from the skin surface.
- Always keep the probe perpendicular to the skin surface. Don't rock, rotate or tilt the probe during the scan.
- The system accommodates a reasonable range of motion velocity. Don't make abrupt changes in speed of motion.
- Deeper scans generally require reduced acquisition speed.

### 5.11.3 iScape Viewing

After completing the image acquisition, the system performs image splicing and then enters the iScape viewing mode.

In iScape viewing mode, you can perform the following functions:

- Image parameters setting, for details, please refer to “5.11.3.1 Image Parameters ”.
- Image zooming, for details, please refer to “5.11.3.2 Image Zooming”.
- Image rotation, for details, please refer to “5.11.3.3 Rotating the Image”.
- Measurement, comment, and body mark, for details, please refer to “5.11.3.4 Measurement, Comment, and Body Mark”.

### 5.11.3.1 Image Parameters Adjusting

In image viewing mode, you can adjust the following parameters:

- Image size
  - Click [Actual Size] to display the image in its actual size.
  - Click [Fit Size] to display the image in an appropriate size according to the current window. Also this is the system default format.
- Tint map
  - Click the [Tint Map] on the menu to adjust it.
- Ruler
  - Click [Ruler] on the menu to hide or show the ruler around the image.

### 5.11.3.2 Image Zooming

Press <Depth/Zoom> knob on the control panel to enter image zooming mode. Rotate the knob to zoom in/out the panoramic image.

- Rotate clockwise to zoom in the image.
- Rotate anticlockwise to zoom out the image.
- Roll the trackball to change position of the magnified image.
- Press the <Depth/Zoom> knob again to exit the zoom mode.
- When image displayed is bigger than the image area, the thumbnail is automatically displayed.

### 5.11.3.3 Rotating the Image

For the convenience of viewing the image, you can rotate the image by clicking [Rotation] on the image menu.

### 5.11.3.4 Measurement, Comment, and Body Mark

In iScape image viewing status, you can perform measurement, comment, and body mark. The operations are the same as that of B mode.

- NOTE:**
1. The measurement accuracy for the spliced image may be degraded, exercise caution when measurements are performed on an iScape image.
  2. If there is a trace during the retracing, please don't perform measurement across the trace.

### 5.11.3.5 Evaluate Image Quality

Many variables may affect the overall image quality. It is important to evaluate the image content and quality before an image is used for diagnosis or measurements.

- NOTE:** iScape panoramic imaging is intended for well-trained ultrasound operators or physicians. The operator must recognize image artifacts that will produce a sub-optimal or unreliable image.

The following artifacts may produce a sub-optimal image. If the image quality cannot meet the following criteria, you shall delete the image and do image acquisition again.

- The image must be continuous (no part of an image moves suddenly or disappears.)
- No shadow or absent signal along the scan plane.
- Clear profile of anatomy through the entire scan plane without distortion.
- Skin line is continuous.
- The images are captured from the same plane.
- There is no large black area in the image.

### 5.11.4 Cine Review

Click [Review Cine] on the image menu in panoramic image viewing status to enter cine reviewing mode. In cine reviewing mode, there is a green frame marker indicating the sequence of currently reviewed image in the panoramic image on the left side of screen.

In cine review status:

- Roll the trackball to review the captured images frame by frame.
- Click [Auto Play] to start or end auto play.
- In auto play mode, click [Auto Play] on the image menu; or, press/rotate the corresponding knob to change the play speed. When the speed is 0, the system exits auto play mode.
- Review to a certain image; click [Set First Frame] to set the start point. Review to another image; click [Set End Frame] to set the end point. In auto play mode, the review region is confined to the set start point and end point.
- Click [Return] item on the image menu to exit the cine review mode, and there displays the panoramic image.
- In cine review mode, press <Freeze> on the control panel to return to the acquisition preparation status.

# 6 Display & Cine Review

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## 6.1 Image Display

### 6.1.1 Splitting Display

The system supports dual-split (B/B) and quad-split (4B) display format. However, only one window is active.

- Dual-split: press <Dual> key on the control panel to enter the dual-split mode, and using <Dual> key to switch between the two images; press <B> on the control panel to exit.
- Quad-split: press <Quad> key on the control panel to enter the quad-split mode, and using <Quad> key to switch between the two images; press <B> on the control panel to exit.

### 6.1.2 Image Magnification

**NOTE:** Zooming an image changes the frame rate which tends to change thermal indices. The position of the focal zones may also change which may cause the peak intensity to occur at a different location in the acoustic field. As a result, the MI may change.

#### 6.1.2.1 Spot Zoom

Procedures:

1. Enter zoom:  
In real-time image scanning, press <Depth/Zoom> knob on the control panel to light the Zoom indicator.
2. Adjust ROI:  
Roll the trackball to change the box size and position, press <Set> to toggle between setting the size and position. And after sample volume is set, press <Zoom> key again to enter spot zoom status.
3. Exit:  
In spot zooming status, press <Depth/Zoom> again.

Note:

- Spot zooming only can be realized on a scanning image.
- The size and position of sample volume box will be changed along with scanning depth and area.

### 6.1.2.2 Pan Zoom

Procedures:

1. Enter Zoom:  
Freeze the image, press <Depth/Zoom> knob on the control panel to light the Zoom indicator. Image-in-image is displayed.
2. Rotate <Depth/Zoom> knob to change the magnification factor among 0.8-10.
3. Exit:
  - Press <Depth/Zoom>.
  - Unfreeze the image, the system exit pan zooming status automatically.

### 6.1.2.3 iZoom (Full-screen Zooming)

Function: to magnify the image in full screen.

According to the region to be zoomed, the system supports two types of full-screen zooming:

- Zoom in the standard area to full-screen, including image area, parameter area, image banner, thumbnail area and so on.
- Zoom in the image area only to full-screen.

■ Procedures:

1. Set the User-defined key:
  - (1) Press <Setup> to enter [Setup] -> [System Preset] -> [Key Config].
  - (2) Select a function-free key in the function list.
  - (3) Select "iZoom" in the "Other" page.
  - (4) Click [Save] to complete the setting.
2. Open the image (or the under scanning image), press the user-defined iZoom key once to zoom in the standard image area; and then press the key again to zoom in the image area only.
3. Press the user-defined key again to return to normal status.

■ The iZoom status supports:

- Measurements, adding comments and body marks.
- Video output, saving image and printing the current area that is zoomed in.
- Exiting the zooming status by pressing <Probe>, <Patient>, <iStation>, <Review> or <Setup>.

### 6.1.3 Freeze/ Unfreeze the Image

Press <Freeze> on the control panel to freeze a scanning image. In freeze mode, the probe stops transmitting acoustic power, and all images as well as the parameters are kept still.

Tip: after freezing an image, the system may enter cine review, measure, comment adding, or body mark mode, which is dependent upon preset. (Setting path: [Setup]→[System Preset]→[Image Preset]→"Freeze Config")

Press <Freeze> in freeze mode to unfreeze the image, the system continues image scanning.

#### 6.1.3.1 Imaging Mode Switching When Frozen

Imaging mode switching in freeze mode follows the following principles:



- In splitting display B mode, press <B> to exit splitting display mode and display the image of the currently activated window in full screen.
- In freeze mode, the system supports imaging mode switching between the sub-modes (only for the activated window).
- The imaging mode and parameters of an unfrozen image is the same as the corresponding one that before frozen; but the display format is the same as the one before unfrozen.

### 6.1.3.2 Imaging Display Format Switching When Frozen


Image display format switching in freezing mode follows the following principles:

- 2D + M (Press <Freeze> in 2D + M scanning mode)
  - If the imaging mode before frozen is 2D (frozen) +M (real time) or 2D (real time) +M (frozen), then in freeze mode, you can switch between 2D(real time)+M(real time) or 2D(frozen)+M(real time)) by pressing <Update> key on the control panel.
- Dual/quad splitting display mode (Press <Freeze> key in dual/quad splitting display mode)
  - When enters freeze mode, the default activated window is the real-time window before frozen. Other image windows display the corresponding cine memories, if a certain cine memory is empty, then no image is displayed.
  - Press <Dual> or <Quad> to switch between dual-splitting and quad-splitting modes.
  - Press <B> button on the control panel to enter the single display format, which displays the currently activated window. In single display format, press <Dual> or <Quad> to switch between dual-splitting and quad-splitting mode.
  - Unfrozen: in splitting display status, when you unfreeze the image you can only unfreeze the image in the activated window, other images still keep frozen. In single-window display status, the system displays single image after being unfrozen.

## 6.2 Cine Review

After you press the [Freeze] key, the system allows you to review and edit the images prior to the image frozen. This function is called as cine review. The magnified images can also be reviewed after <Freeze> is pressed, and the operating method is the same. You can perform post process operations, measurements, adding comments and body marks on the images being reviewed.

The system supports manual review as well as automatic review. The default mode is Manual Cine, but you can switch between Auto Cine and Manual Cine.

 <b>CAUTION:</b>	<ol style="list-style-type: none"> <li>1. Cine Review images can be inadvertently combined in-between separate animal scans. The cine memory must be cleared at the end of the current animal and the onset of the next new animal by selecting the &lt;End Exam&gt; key on the control panel.</li> <li>2. Cine files stored in the system's hard drive shall contain animal information, to avoid the selection of an incorrect image file and potential misdiagnosis.</li> </ol>
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## 6.2.1 Entering/ Exiting Cine Review

- To enter cine review:
  - Enter "[Setup]-> [System Preset]-> [Image Preset]-> "Freeze Config", to set "Status after Freeze" to be "Cine". Then the system enters the manual cine review status once press <Freeze> to freeze the image.
  - Open cine files in thumbnail, iStation or Review, the system enters automatic cine review status.
- To exit cine review:
  - Press <Freeze> key again, the system will return to image scanning and exit cine review.
  - Press <Cine> or <Esc>, the images are still frozen but the system exits cine review.

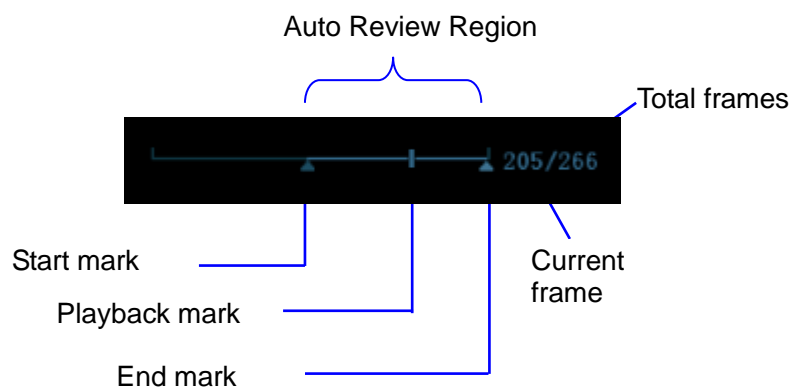
## 6.2.2 Cine Review in 2D Mode

### ■ Manual cine review

After entering the cine review of 2D mode, rolling the trackball or rotating the multifunctional knob will display the cine images on the screen one by one.

If you roll the trackball to the left, the review sequence is reversed to the image-storing sequence, thus the images are displayed in descending order. Whereas, if you roll the trackball to the right, the review sequence is the same as the image-storing sequence, thus the images are displayed in ascending order. When the reviewing image reaches the first or the last frame, further rolling the trackball will display the last or first frame.

The cine progress bar at the bottom of the screen (as shown in the figure below):



### ■ Auto Review

- Reviewing all
  - a) In the manual cine review status, click [Auto Play] on the image menu to activate auto cine review.
  - b) Reviewing speed: In the auto cine review status, use [Auto Play] item in the image menu to adjust the review speed.
  - c) In auto play status, set [Auto Play] item to Stop to exit auto play.
- Setting Region of Auto Review
  - a) Set start frame: move the playback mark to the desired frame, and click [Set First Frame] in the image menu to set the frame as start point.

- b) Set end frame: move the playback mark to the desired frame, and click [Set End Frame] in the image menu to set the frame as end point.
- c) Click [Auto Play] in the image menu; the system plays the auto review region automatically.
- d) Rotate the knob on the left of the control panel to increase/decrease the auto play speed.
- e) In the auto cine review, setting [Auto Play] to Stop or rolling the trackball will stop the auto cine review and enter the manual cine review.
- f) Click [Skip to First]/ [Skip to Last] to review the first or last frame.

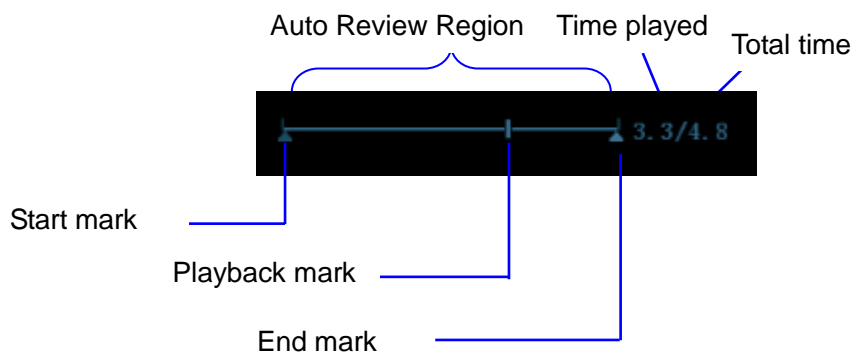
Tips: you can perform cine review on each image window in the dual/ quad splitting mode, and set auto review region for each window.

### 6.2.3 Cine Review in M/PW Mode

After entering the cine review of M/PW mode, rolling the trackball or rotating the multifunctional knob will display the cine images on the screen one by one.

Roll the trackball to the left, the review progress slider moves to the left, the images moves to the right, and the earlier stored images are invoked. Whereas, roll the trackball to the right, the review progress slider moves to the right, and the images move to the left, the recently stored images are invoked. When you review the images until the earliest or the latest frame, further rolling the trackball will display the last or first frame.


The cine progress bar at the bottom of the screen (as shown in the figure below):



Cine review operations are the same as those of 2D mode.

### 6.2.4 Linked Cine Review

The linked cine review refers to review of the images captured at the same moment.

There displays the frame mark  on the time mark of M image indicating the current 2D image.

In dual or quad split display mode, you can only review images of the current active window, use <Dual> or <Quad> to switch the window.

## 6.3 Image Compare

### 6.3.1 Image Compare in Review Mode

1. Press <Review> to enter Review screen, press <Ctrl>+<Set> to select files to be compared.  
Tip: for B/ B+Color/ B+Power mode image, you can select at most 4 images; for PW/M mode image, you can select at most 2 images.
2. Click [Compare] to enter image compare mode.
3. Review the images of different image windows (cine replaying can't be performed for single-frame image file), press <Dual> or <Quad> key to switch the active image window.  
The window with the highlighted "M" mark is the current activated window.  
Press <Cursor> and double click the image in the thumbnail area at the bottom of the screen to change the current active window
4. Save the image if it is necessary.
5. Click [Return] on the screen or press <Freeze> to exit image compare.  
Image compare of different exams for the same patient:
  - a) Select different exams in iStation screen, select [Review] in the popped up menu to enter Review screen.
  - b) In Review screen, click [History] to select the exam; click to select the image to be compared in different exams, and click [Image Compare].

### 6.3.2 Frame Compare

1. Freeze the image in B/C mode, click [Frame Compare] in "Cine" page on the image menu to enter frame compare mode.
2. Review the images of different image windows (cine replaying can't be performed for single-frame image file), press <Update> or the user-defined <Dual> key to switch the active image window.
3. Save the image if it is necessary.  
Measurements, adding comments and body marks are allowed.
4. Click [Frame Compare] again to return to image frozen status; press <Freeze> to enter real-time imaging.

Tips: cine compare can only be performed on single-format 2D images only.

## 6.4 Cine Memory

### 6.4.1 Cine Memory Setting

There are 2 ways of cine memory split: auto and split.

Setting path: select "Auto" or "Split" for cine memory in [Preset]→ [System Preset]→ [Image Preset].

Where,

- "Auto" for the cine memory indicates the system splits the cine memory as per the number of B image windows.
- "Split" indicates the system always splits the cine memory, even if in the single-B window, the system splits the cine memory into two as well. You can press <B> key to switch and display the images in either memory, so you can compare images in Split mode.

The memory capacity is evenly distributed as per splitting number, as shown in the following table (Taking B images in low density as an example, the capacity of B cine memory is N frames):

Imaging Mode Split	Single-B/Color	Dual	Quad
Auto	One memory, with capacity N frames.	The memory splits into two, with capacity N/2 frames each	The memory splits into four, with capacity N/4 frames each
Split	The memory splits into two, with capacity N/2 frames each	The memory splits into two, with capacity N/2 frames each	The memory splits into four, with capacity N/4 frames each

## 6.4.2 Cine Memory Clear



In the following conditions, the cine review memory will be cleared:

- Start an exam of a new animal.
- Start a new exam for the same animal.
- Switching the probe (if the cine memory is split, only the cine memory corresponding to the currently activated window is cleared)
- Changing the exam condition (if the cine memory is split, only the cine memory corresponding to the currently activated window is cleared)
- Imaging Mode Switching: include imaging mode switching among B, M, display mode switching etc.
- Parameters modification, including:
  - Parameters that can result in imaging region or direction changing, such as depth, FOV, trapezoid, steer, zoom and so on.
  - Parameters that can result in image frame changing, such as line density, focus number and so on.
  - Change speed in M mode
  - 2D image cleared
- Unfreeze the image: after the image is unfrozen, images stored in the cine memory will be cleared, but if the cine memory is split, only the currently cine memory corresponding to the activated window will be cleared.
- Open/ close the image file that occupies cine memory.

## 6.5 Image Compare

You can perform image compare through the path:

- iStation screen (press <iStation> to enter);

- Review screen (press <Review> to enter).
1. In the above condition, press <Cursor> to show the cursor and click the target image file.
  2. 3 buttons will appear to the right of the image, click  to select the image for comparison marked by a .

If the wrong image has been chosen, click  to cancel the selection of this image.

Tip: for B mode image, you can select at most 4 images; for M single mode image, you can select at most 2 images.

3. Repeat the above steps to add other image files for comparison.
4. Click [Compare] to enter image compare mode.
5. Review images from different image windows. Press the <Dual> or <Quad> key to switch the active image window.

The window with the highlighted “M” mark is the currently activated window.

6. Save the image if necessary.
7. Click [Return] on the screen or press <Freeze> to exit image compare.

Image compare of different exams for the same animal:

- c) Select different exams in the iStation screen, then select [Review Image] in the menu which appears to enter the Review screen.

In the Review screen, click [Exam History] to select the exam. Click to select the image to be compared in different exams, and click [Compare].

## 6.6 Preset

Open [Setup] → [System Preset] → [General] to preset the cine storage length.



Clip length: 1~60s.

# 7 Measurement

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There are general measurement and application measurement. You can perform measurements on a zoomed image, cine reviewing image, real-time image, or a frozen image. For measurements details, please refer to the [Advanced Volume].



## **WARNING:**

**Be sure to measure areas of interest from the most optimal image plane to avoid misdiagnosis from inaccurate measurement values.**



## **CAUTION:**

- 1. If an image is unfrozen or the mode is changed during a measurement, the calipers and measurement data will be cleared from the screen. The general measurement data will be lost (the application measurement data are stored in the report).**
- 2. If the system is turned off or <End Exam> is pressed during a measurement, the data not saved will be lost.**
- 3. In Dual-B imaging mode, the measurement results of the merged image may be inaccurate. Therefore, the results are provided for reference only, not for confirming a diagnosis.**

## 7.1 Basic operations

### ■ Entering/Exiting Measurement

Enter: on the control panel, press the <Caliper> to enter general measurement; press <Measure> key to enter application measurement.

Press <Caliper> or <Measure> key again to exit.

### ■ Measurement result and help information

The system displays and updates measurement results in the result window.

The help information concerning measurement and calculation is displayed in the Help Information area at the bottom of the screen.

## 7.2 General Measurements

### 7.2.1 2D General Measurements

2D general measurements refer to general measurements on 2D mode:

Measurement Tools	Function
Distance	Measures the distance between two points of interest.
Depth	The distance between probe surface and the probing point along ultrasound beam.
Angle	The angle between two intersected planes.
Area	Measures the area and perimeter of a closed region.
Volume	The volume of a target.
Cross Line	The length of two line segments, which are perpendicular to each other.
Parallel Line	The distance between each pair of parallel lines in a sequence.
Trace Length (Trace)	Measures the length of a curve on the image.
Trace Len (Spline)	Measures the length of a curve on the image.
Double Dist	Measures the length of two line segments, which are perpendicular to each other.
Distance Ratio	Measures the lengths of any two line segments and the calculated ratio.
Area Ratio	The areas of any two regions and the calculated ratio.
B histogram	The grayscale distribution of ultrasonic echo signals in a closed region.
B profile	The grayscale distribution of ultrasonic echo signals across a line.
Color Velocity	Color flow velocity (only valid for Color mode).
Volume Flow	Blood flow through some vascular cross section per unit time.
IMT	Measures the distance between LI (Lumen-Intima) and MA (Media-Adventia) NOTE: The IMT function is unavailable on the product not configured with IMT.

### 7.2.2 M General Measurements

M general measurements refer to general measurements on M mode. The measurements listed below can be performed:

Measurement Tools	Function
Distance	The vertical distance between two points.
Time	The time interval between any two points.



Measurement Tools	Function
Slope	Measures the distance and time between two points and calculates the slope.
HR	Measures the time of n (n≤8) cardiac cycles and calculates the heart rate in M mode image.
Velocity	Calculates the average velocity by measuring the distance and time between two points.

### 7.2.3 Doppler General Measurements

Doppler general measurements refer to general measurements on PW mode images. The measurements listed below can be performed:

Measurement Tools	Function
Time	The time interval between any two points.
HR	N intervals (n≤8) are measured to calculate a PW mode derived HR value in Beats Per Minute (BPM).
D Velocity	On the Doppler mode image, velocity and PG (pressure gradient) of a point on the Doppler spectrum waveform are measured.
Acceleration	Velocity and time interval between two points are measured to calculate speed difference and acceleration.
D Trace	On the PW mode image, one or several Doppler waveforms are traced to obtain speed and PG, etc.
PS/ED	Velocity and PG between two peaks on the Doppler spectrum to calculate RI (resistance index) and PS/ED (peak systolic/end diastolic).
Volume Flow	Blood flow through some vascular cross section per unit time.

## 7.3 Application Measurement

The system support following measurement types:

- Abdomen measurements - Used for measurements of abdominal organs (liver, gall bladder, pancreas and kidney, etc.) and large abdominal vessels.
- Reproduction measurements- Used for measurements of animal growth indice.
- Cardiac measurements- Used for left ventricle function measurements and measurements of main artery and vein parameters, etc.
- Small Part measurements – Used for small parts such as thyroid.
- Vascular measurements – Used for vessels measurements.

## 7.4 Measurement Accuracy

Table 1 Error of 2D Images

Parameter	Value Range	Error
Distance	Full screen	Within $\pm 3\%$ ; or when the measured value is less than 40 mm, the error is less than 1.5 mm.
Area (Trace)	Full screen	Within $\pm 7\%$ ; or when the measured value is less than 16 cm <sup>2</sup> , the error is less than 1.2 cm <sup>2</sup> .
Area (ellipse, circle)	Full screen	Within $\pm 7\%$ ; or when the measured value is less than 16 cm <sup>2</sup> , the error is less than 1.2 cm <sup>2</sup> .
Angle	Full screen	Within $\pm 3\%$ .
Circumference	Full screen	Within $\pm 10\%$ .
Distance (iScope)	Full screen	Micro-convex probe: within $\pm 15\%$ Other probe: within $\pm 10\%$

Table 2 Volume Measurements

Parameter	Value Range	Error
Volume	Full screen	Within $\pm 10\%$ ; or when the measured value is less than 64 cm <sup>3</sup> , the error is less than 6.4 cm <sup>3</sup> .

Table 3 Time/Motion Measurements

Parameter	Value Range	Error
Distance	Full screen	Within $\pm 3\%$ ; or when the measured value is less than 40mm, the error is less than 1.5mm.
Time	Timeline Display	Within $\pm 2\%$ .
Heart rate	Timeline Display	Within $\pm 4\%$ .
PW velocity	10 cm/s ~200cm/s	When the correction angle is $\leq 60^\circ$ , the PW velocity $\leq \pm 10\%$ .

**NOTE:** Within the selected field range, the measurement accuracy is ensured within the range mentioned above. The accuracy specifications are performance in the worst conditions, or based on the real test for the system, regardless of acoustic speed error.

# 8 Comments and Body

## Marks

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### 8.1 Comments

Comments can be added to an ultrasound image to bring attention, notate or communicate information observed during the examination. You can add comments to: zoomed image, cine review image, real-time image, frozen image. You can type the character as comments; insert the pre-defined comments from the comment library; or insert arrow markers.

 **WARNING:** You must ensure that the entered comments are correct. Incorrect comments may cause misdiagnosis!

#### 8.1.1 Comment Basic Procedures

1. To enter comment status:
  - Press the [Comment] key to enter the comment status, and the cursor becomes “[].
  - Press any alphanumeric key, and the corresponding letter or numeral is displayed besides the cursor.
  - Press the <Arrow> key to enter the arrow-adding status.

Tips: when the system entered comment status, the default characters entered are uppercase. You can see the <Caps Lock> indicator lights on.

2. Place the cursor to the desired place to set the comment location. Add new comment to the image according to actual situation. Here, you can modify, move, delete, hide or display the completed comments.
3. To exit comment status:
  - In the comment status, press <Comment> key.
  - Or press <ESC> or other operating mode keys, such as [Caliper], [Measure] etc.
  - In the arrow-adding status, press the <Arrow> key.

#### 8.1.2 Comment Menu

You can adjust relevant settings in comment status via menu.

##### ■ Home of comments

Assign the user-defined key for the set home function in “[Setup] → [System Preset] → [Key Config]”.

Move the cursor to the desired location for a comment and press the Set-Home user-defined key. The current position of the cursor is set to be the default position of the comment adding. When pressing Home user-defined key, the cursor will turn to the default setting position.

#### ■ Change Font Size/Arrow Size

- Click [Font Size] to change the font size of comment: Small, Mid, Big.
- Click [Arrow Size] to change the arrow size of comment: Small, Mid, Big.

The default is the comment text library in the current exam mode. When entered the comment status, the system displays the customized comment text library for the current exam. If there is no customized comment text library for the current exam, it will display the comment text libraries of all the exam modes assigned for the current probe. And if no text library for all the exam modes is customized, no comment text will be displayed.

Please refer to “11.5 Comment Preset” for comment preset for the specific exam mode.

#### ■ ABC Display

Click [ABC Display] to display or hide the added comments. Assign the user-defined key for the function in “[Setup]-> [System Preset]->“Key Config” ”.

#### ■ Set comment language

Click [English] to turn on or off the English comments. If “English” is turned on, the comments will display in English; if turn off, the comments will display in the language you set.

If the current language is English, this selection is not available.

#### ■ Custom

Click [Custom] to display the dialog box containing all comments in current menu, you can edit the comment.

## 8.1.3 Adding Comments

The system can be configured with comment text libraries including Abdomen, Cardiology, GYN (Gynecology), OB (Obstetrics), Urology, SMP (Small Part), Vascular, PED (Pediatric) and Nerve Blocks.

#### ■ Typing comment characters

1. To set the comment location:

Roll the trackball or press direction-control keys on the keyboard to move the cursor to the desired location for comments.

2. To type the alphanumeric characters:

- Type the alphanumeric characters through the qwerty (The default characters are uppercase);
- To type the upper characters, press [Shift] and the character key at the same time.

3. Move to a new line:

In the edit status (the characters are in green color), press <Enter> to move the cursor to the new line, and the location of the cursor is aligned with that of the first line.

4. In the edit status, move the trackball or press the multifunctional knob to confirm the character added, and the color of the character added turns yellow.

#### ■ Adding a Comment Text

Move the cursor onto the desired comment text in the menu and press <Set> or the multifunctional knob, and then the system adds the selected comment text on the set location. The added comment text is in the edit status, so you can edit the comment text added.

- Add combined comment: Press <Menu> or the multifunctional knob to show the menu; rotate the knob to view the comments one by one; press the knob again to add the selected item onto the image (comment added in an editable state); rotate the multifunctional knob to search for the next part, and press the knob again to add the

second part of the combined comment. Repeat procedures to add other parts of a combined comment. Press <Set> to complete the comment.

#### ■ Adding an Arrow

You can add an arrow to a location where you want to pay attention.



1. Press the <Arrow> key, and an arrow will appear at the default position.
2. Adjust the arrow
  - Adjust the position and orientation of the arrow: roll the trackball to the desired position and use the multifunctional knob to change the orientation in 15° increments.
  - Click [Arrow Size] on the menu to change the arrow size:
3. Press <Set> or <Enter> to anchor the arrow position, and then the arrow turns yellow.
4. Repeat the above steps to add more arrows.
5. Press <Arrow> key, <ESC> or to exit the arrow comment status.

### 8.1.4 Moving Comments


1. Move the cursor onto the comment that needs to be moved. Press <Set> to select it, where a highlighted box appears around the comment.
2. Roll the trackball to move the comment to the new position.
3. Press the <Set> key to anchor the comment in the new position, and the comment-moving operation is complete.

### 8.1.5 Editing Comments

#### ■ Modifying (Editing) characters

1. Move the cursor onto the comment that needs to be modified.
  - Directly enter the character at the position that the cursor stays; or,
  - Double press the <Set> key to enter the edit status, use the  or  key to move the cursor to a location where needs to insert characters, and type characters.
2. Press the <Del> key to delete the comment character or text on the right side of the cursor; Press the <Backspace> key to delete the comment character or text on the left side of the cursor.
3. Roll the trackball or press the <Set> key or the multifunctional knob to confirm the modification and to exit the edit status, and the color of the comments turns yellow.

#### ■ Modifying (Editing) Arrows

1. Move the cursor on the arrow that needs to be modified. After the cursor turns to , press the <Set> key. The color of the current arrow turns green, and there is green frame around the arrow, indicating the arrow can be edited. Move the cursor to change the arrow position.
2. Rotate the multifunctional knob to modify the arrow direction.
3. Press the <Set> or <Enter> key to complete the modifying operation.

## 8.1.6 Deleting Comments

### ■ Deleting Comment Characters, Texts or Arrows

1. Move the cursor to the comment to be deleted.
2. Press the <Set> key to select the comment.
3. Press the <Del> or <Clear> key to complete the deleting operation.

### ■ Deleting a recently-added character, text or arrow

After you add several comments and the cursor is in the “|” or “↖” status, pressing <Clear> can delete the recently-added or recently-edited comment.

### ■ Erase All Text

Long press the <Clear> to delete all the comments.

- NOTE:**
1. When no object is selected, pressing the <Clear> key will clear all comments and all measurements calipers.
  2. After powering off, the system will clear all comments on the image.

## 8.2 Body Mark

The Body Mark (Pictogram) feature is used for indicating the exam position of the animal and transducer position and orientation.

The system supports body marks for Dog, Cat, Equine, Bovine, Ovine or Other. You can preset the system configured general body marks for each exam mode, also, you can customize the body mark. For details, please refer to “11.4 Body Mark Preset”.

### 8.2.1 Body Mark Operation Procedures

To add the first body mark:

1. Press <Body Mark> to enter the body mark status.
2. Select the body mark, adjust the position and direction of the probe icon.
3. Exit body mark mode :
  - Press the <Set> key to confirm the position and orientation of the probe marker and exit the body mark mode.
  - Press [Body Mark] again on the control panel.
  - Press the [Esc] key to confirm the current operation and exit the body mark status.

### 8.2.2 Menu

In the body mark menu, you can:

#### ■ Select Bodymark library

Move the cursor to menu title, and select the desired library.

#### ■ Custom

Click [Custom] to load the body mark pictures.

You can import a user-defined body mark of PNG and BMP (24/ 32/ 256 bit) image of 75\*75 pixels.

## 8.2.3 Adding Body Marks

- To add the first body mark:


- (1) Enter body mark mode.
- (2) Select the bodymark library through the menu title.
- (3) Select the bodymark.

Move the cursor onto the desired bodymark to highlight your choice, and press <Set> to add the selected bodymark; or rotate the multifunctional knob to view the bodymarks.

- (4) Press <Set> to confirm the selection.
- (5) To adjust the probe position and orientation marker:
  - Roll the trackball to place the probe marker at the correct position.
  - Rotate the multifunctional knob to adjust the orientation.
  - Press the <Set> key to confirm the position and orientation of the probe marker and exit the body mark mode.

## 8.2.4 Moving Body Marks

You can move the body mark graphic to any desired position within the image area.

1. Roll the trackball to move the cursor onto the body mark. The cursor changes into , indicating you can move the pictogram to a new position.
2. Press <Set> key to select the body mark, and a frame will appear around the graphics.
3. Roll the trackball to move the Body Mark graphic to the desired position.
4. Press <Set> to anchor and confirm the new graphics position.

**NOTE:** In Dual B Mode, a body mark cannot be moved between the separated image windows.

## 8.2.5 Deleting Body Marks

- To delete a body mark

1. Use the trackball to position the cursor on the body mark graphic and Press <Set> to select.
2. Press <Clear> to delete the selected body mark.

**NOTE:** In the Body Mark mode, if no object is selected, pressing the [Clear] key will clear all comments, body marks and general measurements from the screen.

Tips:

- Powering off, preset returning, switching the exam/ animal/ mode/ probe will clear the body marks.





# 9 Animal Data Management

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An exam record consists of all information and data of one exam.

An exam record consists of the following information:

- Animal basic information and exam data
- Image files
- Report

**NOTE:**

1. DO NOT use the internal hard drive for long-term image storage. Daily backup is recommended. External storage media is recommended for image archive.
2. The system animal database space is limited, please back up or clear animal data in time.
3. Mindray is not responsible for lost data if you DO NOT follow suggested backup procedures.

## 9.1 Animal Information Management

### 9.1.1 Enter Animal Information

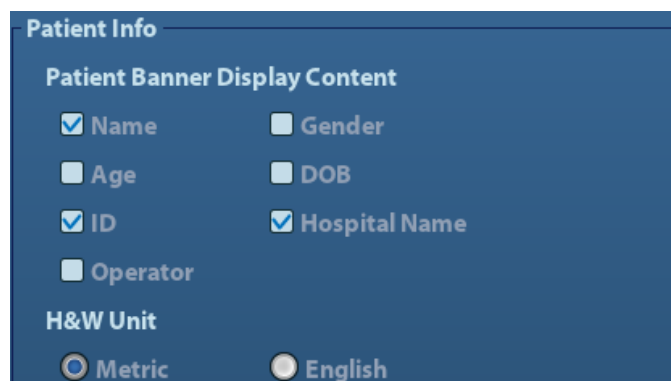
The general animal information and exam information are entered through the Animal Info screen, for details, please refer to “4.2 Animal ”.

After completion of animal information entry, click [OK] to save the animal information to the animal data.

### 9.1.2 Animal Information Setting

Open “[Setup] → [System Preset] → [General]”, and then set the following in the Animal Info area. Here, you can select if to display animal gender, age or operator in the screen; set the H&W applied unit and select the using surface formula.

- Animal information display
- H&W Unit



Patient Info

Patient Banner Display Content

Name  Gender

Age  DOB

ID  Hospital Name

Operator

H&W Unit

Metric  English

## 9.2 Image File Management

You can store the image files either in the animal database in the system, or to external memory devices. For a save image, you can perform operations like image reviewing, analyzing and demonstration (iVision).

### 9.2.1 Storage Media

System supported memory media including:

- System hard disk
- USB memory devices: USB flash drive, removable USB hard disk
- DVD±RW, CD-R/W

### 9.2.2 Image File Formats

The system supports two types of image file formats: system-relevant and PC-compatible.

#### ■ System-relevant formats:

- Single-frame image file (FRM)  
Refers to single-frame static image files not to be compressed; you can perform measurements and comments adding on this type of files.
- Cine file (CIN)  
System-defined multi-frame file format; you can perform manual or auto cine review, and perform measurements or add comments for the reviewed images. After you open a stored CIN file, the system automatically enters cine review status.

The system can save FRM files as BMP, JPG, TIFF or DCM files, or save CIN files as AVI, DCM files. The system can also open FRM, JPG, BMP and CIN files.

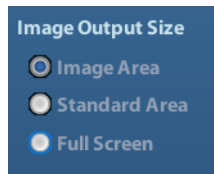
#### ■ PC-compatible formats:

- Screen file (BMP)  
Single-frame file format, used to save the current screen, non-compressed format;
- Screen file (JPG)  
Single-frame file format, used to save the current screen in the compressed format; you can set the compression ratio.
- TIFF: Single-frame export format
- Multi-medium files (AVI)  
Multi-frame file format, general cine file format.
- DICOM files (DCM)  
DICOM standard files format, single-frame or multi-frame format, used to record animal information and images.

### 9.2.3 Image Storage Preset

#### ■ Set image size

You can set the image size via [Setup] → [System Preset] → [General]. The items are shown as follows:



■ Set single frame export format

- Format

You can select the image export format in the Send To dialogue box.

**NOTE:** Compression in a JPEG format may result in image distortion.

■ Set cine saving length

For details, please refer to “6.6 Preset”.

## 9.2.4 Saving Images to the System

■ To save a single-frame image in the system:

- (1) Enter [Setup]-> [System Preset] -> [Key Config]-> [Output], set a user-defined key for function “Save image”.
- (2) Press the user-defined key to save the image.
  - In the image screen, press the shortcut key to save the current single-frame image with the image frozen, and the image is saved with the default filename in the default file directory in the .FRM format. The thumbnail of this image will appear in the thumbnail area on the right side of the screen. When you move the cursor onto the thumbnail, its filename with suffix will be displayed.
  - When a dialog box is displayed on the current screen, press the user-defined key to save the screen in the BMP format.

■ To save cineloop image in the system:

- (1) Enter [Setup]-> [System Preset] -> [Key Config]-> [Output], set a user-defined key for function “Save cine”.
- (2) Freeze an image. Click the user-defined key to save the current image file in the default file directory in the dynamic image format .CIN.

The thumbnail of this image will appear in the thumbnail area on the lower side of the screen. When you move the cursor onto the thumbnail, its filename with suffix will be displayed.

## 9.2.5 Quickly Saving Images to USB Flash Drive

Use user-defined keys to quickly save the single-frame or cine to USB flash drive.

The image file is stored in the directory: U disk\ US Export\ animal folder\ exam folder\ Image ID.bmp, here,

- Animal folder name: animal name+ animal ID
- Exam folder name: exam mode+ exam time

■ To store single-frame image to USB flash drive:

- (1) Set the user-defined key through the path: [Setup]→ [System Preset]→ [Key Config]. Select a key in the Key Function page on the left side and select “Send image to USB disk” in the Output page of Function field on the right side.
- (2) Return from Preset to the main screen.
- (3) Press the user-defined key to save the image to the USB flash drive.

■ To store cine to USB flash drive

Save cine images to a USB flash drive in the AVI format.

- (1) Set the user-defined key through the path: [Setup]→ [System Preset]→ [Key Config]. Select a key in the Key Function page on the left side and select “Send Cine to USB disk” in the Output page of Function field on the right side.
- (2) Return from Preset to the main screen, scan and freeze an image.
- (3) Press the user-defined key to save the cineloop.

## 9.2.6 Quickly Saving Full Screen Image to the System

This function can save the current full screen image to the system with the image in real-time status.

1. Set the user-defined key through the path: [Setup] (by pressing <Setup>)→ [System Preset]→ [Key Config]. Select a key in the Key Function page on the left side and select “Send Screen” in the Output page of Function field on the right side.
2. After the setting, you can use the user-defined key to save full screen image to the system.

## 9.2.7 Thumbnails

The stored images or cineloops are displayed in the form of thumbnails on the screen:

- In the iStation screen, the thumbnails refer to the images stored for the selected exam or the selected animal.
- In the scanning or freeze mode, the thumbnails refer to the images stored in the current exam.
- In the Review screen, the thumbnails refer to the images stored in the same exam.
- In the Review screen, open an image to enter the image analyzing status, all the thumbnails belong to the exam are displayed.
- When you move the cursor onto a thumbnail, its name and format will be displayed.


## 9.2.8 Image Review and Analysis

You can review and analyze the stored images (only refer to the images stored in the system default path).

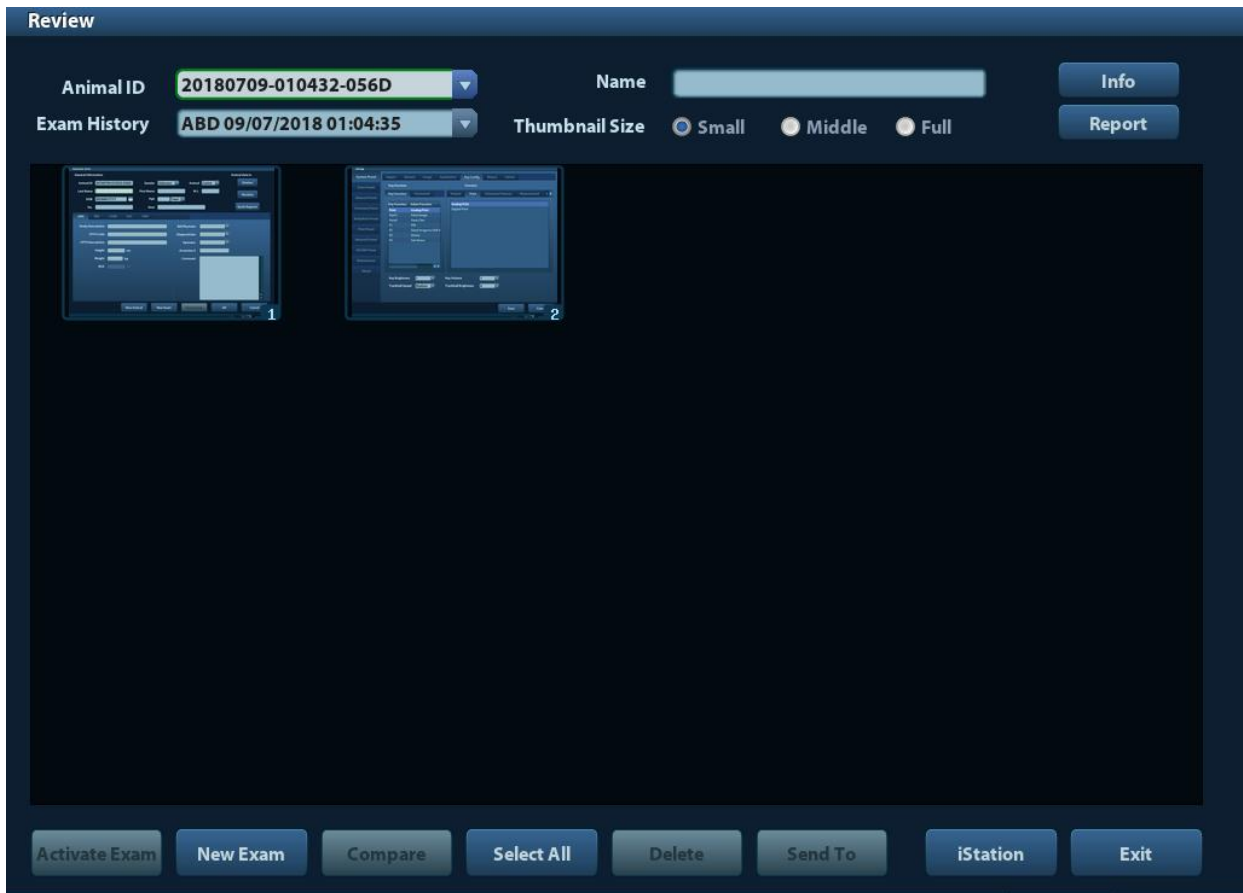
### 9.2.8.1 To review images

You can review all images stored in an exam, and send, delete or analyze the stored images.

■ To enter Review:

- Press <Review> to enter Review screen. The system display the images stored in this exam of the current animal (if there is no current animal information, you can review the images of the latest exam).
- Select an exam of an animal in the iStation screen, and click  to enter the Review screen to review the images of the animal. You can also select more than one exam, and the system will display images of the lately exam images in Review status.

The Review screen is shown as follows:



■ To exit Review:

- Click [Exit] on the Review screen; or,
- Press <ESC> or <Review> again.

■ Basic operations

Move the cursor onto an exam item in the Exam History area and press <Set>. The selected item is highlighted. Click [Info] or [Report] to view animal information or report. Double-click a thumbnail to view and analyze an image. Rotating the Multifunctional knob will navigate through thumbnails.

The function buttons are described as follows:

- Exam History:
  - ▶ You can select one certain exam from the exam directory to review the images.
    - ▶ If entered from iStation, the screen displays the record(s) selected in the iStation. If no animal is selected when it was in iStation, then all the animals in the system database will be displayed, and the current animal exam is listed.
    - ▶ If entered from the imaging status, the Review screen displays the images of the current exam, and the default selected image is the one displayed on the preview main screen.
- Info:
  - ▶ Click to enter the Animal Info screen, you can review or edit the currently-selected animal information.
- Report
  - ▶ Click to review or edit the currently-selected animal report.
- Image operations

[Select All]: click to select all images in the thumbnail window.

[Deselect All]: after clicking the [Select All], the button changes into [Deselect All], you can cancel all the selections by clicking [Deselect All].

[Send To]: click to send the selected image to other location, DICOM server, printer and etc. Or, select the image and click .

[Delete]: click to delete the selected image. Or, select the image and click .

- Thumbnail Size

Small: 4x4

Middle: 2x2

Full: 1x1

- Switching operations:

[New Exam]: click to create a new exam for the selected animal and open the Animal Info screen.

[Activate Exam]: click to enter the currently selected exam and enter the image scanning screen; it grays out if the current animal cannot be activated.

[iStation]: click to enter the iStation screen.

[Exit]: click to exit the Review status, and return to the main screen.

### 9.2.8.2 To analyze images

For the image analysis, you can view, zoom, perform post processing and measurements, add comments and perform cine (multi-frame) review for a stored image. The operation steps are the same as those for real-time scanning; please refer to relevant sections for details.

- To enter image analysis:

- In the image scanning or freeze status, double-click a thumbnail stored in this exam to enter the image analysis status; or
- Double-click the selected thumbnail to open the image.

- To exit the image analysis:

- Press <Freeze> or click [Exit] to exit and enter the real-time scanning status.
- Press <Review> to exit from the image analysis to the Review status.

In image analysis status, the selected image is open on the screen, and the thumbnails of the same exam are displayed on the Thumbnail area, you can turn the pages, delete or send a selected image.

### 9.2.9 iVision

iVision function is used for demonstration of the images stored. Image files are played according to file names one by one (including the image of system-relevant and PC-compatible format).

To perform image demonstration:

1. Enter iVision screen:

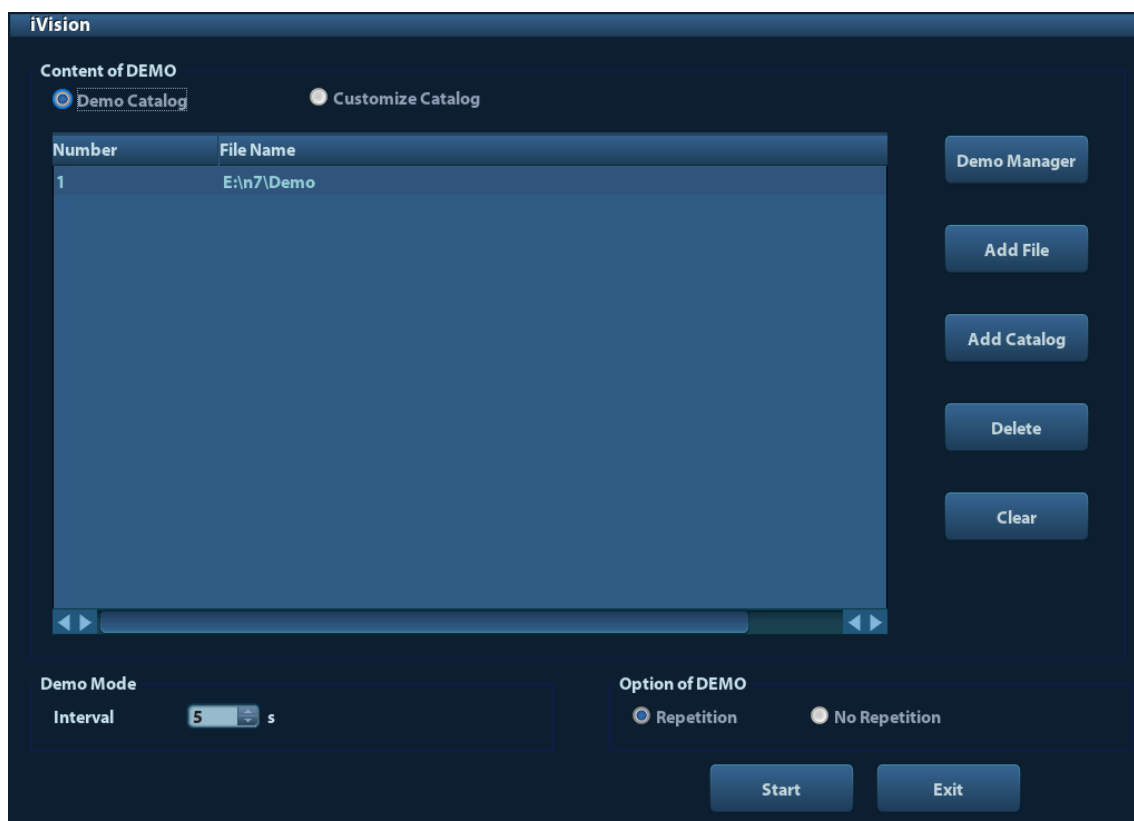
Select [iVision] in the image menu I B mode; or, press the user-defined key for iVision on the control panel (setting path: [Setup]→[System Preset]→[Key Config]).

2. Add the contents to be played and select the demo mode.

3. Select an item in the list, and click [Start] to begin the demonstration.

4. Click [Exit] or press <ESC> to exit the iVision status.

The iVision screen is shown as follows:



■ Demonstration item

The demonstration items are the image files in the formats that the system supports. You can add the exam data in animal database or system supported image files and folders to demonstration list. For files and folders in demonstration list, the images in the directory and subdirectory are played one by one, and the system will automatically jump over the files that can't be opened.

■ Demonstration item

There are two kinds of catalogs: Demo Catalog and Customize Catalog.

- Demo Catalog: demo catalog is the folder in hard disk (E disc), where the factory DEMO is stored. The system plays the images in this folder when performs demonstration.  
The system supports import, delete or clear the data in demo catalog.  
Click [Demo Manager] to operate:  
[>]: to import data to demo catalog.  
[<]: to delete the selected data.  
[<<]: to delete all data.
- Customize Catalog: what saved here is the catalog of the displayed image. The system plays the images in the catalog when performs demonstration.  
Operate the catalog by the buttons on the right:  
[Add File]: to add files to the file list.  
[Add Catalog]: to add catalog to the file list.  
[Delete]: to delete the selected file or catalog in the file list.  
[Clear]: to clear all the files or catalogs in the file list.


- Demonstration mode


Interval: refer to the interval time for demonstration, the adjusting range is 1~500s.

- Option of Demo

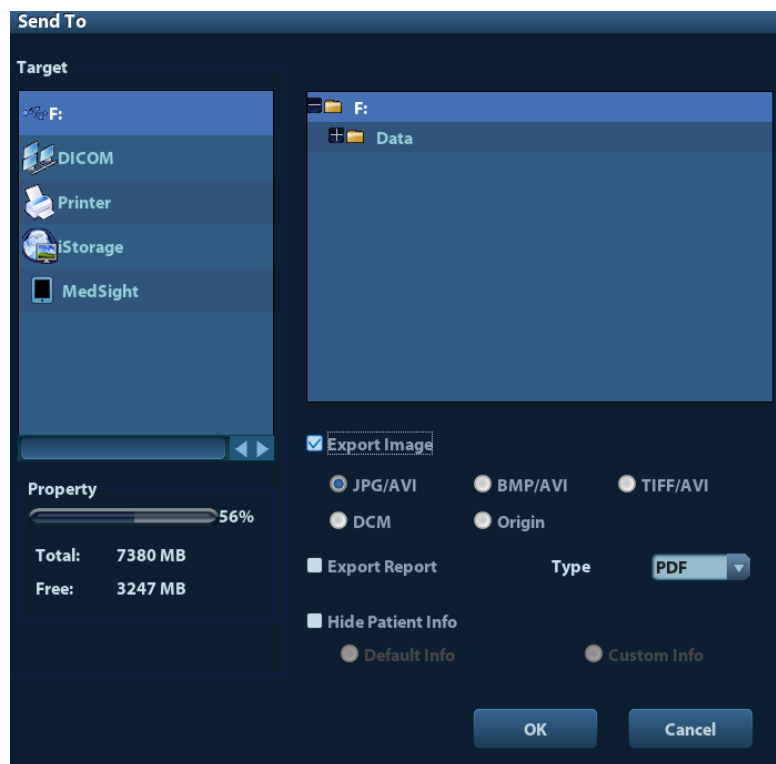
You can choose whether to repeat the demonstration or exit after a demonstration is completed.

## 9.2.10 Sending Image File

- On the image screen, select a stored image thumbnail, click  (Send To) on the right corner of the image, the image can be sent to the external device, DVD recorder, DICOM storage server, DICOM print server, system connected printer, iStorage, MedSight and etc. You can select [Hide Patient Info] to hide the animal information when exporting the image file.

- In the iStation screen, click ; or, in Review screen, click [Send To] to send the selected image to the external devices.

See the figure below.



- For external memory devices (e.g. USB memory devices, DVD iStorage server, or MedSight):
  - a) PC format transfer: JPG/ AVI, BMP/ AVI, TIFF/ AVI. Where a single-frame image is exported as JPG, TIFF or BMP, and the cine file exported as AVI.
  - b) DCM format transfer: DCM (including single-frame DCM and multi-frame DCM).
  - c) You can also select to export report in RTF format.
- For DICOM Storage or Print server, select the DICOM Storage or Print server.
- For a video printer, send images to the video printer connected with the system. For a graph/ text printer, send the images to the default graph/ text printer.
- For MedSight devices, single-frame image will be saved in PNG format, and multi-frame image will be saved in AVI format.





## 9.3 Report Management


- Report storage:

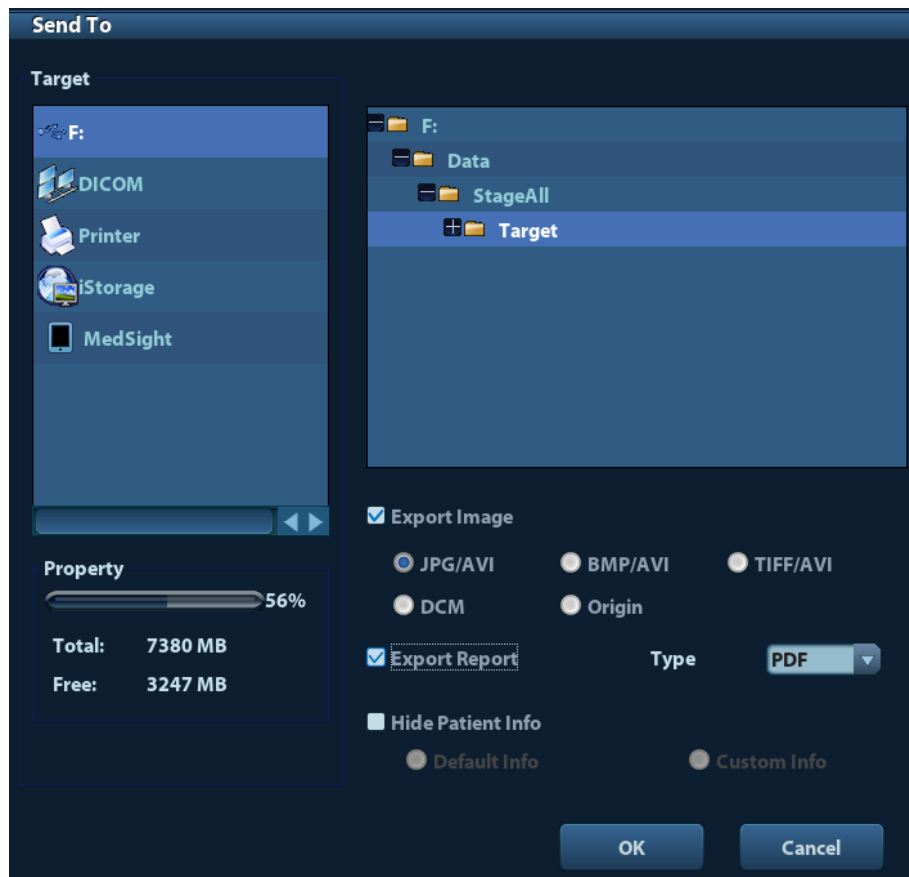
The exam reports are stored under the directory of the exam of the animal.

- Importing, exporting and sending a report

In the iStation screen, select animal data, click  (Restore) or  (Backup) to import or export animal information, images and reports from or to an external memory device. See the following figure:



In the iStation screen, click ; or, in Review screen, click [Send To] to send animal data to an external memory device, you can choose if reports are exported with images. See the figure below.



To export the report:

- (1) Check “Export Report” on the screen.
- (2) Click [OK] to confirm.

You can select paper size for the report in the path: [Setup] → [Print Preset]

#### ■ Printing report

Use a connected graph/text printer to print a report. Please refer to “11.6 Print Preset” for details about default report printer setting.

For details on report relevant operations, please refer to [Advanced Volume].

## 9.4 Animal Data Management (iStation)

The animal data include basic animal information, exam information, image files and reports. You can search, view, backup, send, restore or delete animal data in iStation.

#### ■ To Enter iStation

- Press <iStation> key on the control panel; or
- Click [iStation] in the Animal Info screen; or
- Click [iStation] in the Review screen.

The iStation screen is shown as follows:



#### Viewing Animal Information

- **Data Source**  
Select the data source of animal data, the system animal database is default.
- **Animal List**  
Display animal information, exam mode, number of images and cines, exam state, backed up or not.
- **New Exam:**  
After you select an animal data or exam in the iStation screen, click the [New Exam] to enter the Animal Info screen, where you can select a new exam mode and click [OK] to begin a new exam.
- **Select All Exams/ Deselect All Exams**  
Click [Select All Exams] to select all animal data listed. Then the button changes into [Deselect All Exams], you can cancel all the selections by clicking [Deselect All].
- **Query/Retrieve**  
Select [Query/Retrieve] to enter Query/Retrieve page.

### 9.4.1 Searching an Animal

- (1) Select the data source.
- (2) Set search conditions of Name, ID, DOB, Exam Date in the "Item" drop-down list.
- (3) Enter the keyword in accordance with the "Item" selected, and the system searches and displays the results in the animal list.

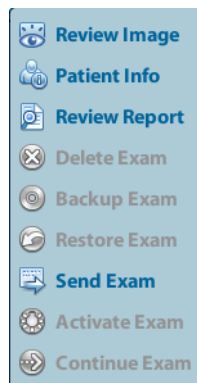
- (4) When you select an animal in the animal list, the images of this animal will be displayed at the bottom of the screen.

Note:

- When you clear the keyword, enter other keyword or cancel the selection “Find in results”, the system will refresh the searched results.
- Select “Find in results”, the system will do searching based on the last searched results.

## 9.4.2 Animal Data View & Management

Select the desired animal information in the list. The following menu pops up:




### ■ Review

Select an exam of an animal, click  **Review Image** to enter Review screen.


### ■ Info:

Select an exam of an animal, click  **Patient Info** on the right side to display the animal information of this exam.

### ■ Report

After you select an exam of an animal, click  **Review Report** to view the report of this exam for this animal. If no report is generated in the exam, the system prompts that “There is no report belongs to the exam”.


### ■ Delete


Select an exam or an animal, click  **Delete Exam** to delete. However, you cannot delete animal data being printed, exported or sent, or delete the current exam.

To delete an image, select the image and click  on the right side.

### ■ Backup/ Restore



You can back up the selected animal data to the system-supported media in order to view it on PC, or restore the animal data to the system from an external media.

 **Backup Exam**: Click to export the selected animal data to the system-supported media.

 **Restore Exam**: Click to import the animal data from an external media. If no external data source is connected, then the button is unavailable.


## ■ Send To

The system supports to send data to external memory devices or print.

- Select the animal record, click  **Send Exam** in the menu to send exam data or images of the selected record.
- Select the image, click  to send the selected image.
  - Send animal exam data to USB devices, DVD drive or iStorage server.
  - Send images to USB devices, DVD drive, DICOM storage server, DICOM printer, video printer, text/ graph printer or iStorage server.
  - Send images with report to USB devices, DVD drive or iStorage server.
  - Format transfer is available when sending images to USB devices, DVD or iStorage server. See "9.2.10 Sending Image File" for details.
  - Press <Shift> on the control panel to select more than one exam or image at one time.
  - MedSight: send the exam to MedSight devices for review.


## ■ Activate exam

After you select an exam, which has been performed within 24 hours, click

 **Activate Exam** to activate the exam and load the basic animal information and measurement data to continue the exam.

If you want to select an animal data in an external memory database to start a new exam or recover the exam, you have to first allow the system to load the animal data to the system's animal database.


## ■ Continue Exam

Select an exam that is paused within 24 hours, click  **Continue Exam** to activate the exam and load the basic animal information and measurement data to continue the exam.

If you want to continue an exam which data lies in an external memory database, you have to first allow the system to load the animal data to the system's animal database.

## ■ Recycle bin

The recycle bin is used to store the deleted animal data, exam data and images (time lasts from deleting to system is powered off). The system supports recovery of those data from the recycle bin. NOTE: The recycle bin will be cleared after the system is powered off.

To recover the deleted animal data, click  at the lower right corner of the screen (when the button is gray, the operation is unavailable) to enter the Patient Recycle Bin screen.

- (1) Select items to be recovered in the list.
- (2) Select operations:
  - Click [Restore Items] to restore the item back to iStation;
  - Click [Delete] to delete the item permanently, and the item can never be restored again;
  - Click [Restore All Items] to restore all the items back to iStation;
  - Click [Empty Recycle Bin] to empty the recycle bin and all items can never be restored again.






Click [Exit] to exit Recycle Bin screen and return to iStation.

## 9.5 Backing Up and Erasing Files through DVD Drive


The system supports DVD-RW to write data in CD/DVD and to read data from CD/DVD in PC.

Support media: DVD±RW, CD-RW.


■ To write data to a CD/DVD:


- (1) Put a CD/DVD in the tray.
- (2) Select the data to be backed up, click  **Send Exam** or  **Backup Exam** in the screen (in iStation or Review). Select the target drive in the Send To or Back Up Patient Record dialogue box.
- (3) Click  **Backup Exam** or [OK] to start writing with the symbol displays .
- (4) After the writing process is completed, click  to pop up the Disc Option dialogue box, and select [Eject] to eject the CD/DVD.

■ To erase data from a CD/DVD

- (1) Put the CD/DVD in the tray.
- (2) Double-click the  symbol to pop up the [Disc Option] screen, as shown in the figure below.
- (3) Click [Erase] to erase data from a CD/DVD;
- (4) After the erasing process is completed, click [Eject] in the Disc Option dialogue box.


Note:

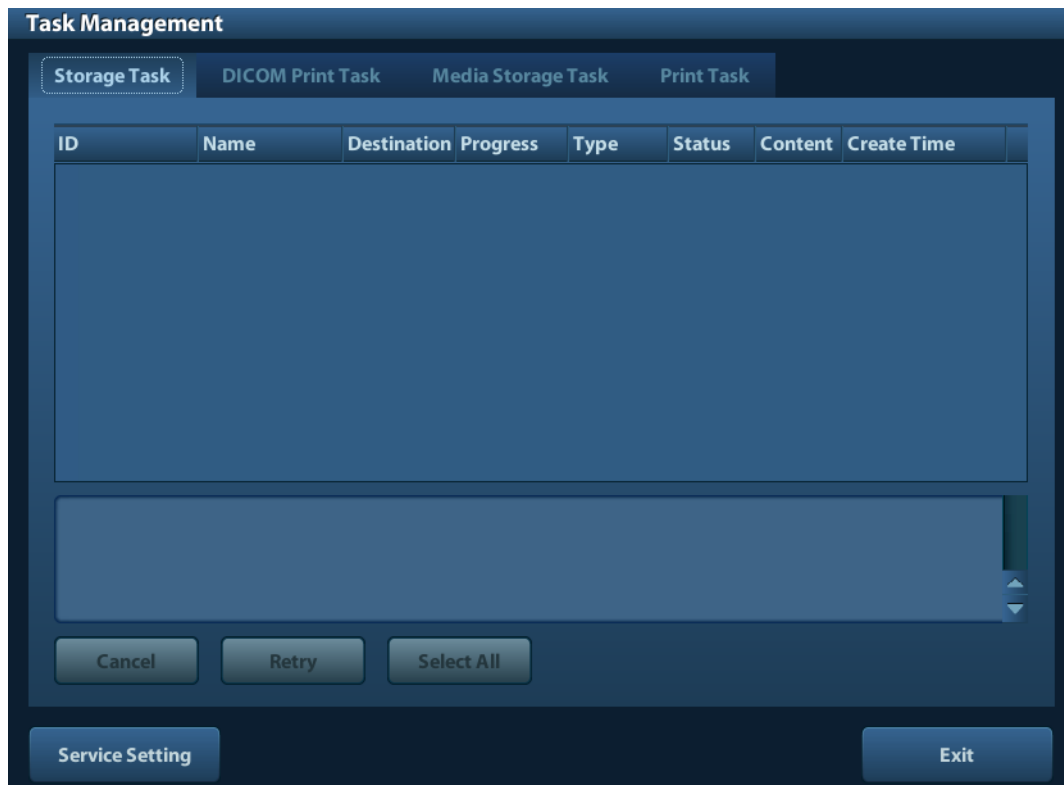
- Writing data using “Send To” supports PC format transfer function, while CD/DVD written by “Backup” supports only system-relevant formats.
- The  symbol indicates that the input CD/DVD is damaged or with data of wrong format.

 **CAUTION:** During the backup process, if a CD/DVD is forcibly taken out or you perform other operations, the backup process will fail or the system may malfunction.



**NOTE:** Directly removing a DVD-RW/DVD+RW drive may result in the damage of drive and/or the system, please refer to “3.6 Connecting/ Removing a USB Storage Device” for disconnection.)

## 9.6 Animal Task Manager

Click  at the lower right corner of the screen to pop up the following dialogue box:



Including:

- Storage Task: displays the DICOM storage task.
- DICOM Print Task: displays the DICOM print task.
- Media Storage Task:
  - DICOM media storage task (including disc and USB devices)
  - Backup task (system-relevant format): select the exam to be backed up in iStation and click  **Backup Exam**.
  - Send to external devices (including disc and USB devices): select exam data or images in iStation or Review screen, click  **Send Exam** or [Send To].
  - iStorage task.
- Print Task
 

List of the current printing task. Displays the file name, status (printing or suspended), printer name, submit time etc.

If all print tasks are finished, the print icon will disappear from the screen, if not, please check the manager to see if there is any failure task.

In the Task Management dialogue box, animal ID, name, destination, progress, type, status, content and task created time are displayed.

You can do the following operations:

- Delete
 

Click [Cancel] to cancel the selected task.
- Retry
 


Click [Retry] to retry the failed task. When the printer ran out of ink or paper, tasks in print list will be paused. Click [Retry] to continue the paused print task.


- Select All


Click [Select All] to select all the tasks.

- Task Status

Select the undergoing task, the system will display its detailed status information or error information.

When there is/are task(s) undergoing, the task management icon displays as , you can click the icon to check the process.

When there is/are task(s) failed, the task management icon displays as , you can click the icon to check the failure reason.

When the task management icon displays as , it means no task is undergoing or failure.

- DICOM Service Setting

Click [Service Setting] to enter DICOM preset. See section 10.3 DICOM Service.

## 9.7 Access Control

### 9.7.1 Access Setting

The system support user type of:

- Administrator

The system administrator can view all animal data, such as animal information, image and report, etc.

- Operator

The operator can only view the exam information saved in the system and operated by himself or herself, such as animal information, image and report, etc. The operator cannot view the exam data operated by others.

Emergency operators are general ones, they can enter the system without entering password. But they can't modify or delete the password.

### 9.7.2 Setting Access Control

The system administrator can preset the access control, that is, if an operator has the right to access to the data in the system.

The access control only can be set by the system administrator.

Setting access control:

1. Open the "Admin" page through the path: [Setup]→[System Preset]→[Admin].
2. If [Enable User Account Control] is selected, you need to login before accessing system data. If unselected, you can access all the data without the authority.



## 9.7.3 System Login

If [Enable User Account Control] is selected, you can access the data in the system only after you login the system.

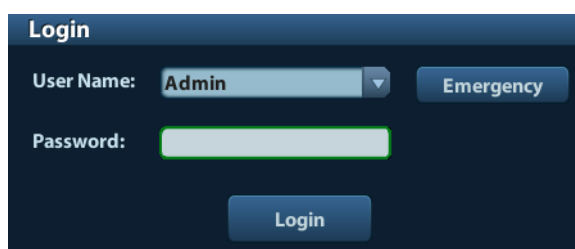
You need to enter user name and password in the following cases:

- Before entering the system
- Changing user

As long as the system is in working status, you can enter the above screens without inputting user name and password repeatedly. You need to login again after system restart or dormancy.

### ■ Login the system:


- (1) If the system requires you to log on the system before you access the data, you can see the following dialogue box.

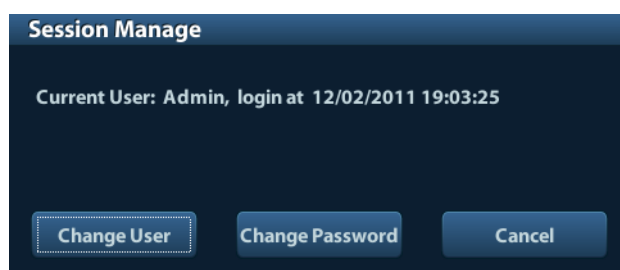


- (2) Select the user name in the drop-down list of User Name.
- (3) Enter password and click [Login].

For emergency users, click [Emergency] directly to log on.

### ■ Changing user

- (1) To log out the current user and change to another user, click  at the lower right corner of the screen to pop up the following dialogue box:



- (2) Click [Change User] to pop up the Login dialogue box.
- (3) Enter the user name and password in the field box.

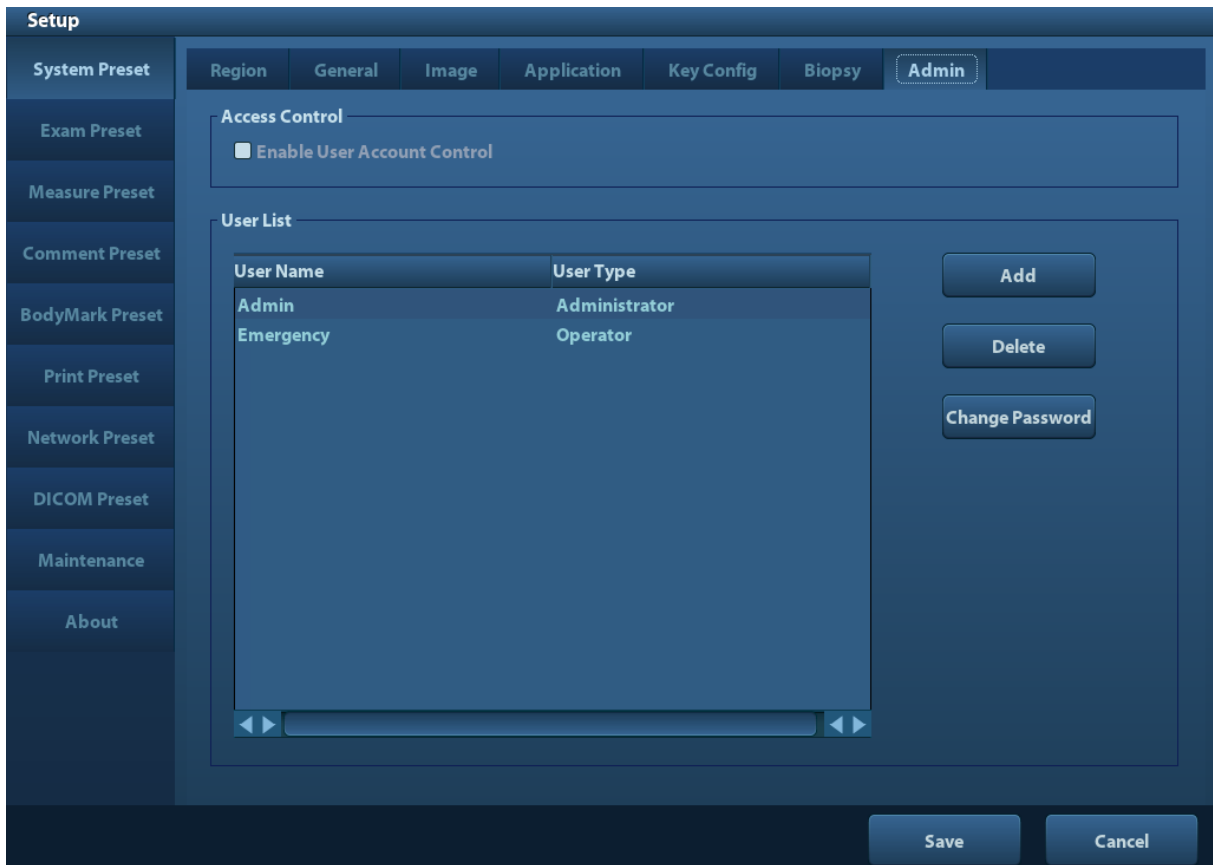
## 9.7.4 Add/ Delete a User

The system administrator can add or delete a user, while the operator can't.

### 9.7.4.1 Add a User

Premise: you must login the system as the system administrator. If not, you will be required to enter administrator name and password before the setting.

1. Open the "Admin" page through the path: [Setup]→[System Preset]→[Admin]. See the figure below.



2. Click [Add] to enter the following page.

3. Enter the user name (you are not allowed to enter the same name or modify the name already exist).
4. Enter user name and the password.
5. Set the user role in the drop-down list: administrator or operator.
6. Click [OK] to confirm the setting and exit the dialogue box, then the new user will appear on the User List.

### 9.7.4.2 Delete a User

Premise: you must login the system as the system administrator. If not, you will be required to enter administrator name and password before the setting.

1. Open the “Admin” page through the path: [Setup]→[System Preset]→[Admin].
2. Select the user to be deleted in the User List (Emergency user can't be deleted), click [Delete] to delete the selected user.


## 9.7.5 Modify Password


The system administrator can modify password of all users. The administrator password by factory is empty. You can set the password for it. The operator can only modify his/her own password.

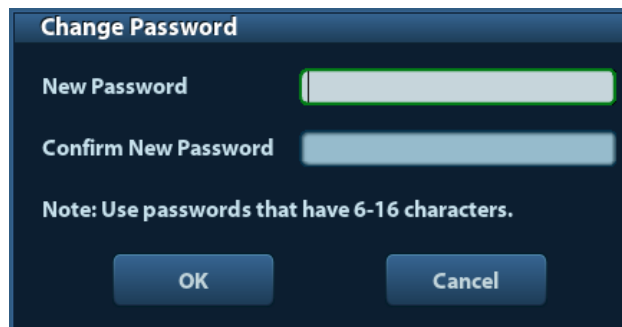
To modify the password, the user has to login the system first.

There are two ways to modify password: modify it on “Admin” page or on “Session Manage” dialogue box.

- “Admin” page (administrator can modify the password)
  - (1) Open the “Admin” page through the path: [Setup]→[System Preset]→[Admin].
  - (2) Select the user name to be modified (except emergency operator) in User List, click [Change Password].
  - (3) Enter new password and confirm password in the dialog, then click [OK].
- Session Manage page (general operator and administrator can modify the password).

When the user has logged on the system, you can see  at the lower right corner of the screen.

- (1) Click  at the lower right corner to pop up the Session Manage dialogue box, on which you can see the current user’s information.
- (2) If you want to modify the current password, click [Change Password] to pop up the Change Password dialogue box.



The image shows a 'Change Password' dialog box with a dark blue header and a light blue body. It contains two text input fields: 'New Password' and 'Confirm New Password'. Below the fields is a note: 'Note: Use passwords that have 6-16 characters.' At the bottom, there are two buttons: 'OK' and 'Cancel'.

- (3) Enter the previous and the new password in the dialogue box.
- (4) Click [OK] to exit.



# 10 DICOM

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**NOTE:** Before using DICOM, please read the electronic file DICOM CONFORMANCE STATEMENT along with the device.

This chapter is confined to the preset, connection verification and DICOM services of the DICOM-configured ultrasound machine, not including SCP configurations like PACS/ RIS/ HIS.

The DICOM package is optional, so the description here is only applicable for the system configured with the DICOM package.

This system supports the following DICOM functions:

- DICOM Basic functions: DICOM verify connectivity, DICOM task management, DICOM storage, DICOM print, DICOM storage commitment, DICOM media storage (DICOMDIR review)
- DICOM Worklist
- DICOM MPPS
- DICOM Query/Retrieve

Workflows of DICOM preset and application are briefly described as follows:

1. DICOM preset (network preset, DICOM preset and DICOM service)
2. Verify connection.
3. DICOM Services (image storage, print, Worklist, storage commitment, media storage, DICOMDIR review, task management).

Abbr. used in this chapter:

Abbr.	Descriptions
DICOM	Digital Imaging and Communications in Medicine
AE	Application Entity
PDU	Protocol Data Unit
SCU	Service Class User (DICOM client)
SCP	Service Class Provider (DICOM server)
SOP	Service-Object Pair

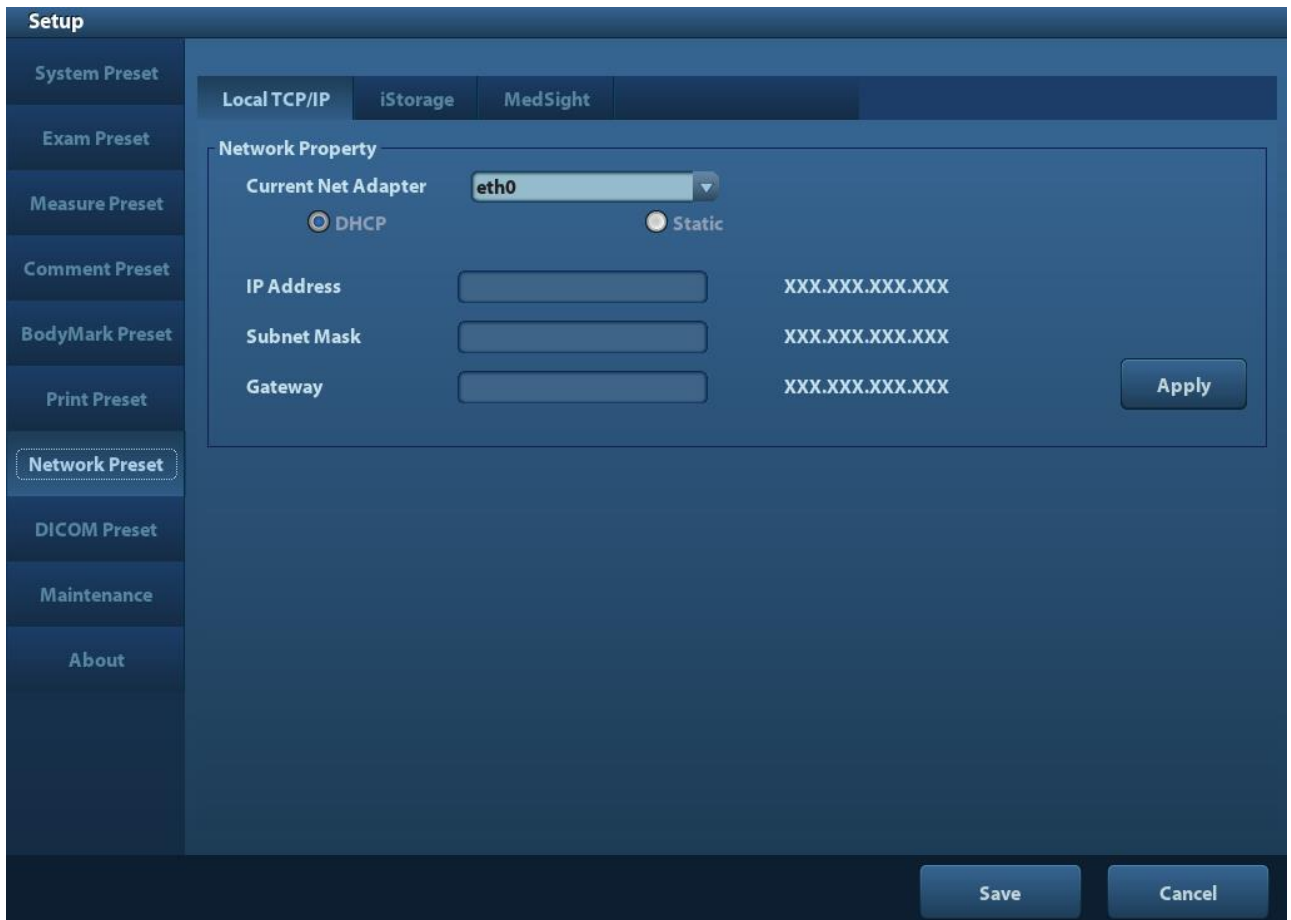
## 10.1 DICOM Preset

### 10.1.1 Network Preset

**NOTE** DO Not edit IP address in Network Preset page as the network task is executed, otherwise it fails. View if there is any undergoing task in task manager of the system.

Preset local TCP/IP settings.

1. Press <Setup> to enter the [Setup] menu.
2. Select [Network Preset].



3. Local TCP/ IP preset items are described as follows:

Name	Description
Current Net Adapter	To select network connection mode.
DHCP / Static	DHCP: IP address will be automatically obtained from DNS server; Static: you need to enter the IP address.
IP Address	IP address of the system.
Subnet Mask	Used to set different network segment.
Gateway	Used to set the gateway IP.

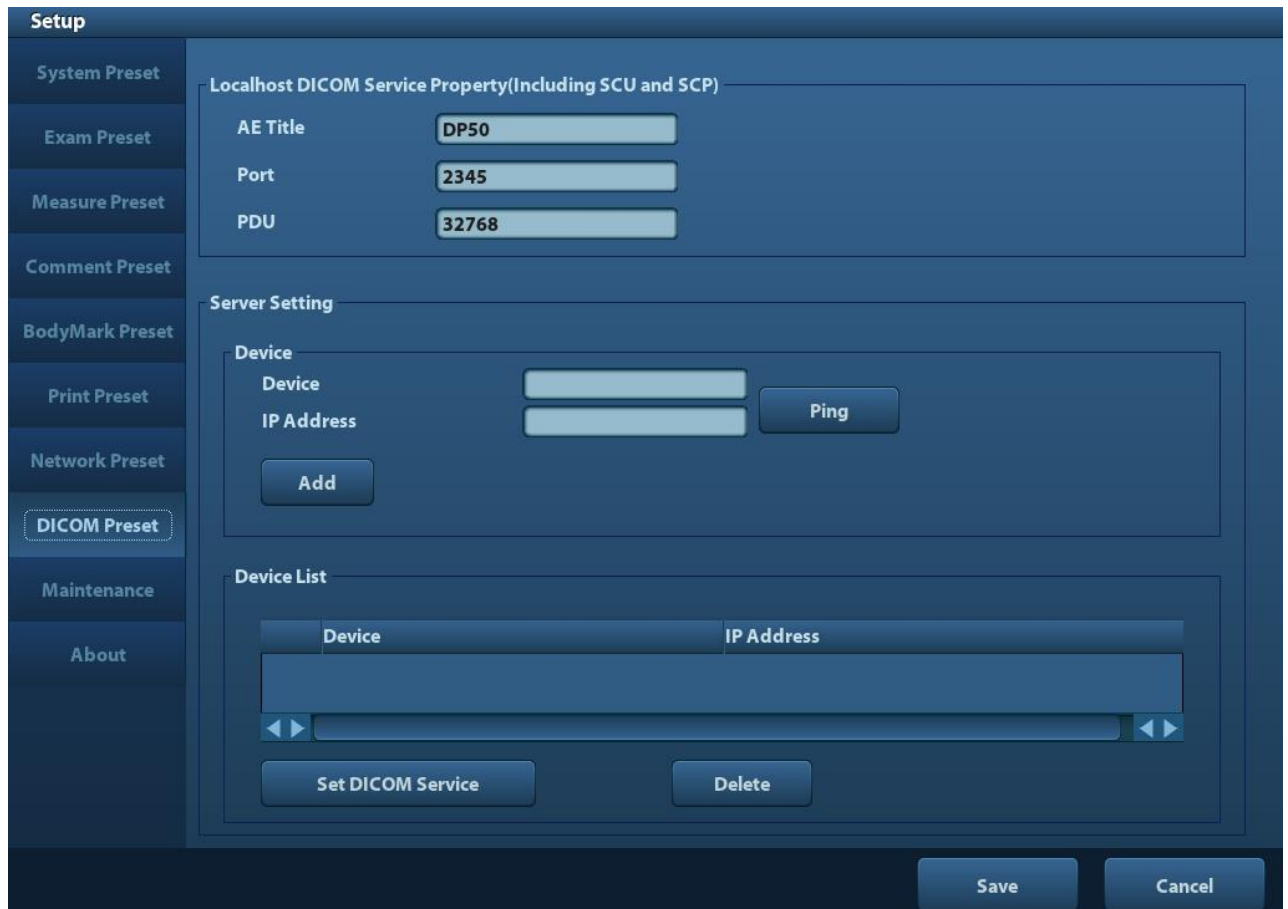
Note:

- The IP address of the system should not be occupied by other devices in the network, or the DICOM function will fail.
- After you changed “Station Name”, you need to restart the system to make the setting effective (press the power button and select “Shut Down” and restart the system after a while).

## 10.1.2 DICOM Preset

To set the DICOM service and server properties.

1. Press <Setup> to enter the [Setup] menu.
2. Select [DICOM Preset].



3. Preset local DICOM properties and DICOM server.

■ Localhost DICOM Service Property

Name	Description
AE Title	Application entity title of the ultrasound system. The AE title here should be the same with the one of the acceptable SCU set in the server.
Port	DICOM communication port, which should be the same with the one in the server.
PDU	Maximum PDU data package size ranging from 16384 to 65536. The default value is 32768.

Enter AE Title, Port, PDU according to the actual situation, and then click [Save] to exit the screen.

Note:

- AE Title should be the same with the SCU AE Title preset in the server (PACS/ RIS/ HIS), for example, if the AE Title of the server preset in the print server is AAA, and the AE Title of the accepted SCU is preset as MMM, then in the figure above, the AE Title of Local should be MMM, and the AE Title of print server should be AAA.

## ■ DICOM Server Setting

Name	Description
Device	Name of the device supporting DICOM services.
IP Address	IP address of the server.
Ping	You can ping other machines to verify connection after entering the correct IP address. Also you can check the connection of the already added server in the list.
[Add]	Click to add servers to the device list.
[Set DICOM Service]	Click to enter DICOM service preset, see “10.1.3 DICOM Service”.
[Delete]	Click to delete the selected server (s) in the device list.

Note:

- If the currently entered name has already existed, the system will pop up: “The server name exists!” Click [Save] to enter another name.

### 10.1.3 DICOM Service

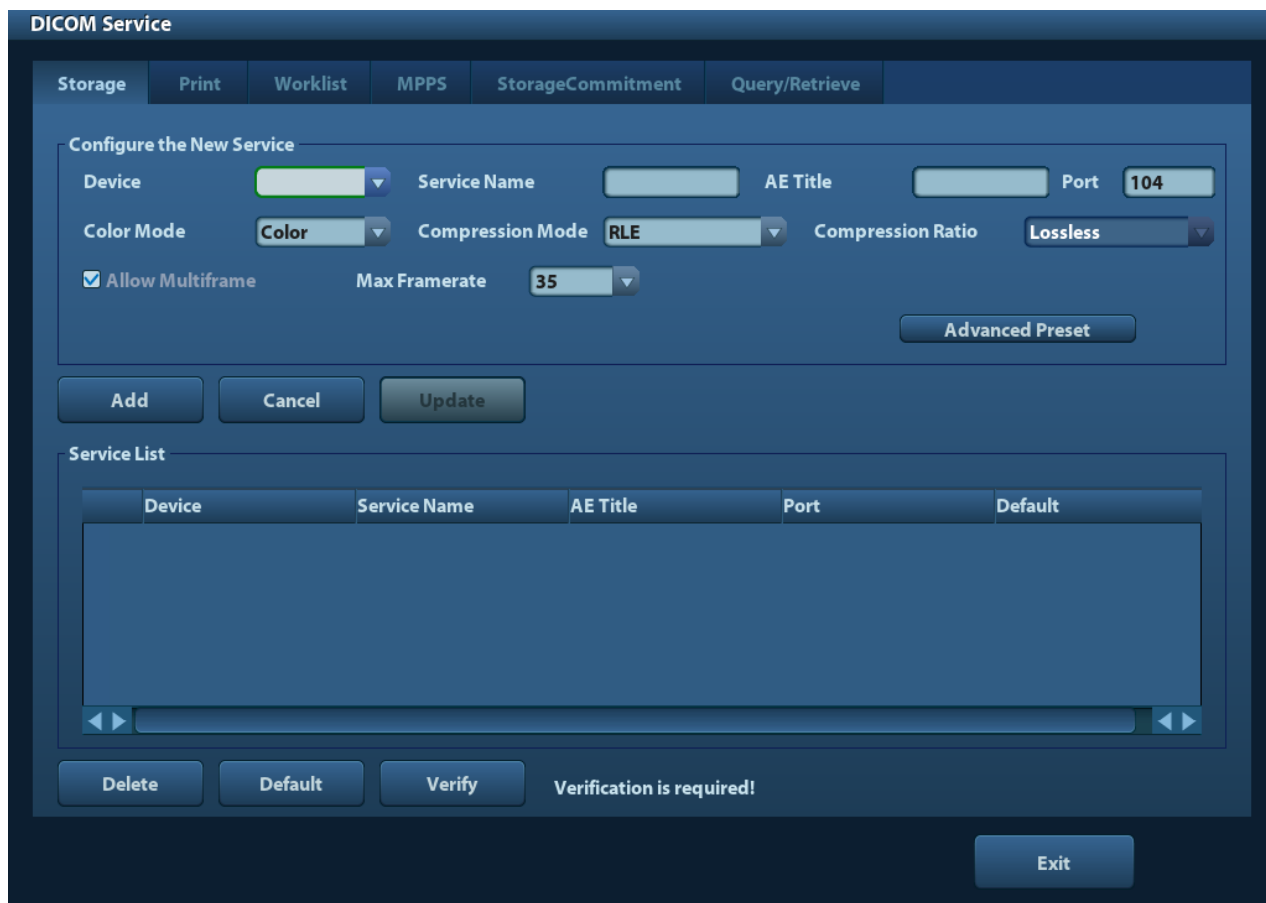
When the system is configured with DICOM basic function module, and installed DICOM Worklist and Storage Commitment, the corresponding preset settings can be found in DICOM Service screen.

Enter [Setup]-> [DICOM Preset], Click [Set DICOM Service], you can add, delete and set the property of the service on DICOM server.

#### 10.1.3.1 Storage

1. Enter [Setup]-> [DICOM Preset]-> [Set DICOM Service]-> [Storage].
2. Select device, and enter the information. For device setting, please refer to “10.1.2 DICOM Preset.”
  - Click [Add] to add the service to the Service list;
  - Select an item in the service list, change the parameters in the above area, and click [Update] to update the item in the service list; click [Cancel] to cancel changing.
  - Select an item in the service list, and click [Delete] to delete the service.
  - Select an item in the service list, and click [Default] to set the server to be the default service.
3. Select an item in the service list, and click [Verify] to verify the connection.
4. Click [Exit] to save and exit the preset.





DICOM storage setting items are described as follows:

Name		Description
Device		After you set the server (s) in DICOM Server Setting, the name (s) will appear in the drop-down list, select the name of the storage server.
Service Name		Default is xxx-Storage, and it can be modified.
AE Title		Application Entity title, Here, it should be consistent with that of the storage server.
Port		DICOM communication port, 104 by default. Here, the port should be consistent with that of the storage server port.
Advanced Preset	Maximum Retries	Range: 0-9.
	Interval Time(s)	Reserved feature.
	Timeout	Refers to time after which the system will stop trying to establish a connection to the service. Value: 5—60s, in increments of 5s, and 15 by default.
Color Mode		Gray/ Mixed/ Color
Compression Mode		Select the compression mode: uncompressed, RLE, JPEG and JPEG2000.
Compression Ratio		Select the compression ratio: lossless, low, medium and high.
Allow Multiframe		If SCP supports this function, then select it.

Name	Description
Max Framerate	25, 30, 35, Full are available, user-changeable
[Add]	Add the DICOM service to the service list.
[Cancel]	Click to cancel the parameter setting.
[Update]	Select an item in the service list, change the parameters in the above area, and click [Update] to update the item in the service list.
[Delete]	Click to delete the selected service in the service list
[Default]	Select an item in the service list, click [Default] and you can see "Y" in the Default column.
[Verify]	Click to verify if the two DICOM application entities are normally connected.
[Exit]	Click to exit the screen.

Tips: RLE, JPEG and JPEG2000 are not supported by all SCPs. Please refer to the electronic file *DICOM CONFORMANCE STATEMENT* of the SCP to check whether SCP supports or not. Do not select these compression modes if the storage server doesn't support them.

### 10.1.3.2 DICOM Print

1. Enter [Setup]-> [DICOM Preset]-> [Set DICOM Service]-> [Print].
2. Select device, and enter the information. For device setting, please refer to "10.1.3 DICOM Service."
  - Click [Add] to add the service to the Service list;
  - Select an item in the service list, change the parameters in the above area, and click [Update] to update the item in the service list; click [Cancel] to cancel changing.
  - Select an item in the service list, and click [Delete] to delete the service.
  - Select an item in the service list, and click [Default] to set the server to be the default service.
3. Select an item in the service list, and click [Verify] to verify the connection.
4. Click [Exit] to confirm the setting and exit the page.

**DICOM Service**

Storage   Print   Worklist   MPPS   StorageCommitment   Query/Retrieve

**Configure the New Service**

Device  Service Name  AE Title  Port

**Print Properties**

Copies  Settings  Film Orientation  Priority

Film Size  Display Format  Medium Type  Trim

Min Density  Max Density  Configuration Info

Destination  Magnification Type

**Service List**

Device	Service Name	AE Title	Port	Default

Verification is required!

DICOM print setting items are described as follows:

Name		Description
Device		After you set the server (s) in DICOM Server Setting, the name (s) will appear in the drop-down list, select the name of the print server.
Service Name		Default is xxx-Print, and it can be modified.
AE Title		Application Entity title. Here, it should be consistent with that of the print server.
Port		DICOM communication port, 104 by default. Here, the port should be consistent with that of the print server port.
Advanced Preset	Maximum Retries	Range: 0-9.
	Interval Time(s)	Reserved feature.
	Timeout	Refers to time after which the system will stop trying to establish a connection to the service. Value: 5—60s, in increments of 5s, and 15 by default.
Copies		Refer to copies of printed files. You can select among 1 through 5, or directly enter the number.

Name	Description
Settings	The system supports RGB (color printing) and MONOCHROME2 (black and white printing). Please select the type the printer supports.
Film Orientation	Select between LANDSCAPE and PORTRAIT.
Priority	Specify printing task priority among HIGH, MED and LOW.
Film Size	Select film size among the selections listed in the drop-down list.
Display Format	Specify quantity of printed files, e.g. STANDARD\2, 3 indicates 6 images are printed for each page.
Medium Type	Specify print medium: Paper, Clear Film, Blue Film.
Trim	Specify whether you want a trim box to be printed around each image on the film: Yes or No.
Min Density	Enter the minimum density of the film
Max Density	Enter the maximum density of the film.
Configuration Info	Enter configuration information in the field.
Destination	Specify where the file is exposed: MAGAZINE (stored in the magazine), or PROCESSOR (exposed in the processor)
Magnification Type	Replicate: interpolated pixels belong to duplicate of adjacent pixels; Bilinear: interpolated pixels are generated from bilinear interpolations between adjacent pixels; Cubic: interpolated pixels are generated from cubic interpolations between adjacent pixels; None: without interpolation. Select how the printer magnifies an image to fit the film.
[Add]	Add the DICOM service to the service list.
[Cancel]	Click to cancel the parameter setting.
[Update]	Select an item in the service list, change the parameters in the above area, and click [Update] to update the item in the service list.
[Delete]	Click to delete the selected service in the service list.
[Default]	Select an item in the service list, click [Default] and you can see "Y" in the Default column.
[Verify]	Click to verify if the two DICOM application entities are normally connected.
[Exit]	Click to exit the screen.

Parameter setting should be consistent with the printer performance:

- For instance, if the printer cannot support film size to be "8IN\*10IN", please select the printer supported size.
- Settings: RGB is color printing and MONOCHROME2 is black and white printing.

- Medium Type: for black and white printing, usually Blue Film or Clear Film is used, and for color printing, Paper is usually used. For details, please refer to printer conformance statement.
- Change the setting if necessary.

### 10.1.3.3 DICOM Worklist

1. On DICOM Service screen, click [Worklist] page tab to enter the Worklist page.
2. Select device, enter the right AE Title, port, etc.
3. Click [Add] to add the service to the Service List.

DICOM Worklist service parameters are similar to those described in DICOM Storage Preset, please refer to “10.1.3.1 Storage” for details.

### 10.1.3.4 MPPS Preset

1. On DICOM Service screen, click [MPPS] page tab to enter the MPPS page:
2. Select device, enter the right AE Title, port, etc.
3. Click [Add] to add the service to the Service List.

DICOM MPPS service parameters are similar to those described in DICOM Storage Preset, please refer to “10.1.3.1 Storage” for details.

### 10.1.3.5 Storage Commitment

1. On DICOM Service screen, click [Storage Commitment] page tab to enter the Storage Commitment page.
2. Select device, enter the right AE Title, port, etc.
3. Click [Add] to add the service to the Service List.

Special setting item for DICOM Storage Commitment service is Associated Storage Service, as described in the following; other parameters are similar to those described in DICOM Storage Preset, please refer to “10.1.3.1 Storage” for details.

Name	Description
Associated Storage Service	The associated storage server should be preset before storage commitment, only after the exam is sent out, can storage commitment be created.

### 10.1.3.6 Query/Retrieve Preset

1. On DICOM Service screen, click [Query/Retrieve] page tab to enter the Query/Retrieve page.
2. Select device, enter the right AE Title, port, etc.
3. Click [Add] to add the service to the Service List.
4. Click [Exit] to confirm the preset and exit the page.

DICOM Query/Retrieve service parameters are similar to those described in DICOM Storage Preset, please refer to “10.1.3.1 Storage” for details.

## 10.2 Verify Connectivity

If you want to verify connectivity (not a must), you can click [Verify] button on the pages of DICOM Service screen respectively.

- If the verification succeeds, it will prompt “xxx Verify Succeed”.
- Otherwise, it prompts “xxx Verify Failed”.

If verification failed, the possible causes may be:

- The ultrasound machine can't communicate normally with the server. Please check if the cable is properly connected; or,  
Check if the IP of the server is configured in the same segment with that of the ultrasound machine; or,  
Check if the network adapter, the router, the exchanger or the HUB are normally working.
- The server does not support the verification. If the connection is normal, it can be concluded that the server does not support the verification.
- The server supports the verification, but this function is not activated. Please check if the verification function is activated.

Note:

Not all the SCPs can support verification; please consult SCP belongings to confirm whether SCP can support this service. If not, the verification won't pass.

## 10.3 DICOM Service

If the system is configured with DICOM modules, and connected to the relevant DICOM servers, after verifying connection, you can perform storage, print, Worklist, MPPS, storage commitment, and query/ retrieve applications.


### 10.3.1 DICOM Storage

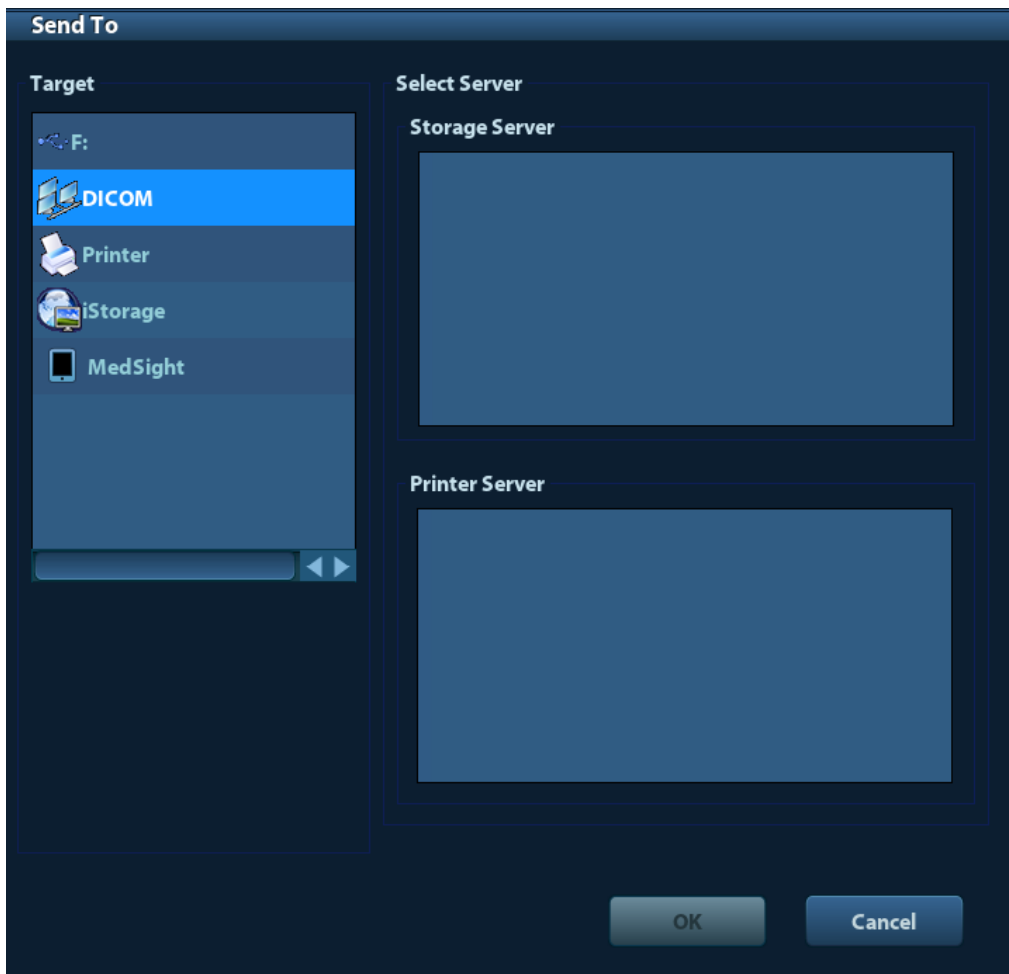
DICOM Storage is used to send image(s) to DICOM storage server for storage.

#### ■ Send image in iStation/Review/main screens

##### (1) Select image(s)

- Press <iStation> to enter the iStation screen, click to select an exam record in the list, where thumbnails are displayed in the thumbnail area in the lower part of the screen, and then click to select a thumbnail or several thumbnails. Or,
- Press <Review> to enter the Review screen, click to select an image or several images. Or,
- On the main screen, select a thumbnail or several thumbnails.

- (2) Select a saved image in the iStation, Review or main screen, and click  on the right side of the image. The following dialogue box pops up:



- (3) Select DICOM in the “Target” list, select a server in the “Storage Server” list.
- (4) Click [OK] to start the sending.

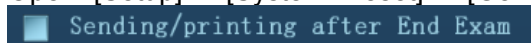
■ To send images by shortcut key

You can save single frame image or multi-frame images to DICOM server while saving to hard drive by shortcut key. Procedures are described as follows:

- (1) Define the key:
  - a) Open Key Config page via “[Setup] → [System Preset] → [Key Config]”.
  - b) Assign functions to the desired keys: in Key Config page, select a free key or footswitch at the left side, then select the corresponding key on the right side:
  - c) Click [Save] to confirm the preset and exit.
- (2) Set a default storage server:
  - a) Enter the DICOM Service Preset screen via “[Setup] → [DICOM Preset] → [Set DICOM Service]”.
  - b) Select a storage server in the Service List and click [Default]; you can see “Y” is marked in the Default column.
  - c) Click [Exit] to exit the page and return to Setup menu, then click [Save] on the Setup menu to make the preset to take effect.
- (3) Press the user-defined key to send DICOM storage.

■ To send image for storage after an exam ends

- (1) Open “[Setup] → [System Preset] → [General]”, and then check

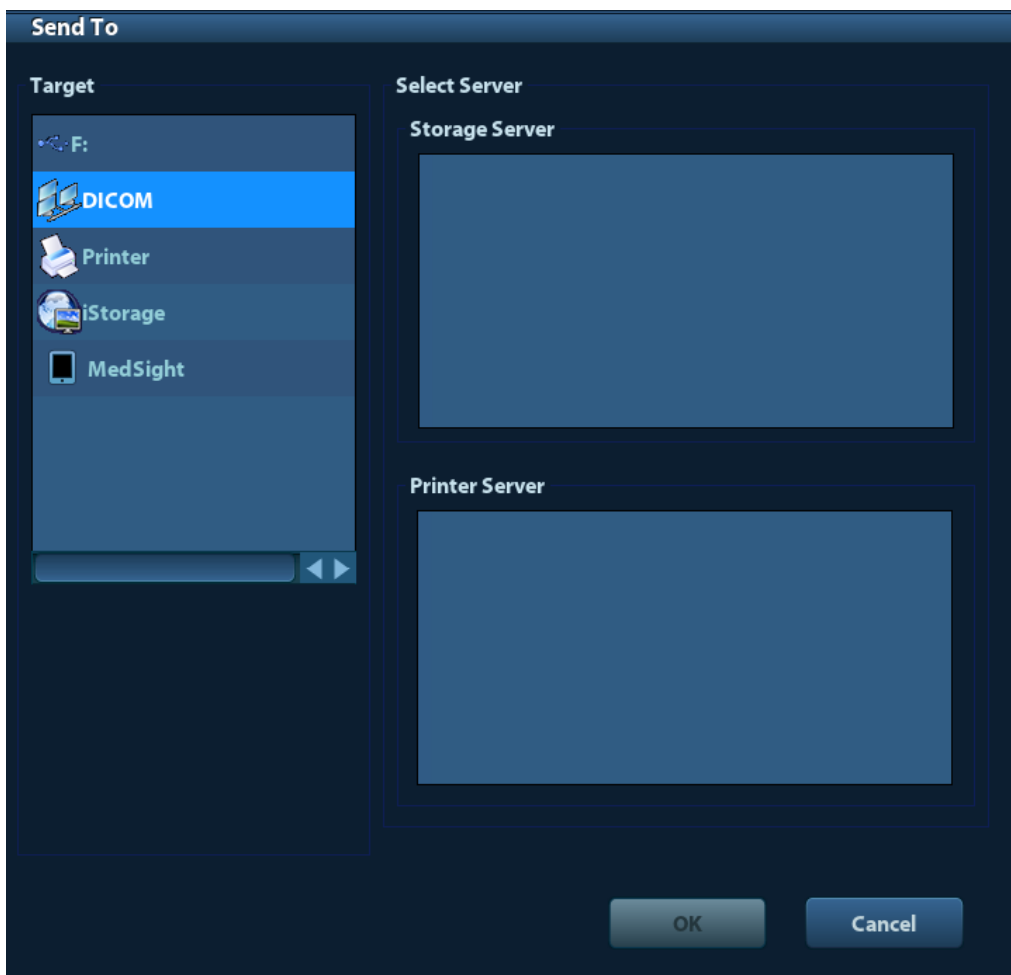


- (2) Set a default storage server.
  - a) Enter the DICOM Service Preset screen via “[Setup] → [DICOM Preset] → [Set DICOM Service]”.
  - b) Select a storage server in the Service List and click [Default]; you can see “Y” in the Default column.
  - c) Click [Exit] to exit the page and return to Setup menu, then click [Save] on the Setup menu to make the preset to take effect.
- (3) After finishing resets, you can perform image scanning, each time you press <End Exam> on the control panel, the system will send the image to the default DICOM storage server for storage.

## 10.3.2 DICOM Print

DICOM Print is used to send image(s) to DICOM print server to print images.

- Print image in iStation/Review/main screens
  - (1) Select image(s), operations are the same with DICOM storage.
  - (2) In the Send To dialog box, select a DICOM print server.



- (3) Click [OK] to send print task.
- To print image for storage after an exam ends
    - (1) Open “[Setup] → [System Preset] → [General]”, and then check  Sending/printing after End Exam.



- (2) Set a default print server.
  - a) Enter the DICOM Service Preset screen via “[Setup]→ [DICOM Preset] → [DICOM Service]”.
  - b) Click [Print] to open the Print page.
  - c) Select a Print server in the Service List and click [Default]; you can see “Y” is marked in the Default column.
  - d) Click [Exit] to exit the page and return to Setup menu, then click [Save] on the Setup menu to make the preset to take effect.
- (3) After finishing presets, you can perform image scanning, each time you press <End Exam> on the control panel, the system will send the image to the default DICOM print server for printing.

### 10.3.3 DICOM Worklist

After successfully connected DICOM Worklist server with ultrasound system, you can query animal records from Worklist server, and then import the desired information to your system.

- To query animal information via Worklist server:
  - (1) Press <Patient> to enter Animal Info screen.
  - (2) Click [Worklist] to enter the Worklist page.

- (3) Retrieve Animal Information
  - a) Set query criteria among Animal ID, Animal Name, Accession #, Search Key, Worklist Server or Exam Date. The default exam date is the current date.

- b) Click [Query].
  - c) The scheduled animals, which meet the criteria, are displayed in the lower part of the screen.
  - d) After the first query, you can perform the second query based on the preview results. The scheduled animals in the list will update in real time.
- (4) Select the desired animal record in the displayed animal list, and  
Select the desired animal and click [Start Exam], the animal information is imported into the system and then an exam is started.  
Click [Transfer], the animal information is imported into the Animal Info screen. Edit the animal information in the Animal Info screen, and select [OK] to start a new exam.
- (5) To show animal information in details:
- a) Click to select an animal record.
  - b) Click [Show Detail] to view the detailed animal information and properties.
- Use the automatic query function via Worklist server
    - (1) Enter DICOM Service Preset screen, and open the Worklist page: [Setup]→[DICOM Preset]→[Set DICOM Service]→“Worklist”.
    - (2) Select an item in the service list, and click [Default] to set the server to be the default service.
    - (3) Click [Exit] and click [Return] in the Setup menu.
    - (4) Press <Patient> to enter Animal Info screen.
    - (5) Click [WorkList] to enter the WorkList page.
    - (6) The system queries intraday animals via Worklist server automatically and the animal records will appear in the list.

In the off-line status, you can:

- Perform a second query; or,
- Click [Show Detail] to view the animal information in details:

### 10.3.4 MPPS

MPPS is used to send exam state information to the configured server. This will facilitate the other systems to obtain the exam progress in time.


The status information is described as below:

- When you begin an exam or send image(s) during the exam, the system sends status information “Active” to MPPS server.
- When the exam is completed, the system sends status information “End” to MPPS server.
- When a paused exam is continued, the system sends status information “Active” to MPPS server.
- When an exam is cancelled, the system sends status information “Cancelled” to MPPS server.

### 10.3.5 Storage Commitment

Storage commitment is used to make sure the images are successfully stored in the DICOM server.


Before storage commitment, you should set a default storage commitment server.

- Storage commitment after sending images on iStation screen
  - (1) Open iStation screen: press <iStation> or press <Patient> and click [iStation].
  - (2) Select an exam record (image (s) is/are stored in the exam record), click  to open the Send To dialogue box.
  - (3) Click to select "DICOM" in the "Target" box on the left side, then select the DICOM storage server in the "Storage Server" box on the right side.
  - (4) Click [OK] to start sending. The system will send all the images stored in the exam record to the storage server, meanwhile, it will send storage commitment to the storage commitment server.
- To send storage commitment after an exam ends
  - (1) Open [Setup] -> [System Preset]-> [General], and then select [Sending/ Printing after End Exam] in the Animal Info area.
  - (2) Set the default storage server and storage commitment server.
    - a) Enter the DICOM Service Preset screen via "[Setup] -> [DICOM Preset] -> [Set DICOM Service]".
    - b) Select a server in the Service List of Storage page and Storage Commitment page and click [Default]; you can see "Y" is marked in the Default column.
    - c) Click [Exit] to exit the page and return to Setup menu, then click [Save] on the Setup menu to make the preset to take effect.
  - (3) When finished the presets, you can perform image scanning, each time you press <End Exam> on the control panel, the system will send the image to the default DICOM storage server for storage and send storage commitment to storage commitment server.

If images are successfully sent to the storage server, the storage commitment server will return information about the successful image storage. In the iStation screen, you will see there is a tick "√" marked in the list below .

Tips:

Storage commitment is confined to the whole exam; not each image sending can be indicated.

**NOTE:** Multi-frame storage is not allowed if "Allow Multiframe" is not selected ([Setup]-> [DICOM Preset] -> [Set DICOM Service] -> [Storage]). For example, if there is multi-frame file in the exam to be sent, then only single-frame image storage will be performed, and after the storage is completed, there is no "√" marked in the list below  in the iStation screen.

### 10.3.6 Query/Retrieve

The query/retrieve function is employed to query and retrieve the animal exam records in a designated server.

After setting the DICOM query/retrieve server, you can perform the query/retrieve function in iStation screen.

1. Open iStation screen: press <iStation> on the control panel; or, press <Patient> on the control panel, and then click [iStation] on the Animal Info screen.
2. Click [Query/Retrieve] to open the screen.

**Query/Retrieve**

**Server and Service**

Source

Destination

**Query**

Patient ID  Patient Name

Accession #  Exam Date  To

Search Key

Patient(Source) 0 records are listed.

Patient ID	Name	Accession #	Exam Description	Exam Date/Time	Gender	DOB

Patient(Destination) 0 records are listed.


Patient ID	Name	Accession #	Exam Description	Exam Date/Time	Content	Gender	DOB

3. Select the server in "Server and Service" area (both the source and the destination).
4. Enter the query information, such as Animal ID, Animal Name, Accession #, Exam Date, or key words.  
Click [Clear] to empty the entered query information.
5. Click [Query], the system performs the query and lists out the results into the animal (source) list.  
You can perform further query basing on the results by entering new query information.
6. Select one or more animal records according to the actual situation.  
Click [Select All] to select all the animal records in the list.  
Click [Deselect All] to deselect all the animal records in the list.
7. Click [Retrieve] to retrieve the animal records in the DICOM query/retrieve server into the local machine.
8. Click [Exit], you can see the retrieved animal records are listed in the iStation screen.

## 10.4 DICOM Media Storage

The system supports to save animal data to the external media in DCM format. Meanwhile, in the system, you can view the saved DCM files from external media

### ■ Media storage:

1. Select animal record(s) in the iStation screen.
2. Click , the following dialog box popped up:



3. Select the destination, and select DICOM format.
4. Set whether to remove animal exam data or only images from the local hard disk.
5. Click [Backup] to begin storage.

If the backup succeeded, there will be a tick marked in the Backup list in iStation screen; otherwise, no tick is marked.


**Tips:** There should be no DICOMDIR/ DICMIMG/IHE\_PDI files in the external storage media of the same name with the one being backed up, otherwise, the backup can't proceed. Please make sure there is enough storage space; otherwise, backup may fail due to space shortage.

■ **Media review:**

1. Connect the external media with DCM files to the system.
2. Select the data source in iStation screen, and the visible data will be shown.

If there are several kinds of data on the media, the system will ask you to select the format from a dialog box.

■ **Data Restore:**

1. If the DICOM format data is backed up to external media, you can restore the data to the system from the media.
2. Review the data stored in the external media.
3. Select the data to be restored in iStation.
4. Click  in the iStation screen.

**NOTE:** Only the system accessible media can be selected.

## 10.5 DICOM Task Manager

DICOM Task Management is used to view task progress or manage tasks after sending images for storage, print, or media storage.

For details on task manager, see 9.6 Animal Task Manager.

# 11 Setup

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The Setup function is designed to set the configuration parameters of operating the system and maintaining user workflow setup data. The setup data of the user and system are stored to the hard drive, and should be backed up to CD/DVD or USB memory devices.



**CAUTION:** When the setup data is changed, be sure to save the preferences according to the methods described in this chapter. Mindray is not responsible for the loss of the setup data.

- To enter Setup:
  - Press the <Setup> to enter Setup.
- To exit Setup:

Click [Save] on the Setup menu and the parameter settings is saved.

Click [Cancel] or press <Esc> on the control panel to exit the setup.

If you change the system language and click [Save] on the Setup menu, the system will automatically restart to make the changing effective.

## 11.1 System Preset


Click [System Preset] on the Setup menu, you can preset:

Page	Description
Region	To set the hospital name, language, time zone, time format, system date/time, logo and so on.
General	To set animal information, exam setup, animal management, storage, system dormancy, operation log and so on.
Image	To set some general parameters in imaging modes.
Application	To set the measure ruler, follicle etc..
Key Config	To assign functions to footswitch and user-defined keys.
Biopsy	To set the needle-guided bracket model and biopsy guide line relevant parameters.
Admin	To set the user account control relevant information.

### 11.1.1 Region

Open the Region page via [Setup]-> [System Preset]-> [Region], as shown in the figure below.

The screenshot shows the 'Setup' application window. On the left is a vertical menu with options: System Preset, Exam Preset, Measure Preset, Comment Preset, BodyMark Preset, Print Preset, Network Preset, DICOM Preset, Maintenance, and About. The main area has tabs: Region (selected), General, Image, Application, Key Config, Biopsy, and Admin. Under the 'Region' tab, there are two sections: 'Hospital Information' and 'Language and Time'. The 'Hospital Information' section contains text boxes for Name, Address, Telephone, Fax, Website, Location, Medical Director, and Associate. To the right of these fields is a logo placeholder with a blue cross and a leaf, and a 'Load Logo' button. The 'Language and Time' section includes a 'Language' dropdown menu set to 'English', a 'Time Zone' dropdown menu set to '(GMT) Greenwich Mean Time: Dublin, Edinburgh, Lisbon, London', 'Date Format' radio buttons for YYYY/MM/DD, MM/DD/YYYY, and DD/MM/YYYY (the last is selected), 'Time Format' radio buttons for 12 Hour and 24 Hour (the last is selected), a 'System Date' field showing '09/07/2018' with a calendar icon, and a 'System Time' field showing '02:05:27' with spin buttons. At the bottom right are 'Save' and 'Cancel' buttons.

Item	Description
Hospital Information	To set the hospital relevant information like name, address, telephone and so on.
Language	To select a language for the system, the available languages are Chinese, English, French, German, Italian, Portuguese, Russian, Spanish, Polish, Czech, Turkish, Finnish, Danish, Icelandic, Norwegian, and Swedish, Indonesian. The system will restart automatically after you change the language and return from the Setup menu.
Time Zone	To select the time zone.
Date Format	To set the date format among DD/MM/YYYY, MM/DD/YYYY and YYYY/MM/DD.
Time Format	To select the time format between 12 Hour and 24 Hour.
System Date	To set the system date. Posit the cursor into the corresponding field, and enter the data through the keyboard; or, click the calendar icon  , and then select the date.
System Time	Enter time to the text box; or modify the time via spin buttons on the right side.



## 11.1.2 General

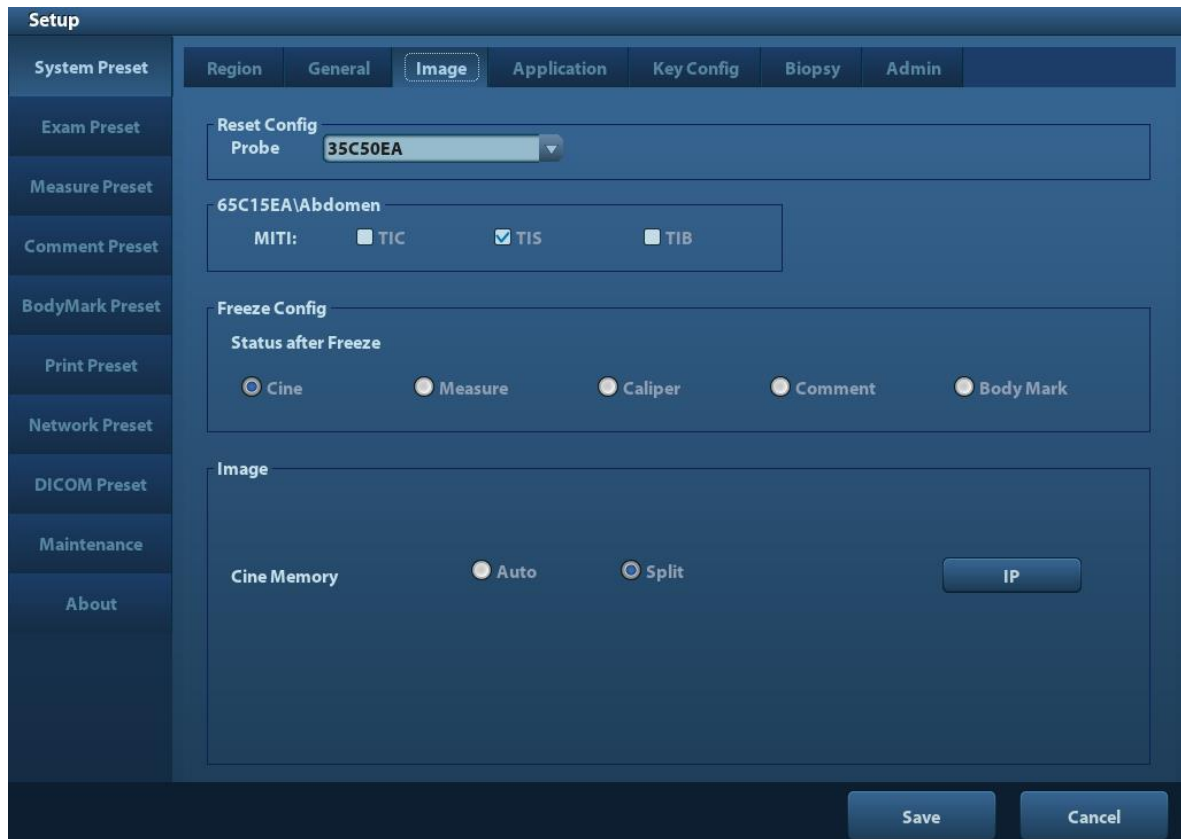
Open the General page via [Setup]-> [System Preset]-> [General], as shown in the figure below.

Type	Item	Description
Animal Info	Patient Banner Display Content	To select if to display the following animal information on the image banner: Gender, Age, Operator, ID, Name, Hospital Name
	H&W Unit	To set the unit for animal height and weight.
Storage	Image Output Size	To set the size for a stored image: Image Area Standard Area Full Screen
	Clip length/ Time (s)	Times: 1~60s
	Output Mode	PAL/ NTSC
Animal Management	Sending/printing after End Exam	Select if to automatically archive the exam data to DICOM server for storage/print.
Screen Saver	Enable ScreenSaver	To enable screen saver function, and select the waiting time until screen saver.
	Enable Standby	Available after "Enable ScreenSaver" is selected.

Type	Item	Description
	Select Picture	After the screen saver function is enabled, click [Browse] to select the figure used for the screen saver and click [Preview] to see the effect.
Exam Setup	Status after exam ends	Select to enter the imaging scanning, animal info or the Worklist after ending an exam.
Display	Color temperature	Cold/ Warm
	Brightness/Contrast Load Factory	Load the factory data of the display brightness and contrast.

### 11.1.3 Image

Open the Image Preset page via [Setup]-> [System Preset]-> [Image], as shown in the figure below.



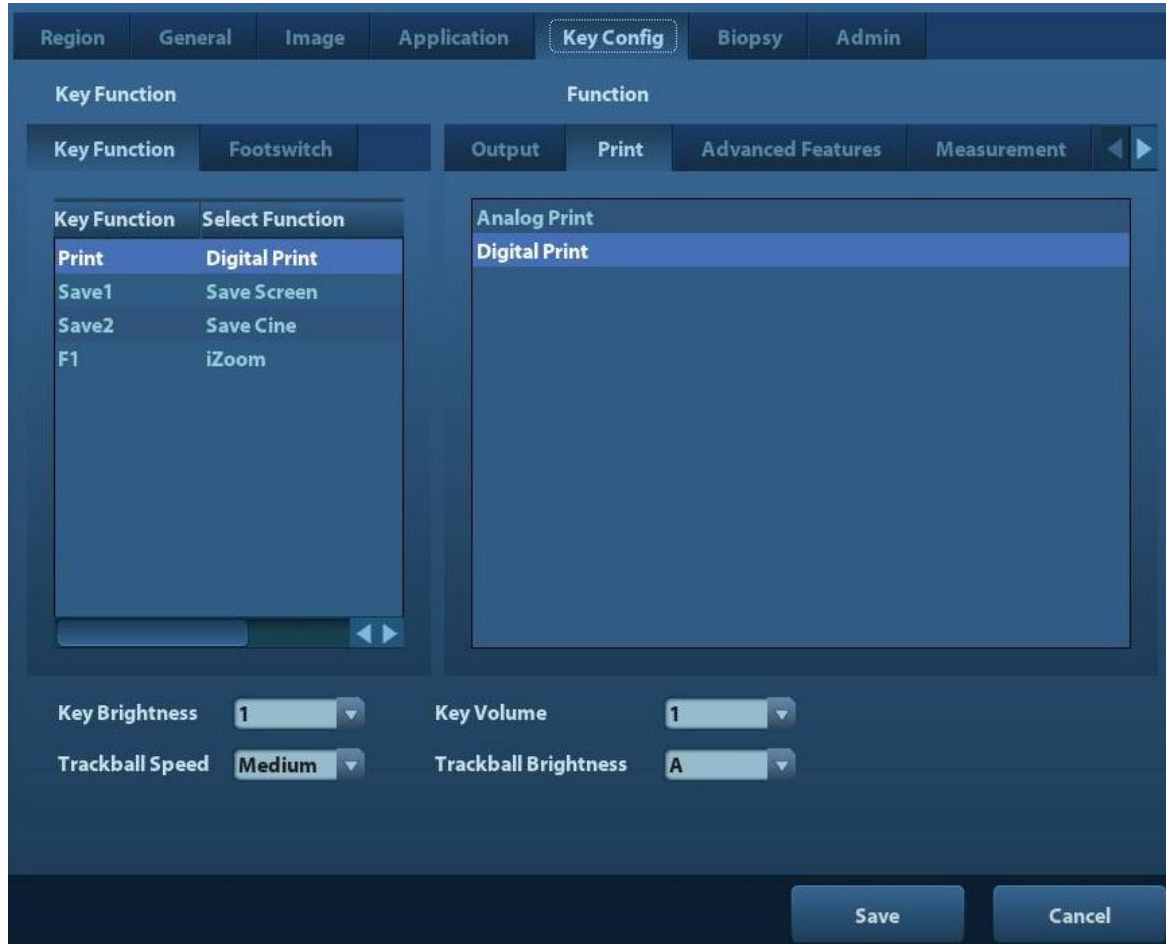
Type	Item	Description
Reset Config	Probe	To set the default probe model for the system.
/	MITI	To set MI TI indexes displayed for current probe/exam mode.
Freeze Config	Status after Freeze	To set the system status after the image is frozen.
Image	Cine Memory	To set the cine memory splitting type: Auto, Split.
	IP	To set the image parameters

## 11.1.4 Application

Open the Application page via [Setup]-> [System Preset]-> [Application]. Through the page, you can set the measure ruler, follicle and relevant information. For details, please refer to the Operator's Manual [Advanced Volume]

## 11.1.5 Key Config

Open the page via [Setup]-> [System Preset]-> [Key Config], as shown in the figure below.



### ■ Key function setting

You can set the functions for <Print>, <Save1>, <Save2>, F-key (F1) and footswitch.

To assign a function to a key:

- (1) Click to select the desired key in the Key Function column at the left side of the page.
- (2) Click to select a function in Function area. You can see the functions selected at the right side of the select key.
- (3) Click [Save] to complete function setting.

The following introduces an example as setting <Print> as "Send Image to USB disk":

- (1) Select "Print" in the "Key Function" list at the left side of the page.
- (2) Select "Send Image to USB disk" in "Function" at the right side of the page.

(3) Click [Save] to complete the setting.

■ Other Settings

Item	Description
Key Brightness	To set the blightness for the keys.
Key Volume	To set the key volume.
Trackball Speed	To set the trackball speed when move the trackball.
Trackball Brightness	To set the color for the trackball.

## 11.1.6 Biopsy

Open the Biopsy page via [Setup]-> [System Preset]-> [Biopsy].

■ Bracket

To select the default needle-guided bracket for the probe.

■ Parameter

Press to display the biopsy guideline.

## 11.1.7 Admin

Open the Admin page via [Setup]-> [System Preset]-> [Admin].

For details of access control, please refer to “9.7 Access Control”.

## 11.2 Exam Preset

Open [Setup]-> [Exam Preset] to enter Exam Preset screen.

Procedures:

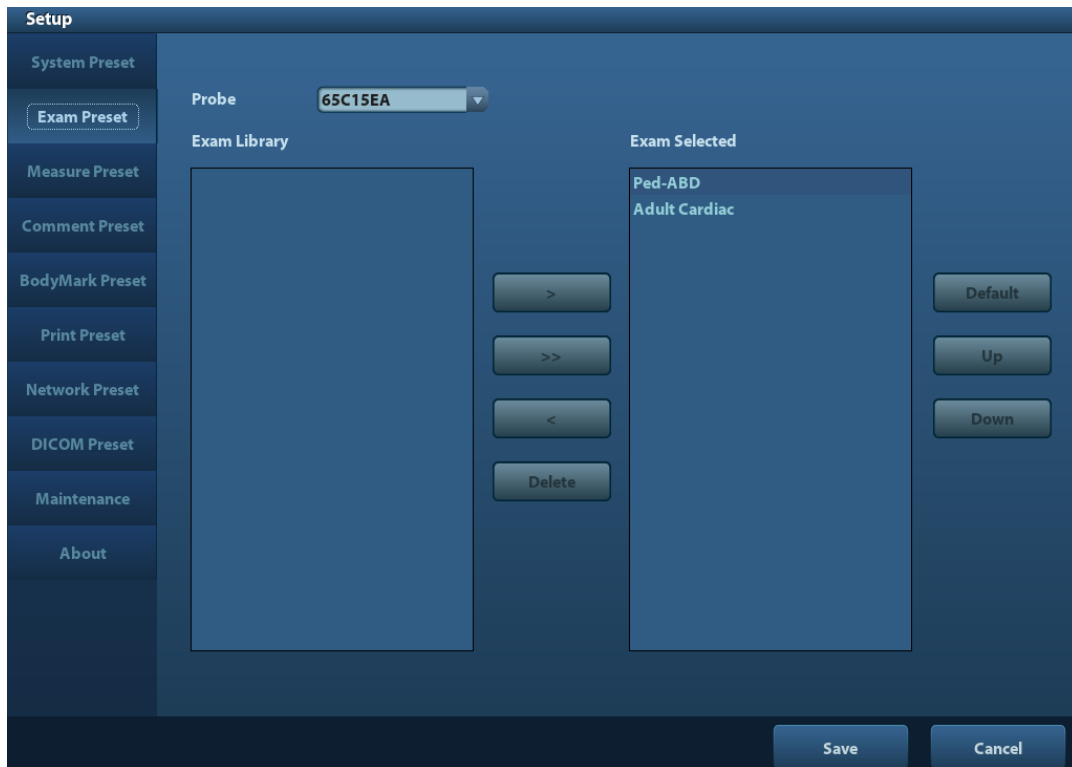
1. Selecting a probe:

Move the cursor to [Probe], and select a probe from the drop-down list.

2. Selecting/deleting exam modes

On the right side of the screen, you can view the exam types supported by the current probe. On the left side, you can view all the exam modes supported by the system, i.e., Exam Library.

- [>]: add a selected exam mode in the [Exam Library] to the [Exam Selected] list.
  - [>>]: add all exam modes in the library to the [Exam Selected] list.
  - [<]: remove an exam mode selected from the [Exam Selected] list.
  - Click [Up] and [Down] to adjust the sequence of the items in Selected Items.
  - Click [Default] to set a selected exam mode as the default exam mode.
3. Click [Save] to confirm the modified setup; or click [Cancel] to cancel the modified settings.



## 11.3 Measure Preset

For measurements details, please refer to the Advanced Volume.

## 11.4 Body Mark Preset

In order to accommodate your workflow – numerous preferential settings can be captured in Body Mark Preset. This function is to preset, body marks in each exam type, or user-defined body marks.

### 11.4.1 Preset Body Mark for Exam Mode

Enter [Setup]-> [Bodymark Preset] (as shown in the figure below).



#### Procedures:

1. Select an exam mode in the drop-down list, the current exam mode is set by default.
2. Enter the library name of custom body marks.
3. Select a package from the drop-down list besides Available Item.
4. Add or delete body mark(s)
  - [>] To add the item selected from the [Available Items] into the [Selected Items].
  - [>>] To add all items from the [Available Items] into the [Selected Items].
  - [<] To remove the selected item in [Selected Items] to the [Available Items].
  - [<<] To remove all items from the [Selected Items].
5. Click [Up] and [Down]: to adjust the sequence of the items in Selected Items.
6. Preset the probe mark of the selected body mark in Selected Items
 

Move the cursor onto the probe mark of the body mark in Probe area and press <Set> to make the cursor turn green. Roll the trackball to change the position of the probe, rotate the multifunctional knob to change the angle, and press <Set> to confirm the orientation of the probe.
7. Select the body mark in Selected Items and click [Default], and then the body mark will be marked with a tick "√".
8. Click [Save] to complete the setting.

## 11.5 Comment Preset

You can preset the custom comments library for each exam mode to your preference.

## 11.5.1 Custom Comments

You can preset the custom comments library for each exam mode to your preference. The comments in the library are provided by the system or user-defined ones. The name of the library, which can be set, will appear on the first page of the library.

Open the Comment page via [Setup]-> [Comment Preset].



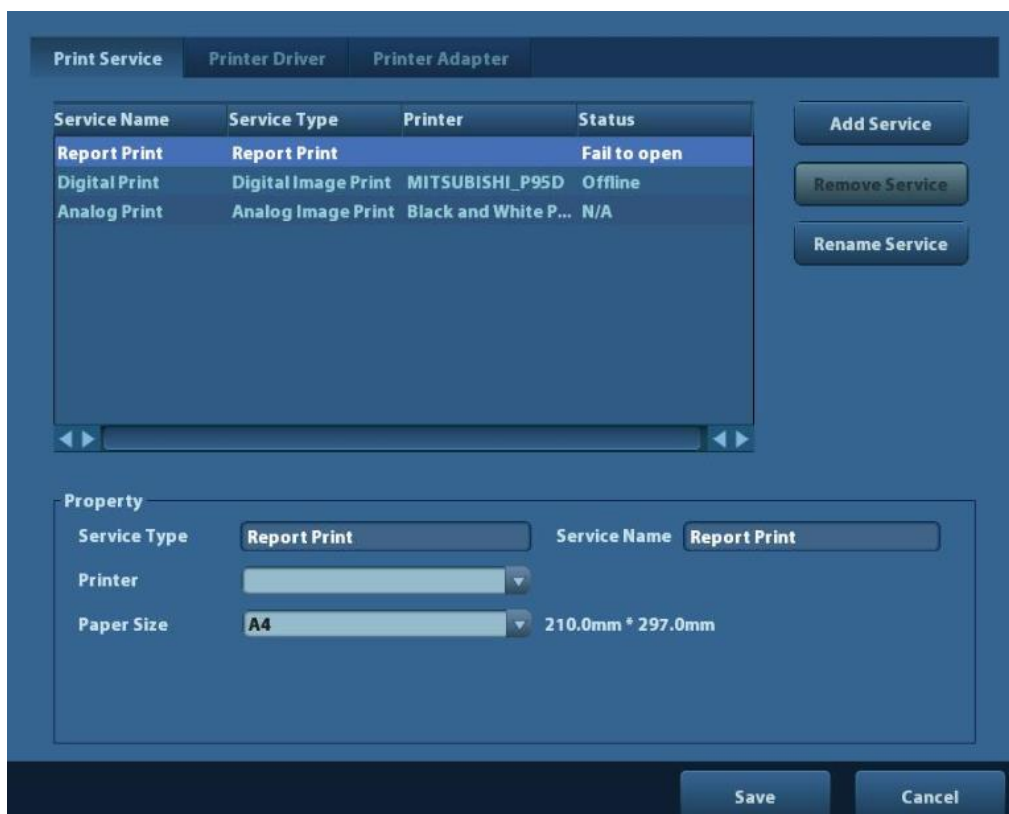
Procedures:

1. Select an exam mode.
2. Enter Library Name: you can enter characters for the library name, or accept the default name (the same as that for the exam mode).
3. Select an available item.
4. Add user-defined comments: directly enter comment texts, or select comment texts for the comment library.
  - Directly enter comment texts: posit the cursor in the field box above [Add Comment], enter the text comment through the keyboard, and then click [Add Comment]. Then the directly-entered comment will be added to the Available Items and Selected Items.
  - Select Available Items: First select a comment library in the drop-down list beside "Available Items", and then click [Set] on one item displayed below "Available Items".
    - Click [>] to add the item in Available Items on the left into Selected Items on the right.
    - Click [>>] to add all items in Available Items on the left into Selected Items on the right.
5. Change position of the selected items: select an item on the right side box and click [Up], [Down], [Left] or [Right] button to change the position of the item.
6. Delete comments:

- Remove item (from the library or user-defined) in the Selected Items list:  
Select an item in Selected Items list, and click [-] to remove it to the Available Items list.  
Click [->] to remove all items in Selected Items.
  - Delete a user-defined item in the Available Items box. You can only delete the user-defined items rather than the items in the system library. After a user-defined item is deleted, it will not be available.  
Select a user-defined item in the Available Items box, and click [Delete]. After the user-defined item in the Available Items box is deleted, the same item in the Selected Items box on the right will disappear as well.
7. After you customize comments, click [Save] to confirm and exit the [Comment Preset] screen.

## 11.6 Print Preset

The settings of a printer include print service, print driver and printer adapter .



- Print Service Setting
  - Add Service: click to add a service.
  - Remove Service: click to delete the selected print service.
  - Rename Service: click to rename the selected print service.
  - Property: to preset the property of print services.
- Printer Driver Setting
 

Printers listed in the operator's manual are all supported by the system, no drive is required.

Click [Print Driver] page to enter printer driver setting screen:

  - Display the printer name as well as print status.



- You can add a printer including a network printer, or delete a printer.
- Check the printer attribute.  
For details about DICOM print, please refer to “10 DICOM”.
- Printer Adapter  
For details, please refer to the “Appendix D Printer Adapter”

## 11.7 Network Preset

For Local TCP/IP preset and DICOM preset, please refer to “10.1 DICOM Preset”.

### 11.7.1 iStorage Preset

The iStorage screen is as follows:

Name	Description
Service Name	Name of the device, which cannot be empty
Port	Port for transmitting.
IP Address	IP address of the PC installed with iStorage software, which cannot be empty
Connect	Click to verify connection with the PC server. On PC server, if the storage path has not been confirmed, a dialog box will pop up and guide the user to set it. If the storage path on PC has already been set, the system displays a successful connection message after clicking this button.
Add	Click it to add the new service to the service list.
Update	Click to save the changed parameters.
Delete	Click to delete the selected service in the service list.
Default	Click to set a selected item in the list as the default iStorage server.

Name	Description
Save	Click to save and exit the screen.

■ Add a network service:

1. Set the network server properties as described above.
2. Click [Add] to add the service to the Service list;
3. You can select and then delete a newly added service in the service list.

■ Modify a network service:

1. Select the service to be updated in the service list.
2. You can see properties in the Configure Service area.
3. Modify the parameters and click [Update] to update the setting.

Tips: in order to make network storage function normally, you must set the sharing folder of the PC server in advance, e.g. machine name, IP address, should be confirmed at first. You can send the image to the iStorage by user-defined key. For details, please refer to “11.1.5 Key Config”.

You can send exam data of images to iStorage server by UltraAssist. For details about this feature, please refer to the UltraAssist manual.

## 11.7.2 MedSight Preset

You can set environment for MedSight here and then use the MedSight function by mobile phone or tablet computers. See MedSight manual for details.

## 11.8 Maintenance

In the Setup menu, select [Maintenance] enter the screen.

### 11.8.1 Option

The system enters Option page after you enter the Maintenance screen. In Option list, the system lists out all the system supported options and the installation status (Not installed or Installed).

■ Install and uninstall

- Click [Install] to begin the installation of a disabled option.
- Click [Uninstall] to begin the un-installation of an already installed option.

■ Trial

Select the option item in the list to see the information on the Comment region on the right. For functions that are not configured, you can use the function for free for 3 months.

- Click to select the function(s) and click [Trial].

Tips: Every trial option can be used only once. Please refer to the dependence relationship between options in chapter “2.5.3 Options”.

Please contact Mindray Customer Service Department or sales representative for details.

## 11.8.2 Other Settings

Type	Item	Description
Preset Manager	Load Factory	Local factory default settings.
	Export	Export preset data to disk.
	Import	Import the preset data into the system.
Other	Export Log	Export the operation log.
	Prepay Installment	Display the prepay installment information.

## 11.9 System Information

Click [About] in the Setup menu to enter the system information screen. (The information varies depending upon the system configurations and version.)

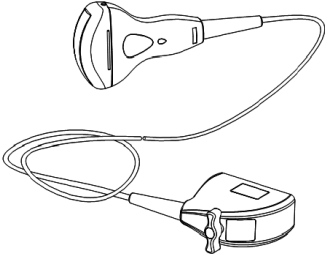

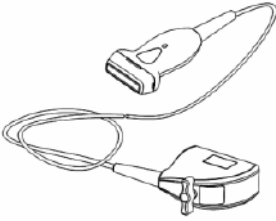
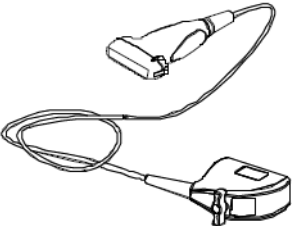
- About  
Product name, manufacture and other information are displayed.
- About Detail  
Version information about the software, hardware and other modules are displayed.


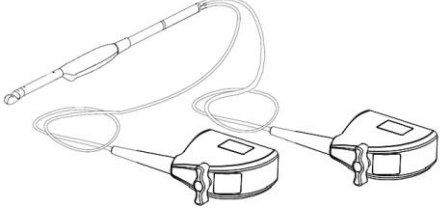
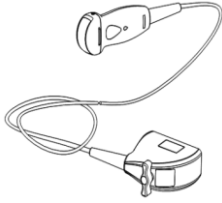
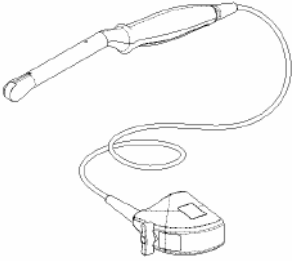
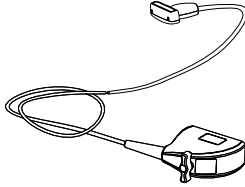
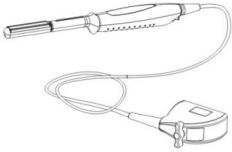


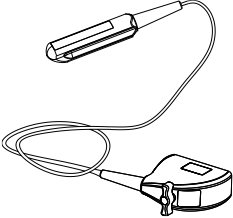
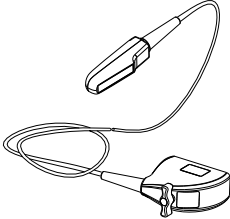
# 12 Probes and Biopsy

## 12.1 Probe

The system supports the following probes:

No.	Probe Model	Probe Type	Illustration
1.	35C50EA	Convex	
2.	65C15EA	Convex	
3.	75L38EA	Linear array	
4.	75L53EA	Linear array	

No.	Probe Model	Probe Type	Illustration
5.	10L24EA	Linear array	
6.	65EB10EA	Convex	
7.	35C20EA	Convex	
8.	65EC10ED	Convex	
9.	75LT38EA	Linear array	
10.	65EL60EA	Linear array	

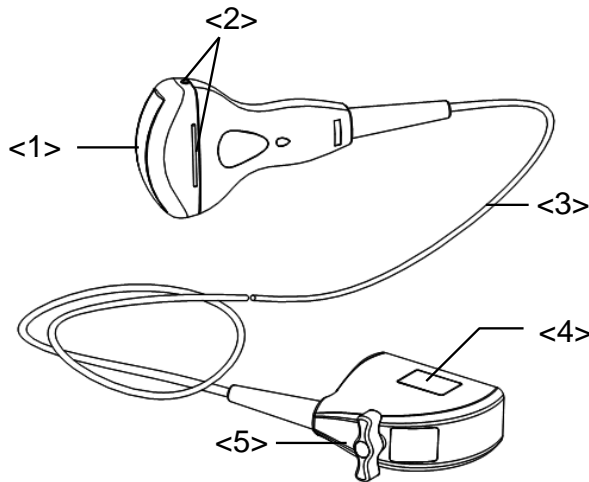
No.	Probe Model	Probe Type	Illustration
11.	50L60EAV	Linear	
12.	75L50EAV	Linear	

**Note:** For details of storage time and condition for disinfected probes or sterilized probes and brackets, please refer to Technical standard for Disinfection of Medical and Health Structures

### 12.1.1 Name and Function of Each Part of the Transducer

Basic structures and functions of all probes listed above are similar, and are described as follows.

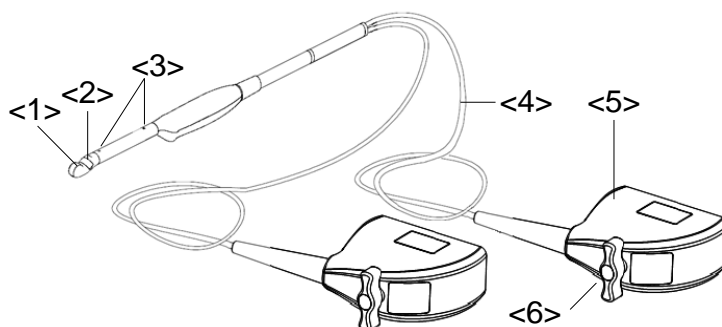
- Probe 35C50EA



No.	Name	Function
<1>	Transducer head	It converts the electrical signal into ultrasound signal, making the sound beams focus in the given direction; meanwhile, it will receive the ultrasound signal and then convert the received signal into electrical signal. The lens on the surface is the acoustic lens. Apply ultrasound gel on the acoustic lens.
<2>	Needle-guided bracket fix tabs and grooves	Used to mount the needle-guided bracket.
<3>	Transducer cable	Used to transmit electrical signals between the transducer body and connector.
<4>	Transducer connector	Used to connect the transducer to the ultrasonic diagnostic system.
<5>	Lock handle	This locks the connector to the ultrasonic diagnostic system.

The probes' structure marked <2> in the figure above may vary with the matched needle-guided brackets.

■ Probe 65EB10EA

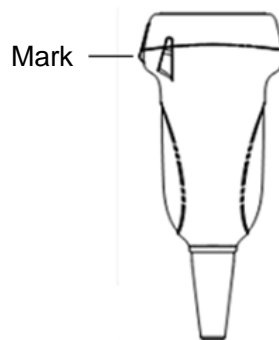
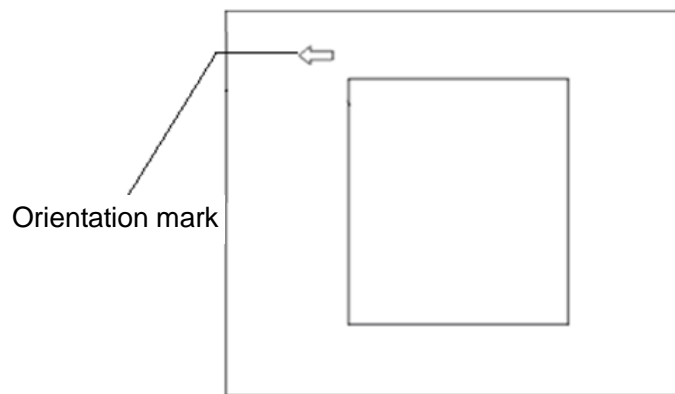


No.	Name	Function
<1>	<1>Transducer head (convex, vertical section)	It utilizes the piezoelectric effect to convert electrical signals into ultrasound waves, which are transmitted to the body, and to generate electrical signals when receiving the reflected ultrasound waves (echoes).The lens on the surface is the acoustic lens. Apply ultrasound gel on the acoustic lens.
<2>	<2>Transducer head (convex, horizontal section)	
<3>	Locating groove	Mount the needle-guided bracket.
<4>	Cable	This transmits electrical signals between the transducer body and connector.
<5>	Connector	This connects the transducer to the ultrasonic diagnostic system.
<6>	Lock handle	This locks the connector to the ultrasonic diagnostic system.



## 12.1.2 Orientation of the Ultrasound Image and the Transducer Head

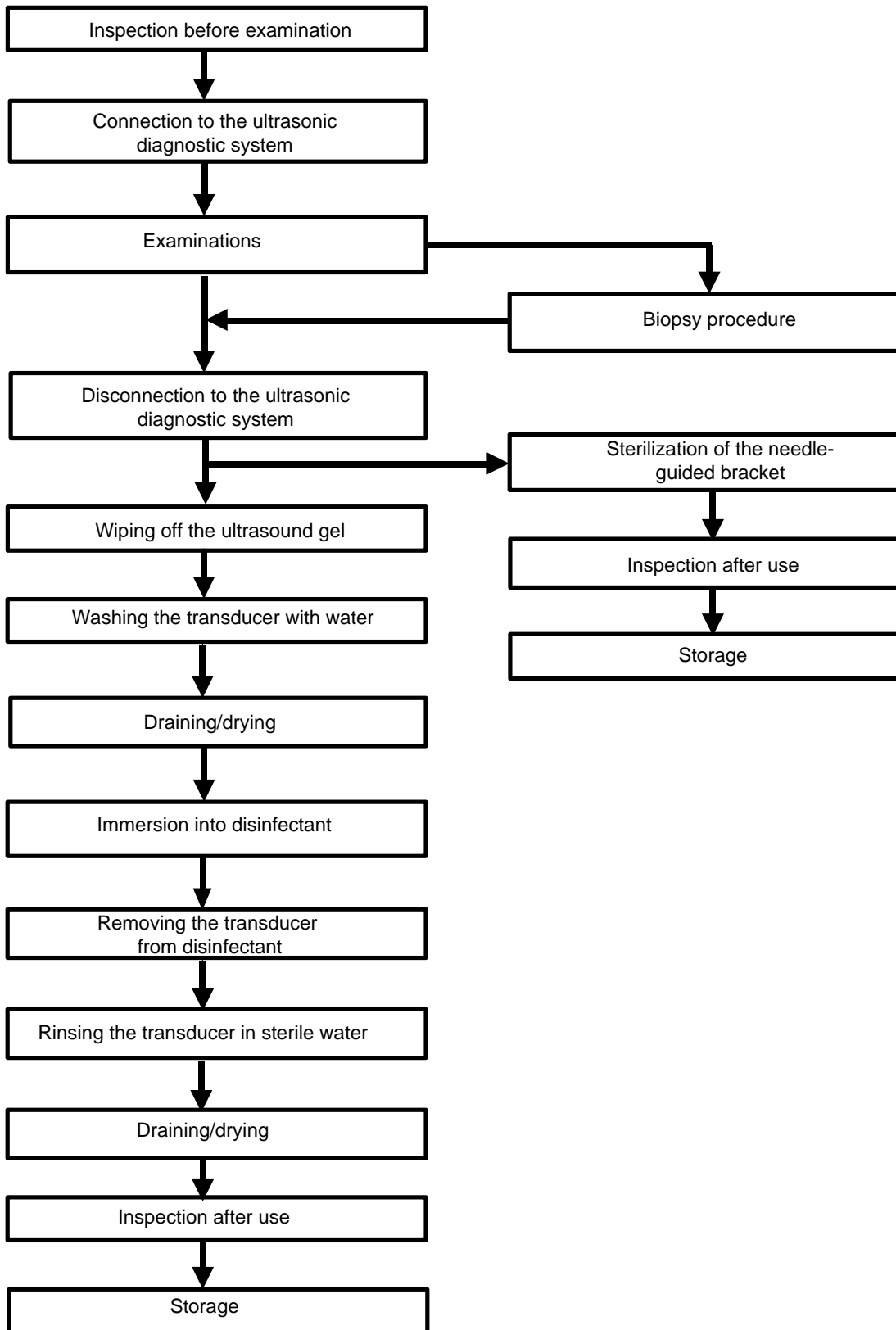
The orientation of the ultrasound image and the transducer are shown below. The “MARK” side of the ultrasound image on the monitor corresponds to the mark side of the transducer. Check the orientation before the examination (take linear probe as an example).



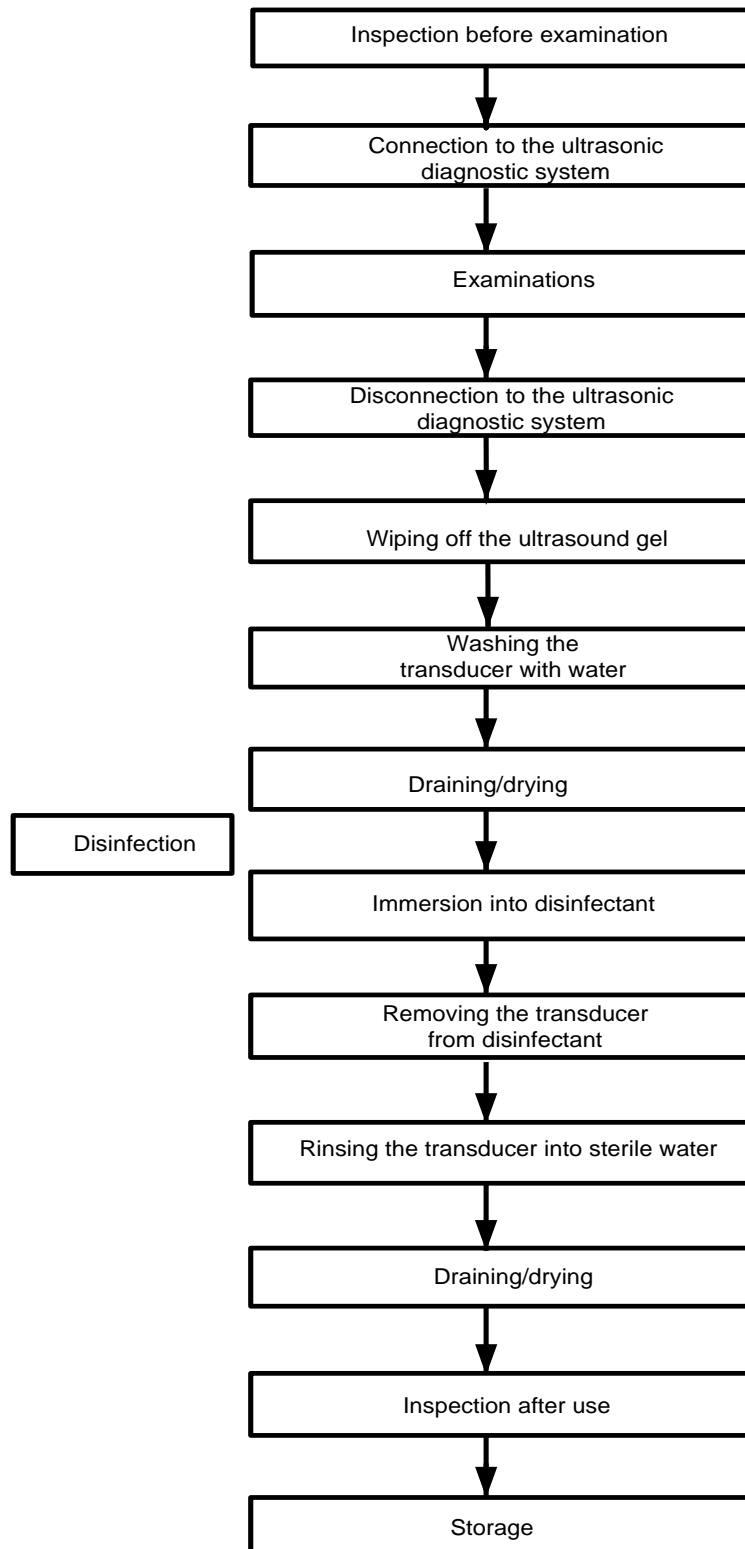
## 12.1.3 Operating Procedures

This section describes general procedures for operating the transducer. The proper clinical technique to be used for operating the transducer should be selected on the basis of specialized training and clinical experience.

■ Procedures for operating (with biopsy function)



■ Procedures for operating (with no biopsy function)



**⚠ WARNING:** Disinfect the probe and sterilize the needle-guided bracket before and after an ultrasound-guided biopsy procedure is performed. Failure to do so may cause the probe and the needle-guided bracket become source of infection.

## 12.1.4 Utilizing the Transducer Sheath

A transducer sheath must be installed over the transducer before performing examination. Probe sheaths are available for use with all clinical situations where infection is a concern.

A probe sheath must be installed over the probe before performing intra-cavity or biopsy examination. Use a commercially available transducer sheath.

To order transducer sheath, contact:

CIVCO Medical Instruments Co.

102 First Street South, Kalona, IA 52247-9589 USA Tel: 1-319-656-4447

E-mail: [info@civco.com](mailto:info@civco.com)

<http://www.civco.com>

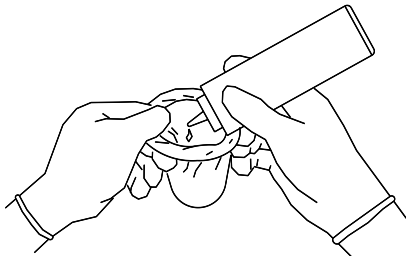


### CAUTION:

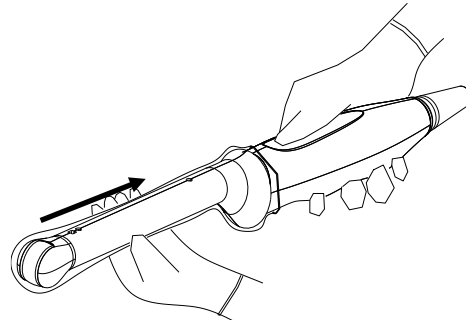
1. Be sure to cover the probe with a new (unused) probe sheath to prevent infection during examination. If the package of a probe sheath is open or broken, the sterilization of the probe sheath may not be sufficient. **DO NOT** use such a probe sheath.
2. The cover contains natural rubber latex and talc that can cause allergic reactions in some individuals.
3. **DO NOT** use an expired probe sheath. Before using probe sheaths, verify whether the term of validity has expired.

Method (for reference only):

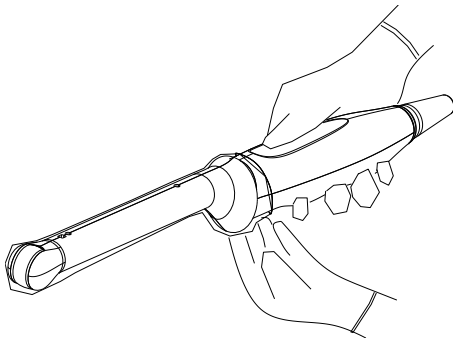
1. Place an appropriate amount of gel inside the sheath or on transducer face. Poor imaging may result if no gel is used



2. Insert the transducer into sheath making sure to use proper sterile technique. Pull cover tightly over transducer face to remove wrinkles and air bubbles, taking care to avoid puncturing cover.



3. Secure the sheath with enclosed elastic bands.



4. Inspect the sheath to ensure there are no holes or tears.


## 12.1.5 Probes Cleaning and Disinfection

After completing each examination, clean and disinfect (or sterilize) the probes as required. When biopsy procedures have been performed, be sure to sterilize the needle-guided bracket. Fail to do so may result in the probe and the needle-guided bracket to becoming sources of infection. Please follow the instructions in the manual for cleaning.

**⚠ WARNING:** Never immerse the probe connector into liquid such as water or disinfectant. Immersion may cause electrical shock or malfunction.

**⚠ CAUTION:**

1. When performing cleaning and disinfection of the probe to prevent infection, wear sterile gloves.
2. After disinfection, rinse the probe thoroughly with sterile water to remove all chemical residues. Chemical residues on the probe may be harmful to the human body.
3. No cleaning and disinfecting may result in the probe becoming a source of infection.



**NOTE:**

1. After the examination, wipe off the ultrasound gel thoroughly. Otherwise, the ultrasound gel may solidify and degrade the image quality of the transducer.
2. DO NOT make the probe to become overheated (more than 55°C) during cleaning and disinfections. High temperature may cause the probe to become deformed or damaged.

### Cleaning

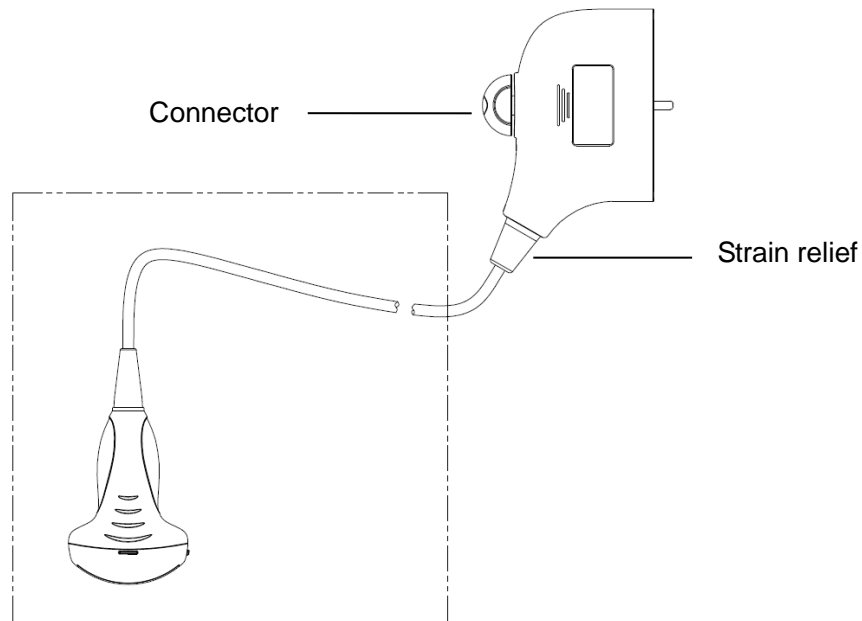
Please refer to the instructions in the manual and follow your hospital policy and procedures for cleaning.

1. Disconnect the probe from the system.
2. Wear sterile gloves to prevent infection.
3. Wash the transducer with clean water or soapy water to remove all the foreign matters, or, wipe the transducer with a soft ethyl carbamate sponge. Avoid using a brush, because it may damage the transducer.
4. Dry the transducer using a sterile cloth or gauze after rinsing. Do not dry the transducer by heating it.

### Disinfecting with Sprays

**⚠ CAUTION:** Use protective eyewear when disinfecting using sprays.

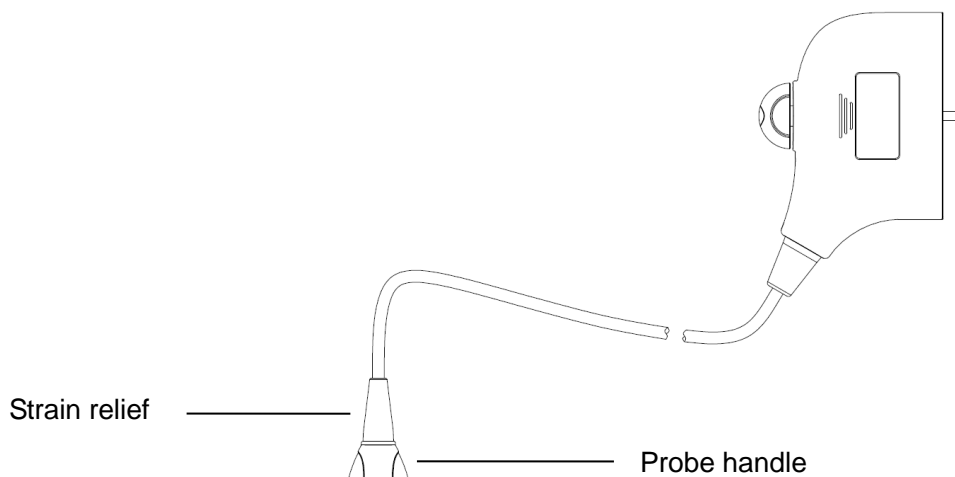
1. Wear sterile gloves to prevent infection.
2. After you have finished cleaning, spray the transducer with a disinfectant. Follow the disinfectant manufacturer's recommended contact time and mode.
3. Remove any residue with a water-moistened soft cloth on the transducer.
4. Wipe off water on the transducer using sterile cloth or gauze after washing.



**NOTE:** Observe the graph here carefully to perform disinfection. Do not spray the strain relief on the connector end or the connector.

### Disinfecting by Immersion

1. Wear sterile gloves to prevent infection.
2. Clean the transducer before disinfecting it. MINDRAY recommends the following solutions to disinfect the transducer.
  - Refer to the instructions provided by the chemical manufacturer concerning concentration of the disinfectant solution, method of disinfection and dilution and cautions during use. Do not soak the transducer connector or the cable near it into water or any solution.
  - Soak the transducer into the disinfectant solution for the shortest time the manufacturer recommends (for example, the shortest time recommended by the manufacturer for soaking Cidex OPA is 12 minutes).
  - Follow local regulations when selecting and using the disinfectant.
3. Rinse the transducer with plenty of sterile water (about 2 gallons) for at least 1 minute to remove all chemical residues on it. Or, follow the rinsing method recommended by the disinfectant manufacturer to rinse the transducer.
4. Wipe off the water on the transducer with sterile cloth or gauze after rinsing it. Do not dry the transducer by heating.



**NOTE:**

1. Observe the graph here carefully to immerse the transducer. Only soak parts of the transducer below the strain relief.
2. Repeated disinfection will eventually damage the probe, please check the probe performance periodically.

**Compatible Disinfectants**

Please see Mindray Transducer Disinfectant Recommendation for the disinfectant use in details.

**Sterilization**

For intra-operative probes (75LT38EA), they have to be sterilized after completing each examination.

1. Wear sterile gloves to prevent infection.
2. Clean the probe before sterilizing it. MINDRAY recommends the following solutions to sterilize the probe.

Hydrogen Peroxide and Peroxyacetic Acid -based sterilization solution

Trade Name	Chemical Name	Procedures
Minnicare® Cold Sterilant	22% Hydrogen Peroxide 4.5% Peroxyacetic Acid	Dilute the sterilant with sterilized purified water (1:20). Immersed time: 11 hours. Temperature: 20°C-25°C. Please refer to the instructions provided by the manufacturer of the solution for details.

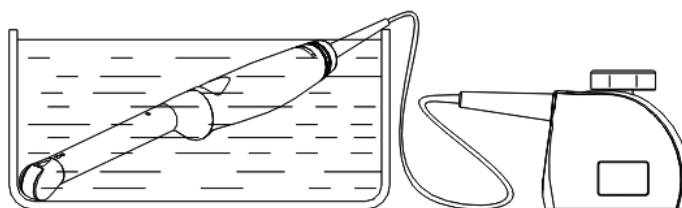
Before safety and performance is affected, probe 75LT38EA can be sterilized by Minncare COLD STERILANT for at least 135 times (11 hours for one time).

Glutaraldehyde-based sterilization solution

Trade Name	Chemical Name	Procedures
Cidex Activated Glutaraldehyde Solution	2.2-2.7% Glutaraldehyde	Soak the transducer into the activated solution for 10 hours (20-25°C) Please refer to the instructions provided by the manufacturer of the solution for details.

Before safety and performance is affected, probe 75LT38EA can be sterilized by Cidex Activated Glutaraldehyde Solution for at least 217 times (10 hours for one time).

- Refer to the instructions provided by the chemical manufacturer concerning concentration of the sterilization solution, method of sterilization and dilution and cautions during use.
  - Do not soak the probe connector or the cable near it into water or any solution.
  - Follow local regulations when selecting and using the sterilization solution.
3. Rinse the probe with plenty of sterile water (about 2 gallons) for at least 1 minute to remove all chemical residues on it. Or, follow the rinsing method recommended by the sterilization solution manufacturer to rinse the probe.
  4. Wipe off the water on the probe with sterile cloth or gauze after rinsing it. Do not dry the probe by heating.



Immerse the probe 75LT38EA in the solution

**NOTE:** Repeated disinfection may degrade the performance and safety of the probe.

## 12.1.6 Environment

### Working condition

Use the probes in the following ambient conditions:

Probe	Ambient temperature	Relative humidity	Atmospheric pressure
35C50EA	0-40°C	30%-85%RH (no condensation)	700-1060hPa
65C15EA	0°C-40°C	30%~85%RH (no condensation)	700 hPa ~ 1060 hPa
65EB10EA	0°C~40°C	30%~90%RH (no condensation)	700hPa~1060hPa
75L38EA	0°C-40°C	30%~85%RH (no condensation)	700 hPa ~ 1060 hPa
75L53EA	0°C~40°C	30%~85%RH (no condensation)	700hPa~1060hPa
10L24EA	0°C~40°C	30%~90%RH (no condensation)	700hPa~1060hPa
35C20EA	0°C-40°C	30%~85%RH (no condensation)	700 hPa ~ 1060 hPa



Probe	Ambient temperature	Relative humidity	Atmospheric pressure
65EC10ED	0°C~40°C	30%~90%RH (no condensation)	700hPa~1060hPa
75LT38EA	0°C~40°C	30%~85%RH (no condensation)	700hPa~1060hPa
65EL60EA	0°C-40°C	30%~85%RH (no condensation)	700 hPa ~ 1060 hPa
50L60EAV	0°C-40°C	30%~85%RH (no condensation)	700 hPa ~ 1060 hPa
75L50EAV	0°C-40°C	30%~85%RH (no condensation)	700 hPa ~ 1060 hPa

### Storage and transportation Condition

When all examinations for the session have been completed, confirm that the probe is in good condition. After disinfecting the probe, confirm that the probe is in good condition and stored in a suitable place.

Store and transport the probes in the following ambient conditions:

Probe	Ambient temperature	Relative humidity	Atmospheric pressure
35C50EA	-20°C~55°C	30%~95%RH (no condensation)	700 hPa ~ 1060 hPa
65C15EA	-20°C~55°C	30%~95%RH (no condensation)	700 hPa ~ 1060 hPa
65EB10EA	-20°C~55°C	30%~95%RH (no condensation)	700 hPa ~ 1060 hPa
75L38EA	-20°C~55°C	30%~95%RH (no condensation)	700 hPa ~ 1060 hPa
75L53EA	-20°C~55°C	30%~95%RH (no condensation)	700 hPa ~ 1060 hPa
10L24EA	-20°C~55°C	30%~95%RH (no condensation)	700 hPa ~ 1060 hPa
35C20EA	-20°C~55°C	30%~95%RH (no condensation)	700 hPa ~ 1060 hPa
65EC10ED	-20°C~55°C	30%~95%RH (no condensation)	700 hPa ~ 1060 hPa
75LT38EA	-20°C~55°C	30%~95%RH (no condensation)	700 hPa ~ 1060 hPa
65EL60EA	-20°C~55°C	30%~95%RH (no condensation)	700 hPa ~ 1060 hPa

Probe	Ambient temperature	Relative humidity	Atmospheric pressure
50L60EAV	-20°C ~ 55°C	30%~95%RH (no condensation)	700 hPa ~ 1060 hPa
75L50EAV	-20°C ~ 55°C	30%~95%RH (no condensation)	700 hPa ~ 1060 hPa

- To prevent the probe from being damaged, DO NOT store it where it may be exposed to:
  - Direct sunlight or X-rays
  - Sudden changes in temperature
  - Dust
  - Excessive vibration
  - Heat generators
- When the probe is sent to the MINDRAY Customer Service Department or a sales representative for repair, be sure to disinfect it and keep it in the carrying case to prevent infection.
- Sterilize the carrying case as necessary.

## 12.2 Biopsy Guide

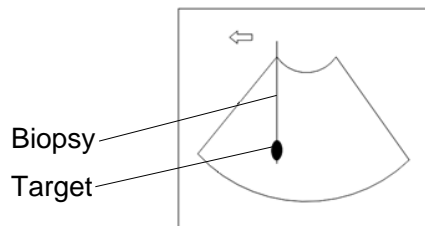
### WARNING:

- The person performing biopsy procedures must understand diagnostic ultrasound thoroughly and have been trained adequately, otherwise, side effects may be caused in the animal.
- In situations listed below, the biopsy needle may fail to penetrate the target. The incorrect biopsy may cause various side effects in the animal.
  - Use a needle-guided bracket that doesn't match with the transducer.
  - Mounts the needle-guided bracket incorrectly.
  - Use a biopsy needle that is unsuitable for the type of biopsy being performed.
  - Use a biopsy needle that is unsuitable for the type of biopsy being performed.
- Before and after a biopsy procedure is performed, confirm that the needle-guided bracket is normal. Manually confirm that the parts of the needle-guided bracket do not slip off or move from their proper positions. If the needle-guided bracket is used when parts are not securely and correctly installed, the animal may be injured. If an abnormality is found on the needle-guided bracket, immediately stop using it and contact MINDRAY Customer Service Department or sales representative.

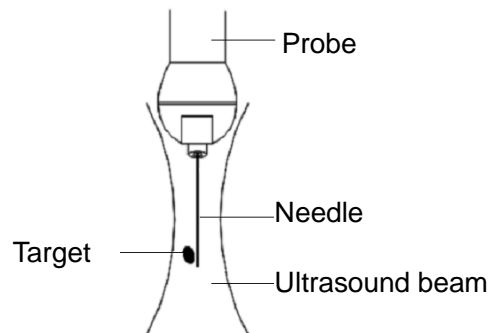
4. Do not use a needle-guided bracket when scanning is performed. The needle may advance in an incorrect direction and possibly injure the animal. Never perform a biopsy during image scanning.
5. Do not freeze an image while performing biopsy procedure.
6. During biopsy procedures, the needle may deviate from the desired course due to the tissue characteristics or the type of needle. In particular, needles of small diameters may deviate to a greater degree.
7. Sterilize the transducer and the needle-guided bracket before and after each ultrasound-guided biopsy procedure is performed. Fail to do so may cause the transducer and the needle-guided bracket become sources of infection.
8. The needle mark displayed on the ultrasound image does not indicate the actual position of the biopsy needle. Therefore, it should only be used as a reference. Always monitor the relative positions of the biopsy needle during the procedures.
9. Adjust the needle mark before the biopsy procedure is performed.
10. When performing biopsy procedures, use only sterile ultrasound gel that is certified to be safe. And manage the ultrasound gel properly to ensure that it does not become a source of infection.
11. When performing the operation concerning biopsy, wear sterile gloves.

12. Image of the biopsy target and the actual position of the biopsy needle:

*Diagnostic ultrasound systems produce tomographic plane images with information of a certain thickness in the thickness direction of the transducer. (That is to say, the information shown in the images consist all the information scanned in the thickness direction of the transducer.) So, even though the biopsy needle appears to have penetrated the target object in the image, it may not actually have done so. When the target for biopsy is small, dispersion of the ultrasound beam may lead to image deviate from the actual position. Pay attention to this. Image deviation is shown as the figures below:*



The biopsy needle appears to reach the target object in the image



**Dispersion of the ultrasound beam**

*To avoid this problem, note points below:*

Do not rely only on the echo of the needle tip on the image. Pay careful attention to the target object, which should shift slightly when the biopsy needle comes into contact with it.

Before you perform the biopsy, please evaluate the size of the object and confirm if the biopsy can be carried out successfully.

**⚠ CAUTION:**

1. When using the needle-guided bracket wear sterile gloves to prevent infection.
2. During biopsy of the probe 65EB10EA, misoperation may occur when the scan range is not set to "W", which will affect the blind area of the image and the accuracy of needle displaying. The scan range should be kept to "W".

## 12.2.1 Basic Procedures for Biopsy Guiding

1. Select the right needle-guided bracket and needle, install them properly.  
Before biopsy guiding, you can preset bracket model, biopsy display and guide line dot type. For details, please refer to “12.2.3 Biopsy Preset”.
2. Verify the biopsy guide line. For details, please refer to “12.2.5 Biopsy Menu”.
3. Press <Biopsy> on the control panel.
  - If the current probe has no matched bracket; or, the image is frozen and the guide line is hidden before image frozen, then you can't enter Biopsy menu.
  - Before entering Biopsy menu, the system will prompt you “Please verify guidelines before biopsy”.
4. Set [Display] as “On” to display the guide line, select the bracket and guide line according to actual situation. For details, please refer to “12.2.5 Biopsy Menu”.
5. On the Biopsy menu, click [Verify] to enter the Verify menu to verify the guide line. After the verification, click [Save] on the menu to save the parameter setting. And then click [Exit] to return to Biopsy menu.

Note:

- If you switch the probe or needle-guided bracket during the biopsy, please verify the guide line again.
  - When exit the Biopsy Verify menu without saving the setting, system will confirm with you “Data have changed. Do you want to save the changes?”, Click [OK] to save the setting and return to Biopsy menu. Click [OK] to save the setting and return to biopsy menu.
6. Scan to locate the target. Center the target in the electronic guidezone path.
  7. Direct the needle into the area of interest for specimen.
  8. After extraction of the biopsy sample is completed, gently remove the probe from the body. To exit Biopsy menu: press <Esc>; or, navigate the cursor onto the Other menu.
  9. Disassemble the items and properly dispose of these items as required.



### **DANGER:**

**Fail to match the guidezone displayed to the guide may cause the needle to track a path outside the zone.**

**It is extremely important that when using the adjustable angle biopsy guides, the angle displayed on the screen matches the angle set on the guide, otherwise the needle will not follow the displayed guidezone which could result in repeated biopsies or animal injury.**

## 12.2.2 Needle-guided Brackets

A needle-guided bracket is available for purchase as an optional accessory; it is used in combination with this transducer. Part of the probes have matched needle-guided bracket and needles. To order needle-guided brackets, contact MINDRAY Customer Service Department or sales representative.

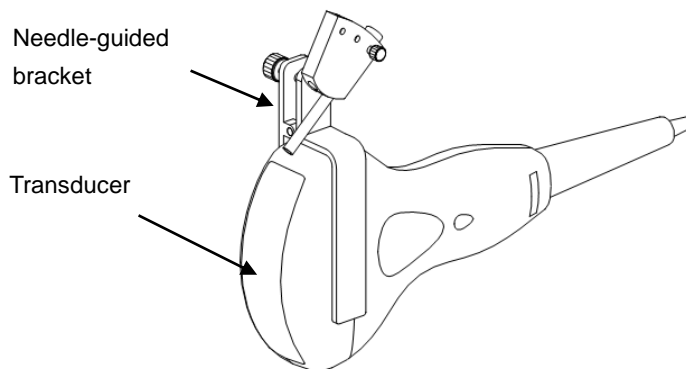
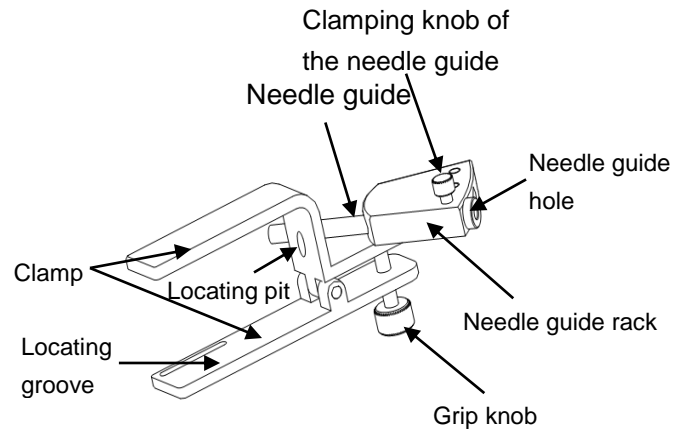
For biopsy or treatment, ultrasound-guided biopsy procedures can be performed using this transducer in combination with a needle-guided bracket (optional accessory) and a biopsy needle (provided by the user).

## Name of Parts

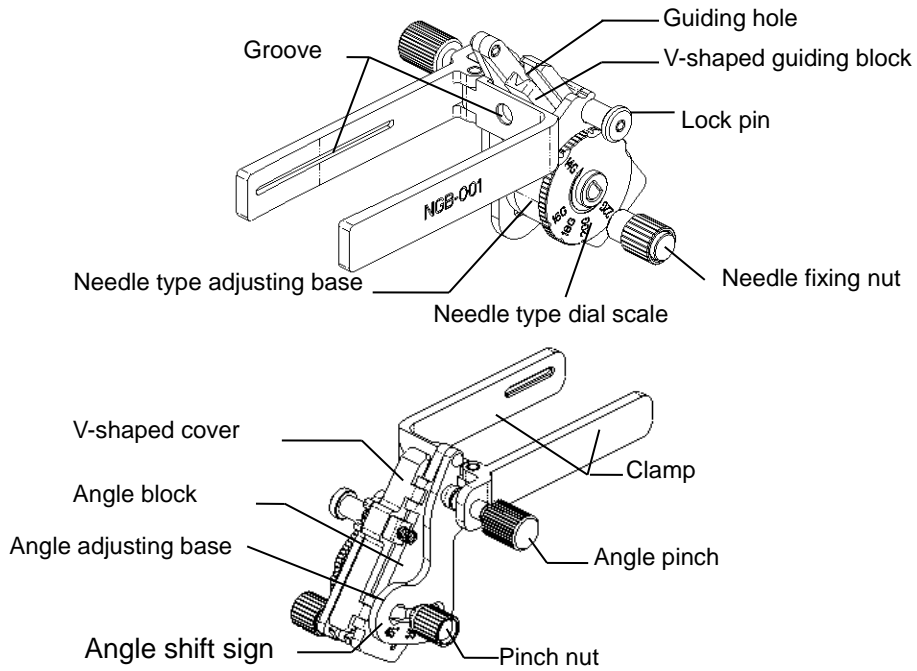
This section describes the parts and corresponding functions of each needle-guided bracket.

### ■ NGB-001, NGB-002, NGB-003, and NGB-005 (Metal/needle un-detachable)

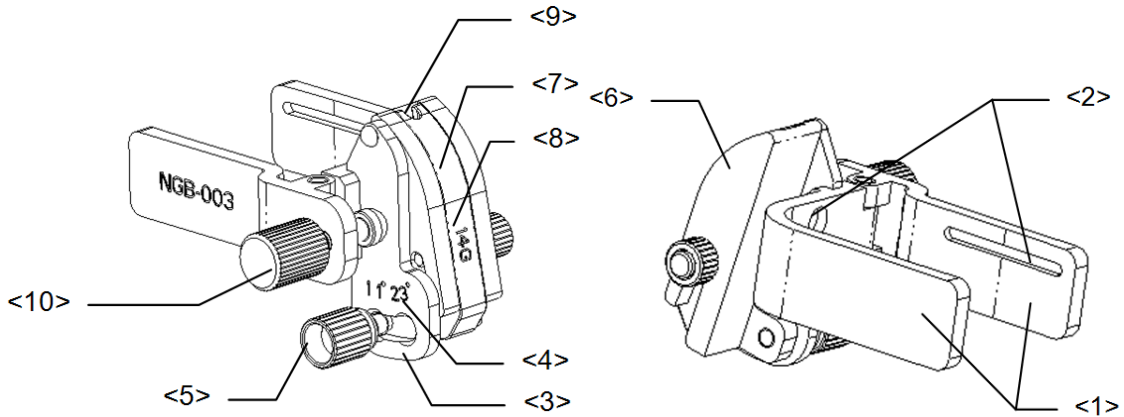
The structure of plastic needle-guided bracket NGB-001, NGB-002, NGB-003 and NGB-005 are similar to each other. The following figure shows the structure with NGB-001 as an example.



■ NGB-001 Metal-needle detachable



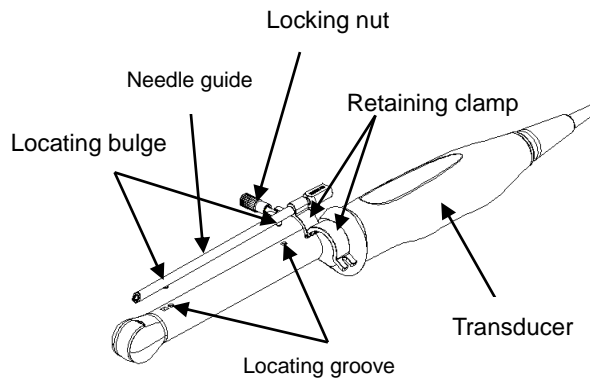
■ NGB-003 (Metal/needle detachable)



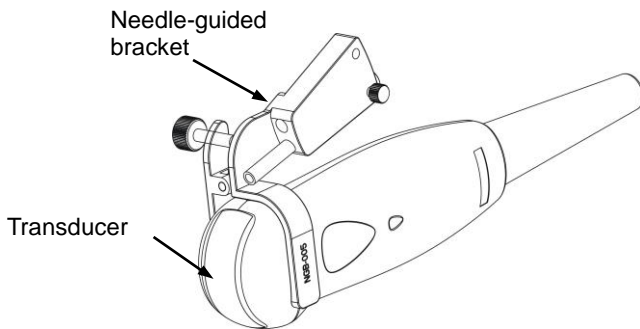
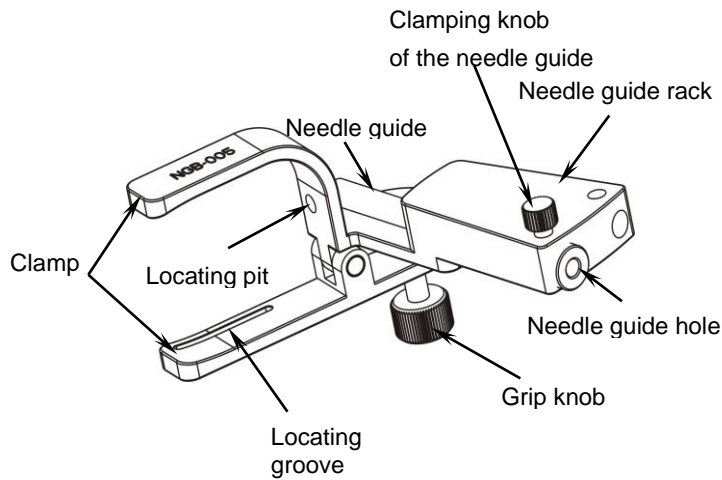
No.	Name	Description
<1>	Clamp of needle-guided bracket	Used for installing the needle-guided bracket on the transducer
<2>	Groove of the needle-guided bracket	Matches with the tab of the transducer
<3>	Angle adjusting base	There are 3 types of angles available to be adjusted
<4>	Angle shift sign (11°, 23°)	Matched with the biopsy angle (11°, 23°)
<5>	Angle pinch nut	Used for fixing the angle lock at a chosen angle
<6>	Angle block	Used for determining the angle of the biopsy; different specifications of blocks can be used

No.	Name	Description
<7>	Guiding block	Used for installing biopsy needle; there are five specifications of guiding blocks for different biopsy needles
<8>	Specification of guiding block (14G)	Matched with the corresponding biopsy needle (14G)
<9>	Needle guide hole	Used for installing the biopsy needle
<10>	Pinch nut of needle-guided bracket	Used for locking the needle-guided bracket and the transducer

■ NGB-004



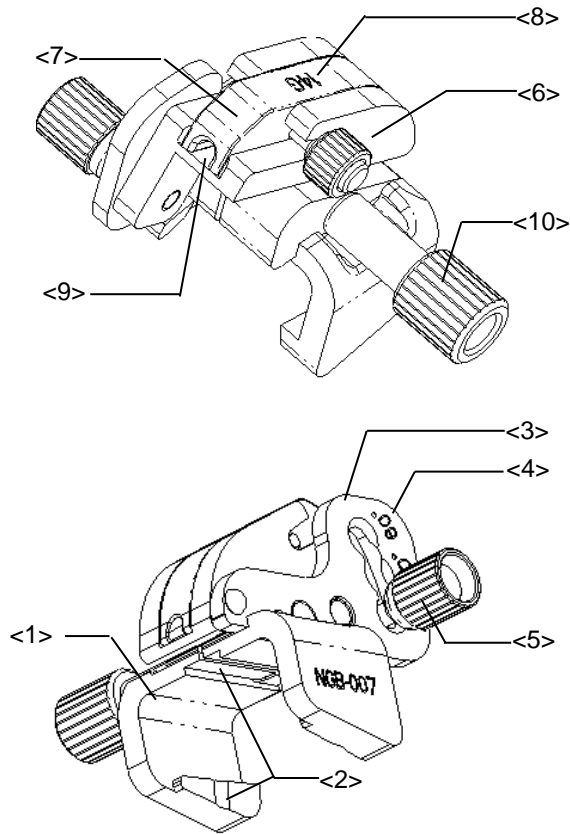
■ NGB-005



■ NGB-007

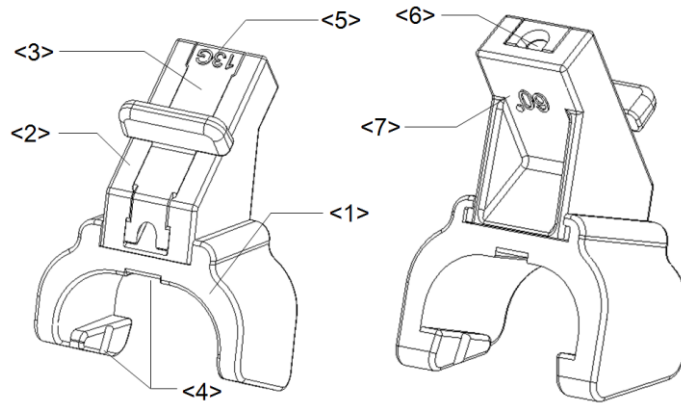
- Metal:





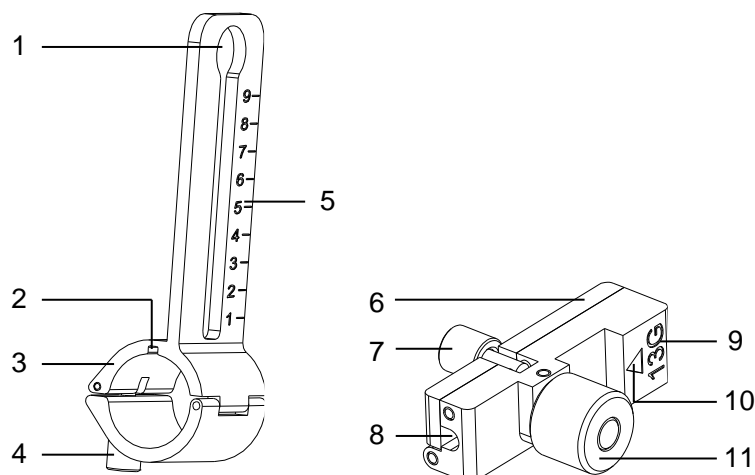
No.	Name	Description
<1>	Support of needle-guided bracket	Used for installing the needle-guided bracket on the transducer
<2>	Groove and tab of the needle-guided bracket	Respectively matched with the tab and groove of the transducer
<3>	Angle adjusting base	There are 3 types of angles available to be adjusted
<4>	Angle shift sign (40°,50°,60°)	Matched with the biopsy angle (40°,50°,60°)
<5>	Angle pinch nut	Used for fixing the angle lock at a chosen angle
<6>	Angle block	Used for determining the angle of the biopsy; different specifications of blocks can be used
<7>	Guiding block	Used for installing biopsy needle; there are five specifications of guiding blocks for different biopsy needles
<8>	Specification of guiding block (14G)	Matched with the corresponding biopsy needle (14G)
<9>	Needle guide hole	Used for installing the biopsy needle
<10>	Pinch nut of needle-guided bracket	Used for locking the needle-guided bracket and the transducer

- Plastic



No	Name	Description
<1>	Support of needle-guided bracket	Used for installing the needle-guided bracket on the transducer
<2>	Angle block	Used for determining the angle of the biopsy; there are three specifications of blocks of angle
<3>	Guiding block	Used for installing biopsy needle; there are five specifications of guiding blocks for different biopsy needles
<4>	Groove and tab of the needle-guided bracket	Respectively matched with the tab and groove of the transducer
<5>	Specification of guiding block (13G)	Matched with the corresponding biopsy needle (13G)
<6>	Needle guide hole	Used for installing the biopsy needle
<7>	Specification of angle block (60°)	Corresponding to the size of the biopsy angle (60°)

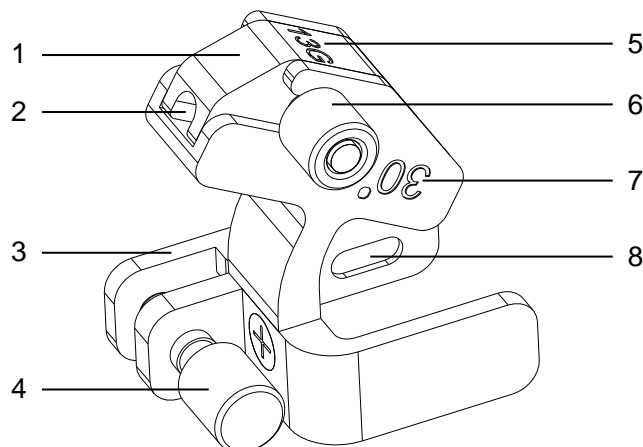
■ NGB-009 (Metal/needle detachable)



No.	Name	Description
1	Hole for installing guiding block	Used for installing the knob of fixing needle-guided bracket

No.	Name	Description
2	Groove	Match with the tab on the transducer
3	Support of needle-guided bracket	Used for installing the needle-guided bracket on the transducer
4	Knob of fixing needle-guided bracket	Used for fixing the needle-guided bracket on the transducer
5	Needle distance scales	Indicate distance between needle and the transducer head surface
6	Guiding block	Used for installing biopsy needle; there are five specifications of guiding blocks for different needles
7	Knob of fixing the needle	Used for fixing the needle
8	Guiding hole of the needle	Used for installing the biopsy needle
9	Specification of guiding block	Matched with the corresponding biopsy needle
10	Mark of indicating scales	Indicating needle distance scales
11	Knob of fixing the guiding block	Used for fixing the guiding block

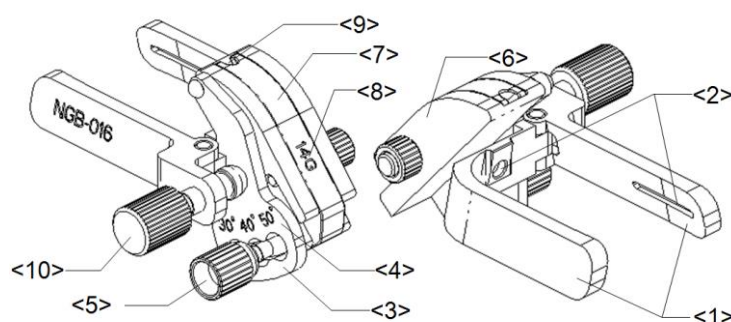
■ NGB-010 (Metal/needle detachable)



No.	Name	Description
1	Guiding block	Used for installing biopsy needle; there are five specifications of guiding blocks for different biopsy needles
2	Guiding hole of the biopsy needle	Used for installing the biopsy needle
3	Support of needle-guided bracket	Used for installing the needle-guided bracket on the transducer
4	Knob of fixing needle-guided bracket	Used for fixing the needle-guided bracket on the transducer

No.	Name	Description
5	Specification of guiding block (13G)	Matched with the corresponding biopsy needle (13G)
6	Knob of fixing the guiding block	Used for fixing the guiding block
7	Needle guide angle	The needle guide angle of this needle-guided bracket
8	Grooves of the needle-guided bracket	Matched with the tabs of the transducer

■ NGB-016



No	Name	Description
<1>	Clamp of needle-guided bracket	Used for installing the needle-guided bracket on the transducer.
<2>	Groove of the needle-guided bracket	Matches with the tab of the transducer.
<3>	Angle adjusting base	There are 3 types of angles available to be adjusted.
<4>	Angle shift sign (30°, 40°, 50°)	Matches with the biopsy angle (30°, 40°, 50°).
<5>	Angle pinch nut	Used for fixing the angle lock at a chosen angle.
<6>	Angle block	Determines the angle of the biopsy; different specifications of blocks can be used.
<7>	Guiding block	Used for installing the needles of different specifications, 5 types of needles are available.
<8>	Specification of guiding block (14G)	Matched with the corresponding biopsy needle (14G).
<9>	Guiding hole of biopsy needle	Used for installing the needles.
<10>	Pinch nut of needle-guided bracket	Used for locking the needle-guided bracket and the transducer.

### 12.2.3 Biopsy Preset

Open Biopsy page via [Setup]-> [System Preset]-> [Biopsy].

■ Bracket model

To set the default bracket for a probe.

- (1) Select a probe model in the Probe Model list, all the supported bracket models will be displayed in the “Bracket Model” list on the right side. (If the selected probe has no bracket matched, no model is displayed.)
- (2) Click to select a bracket model on the Bracket Model list.
- (3) Click [Save] to confirm the setting and return to Setup menu.

■ Parameter

To set if to display/hide guide line.

- (1) Check [Guide Line Display] to set the guide line display, otherwise, the guide line is hidden when enters biopsy status.
- (2) Click [Save] to confirm the setting and return to Setup menu.

## 12.2.4 Needle-guided Bracket Inspection and Installation

### Inspection of the Needle-guided Bracket

Be sure to perform inspections before and after use of the needle-guided bracket. If an abnormality is found on the needle-guided bracket, immediately stop using it and contact MINDRAY Customer Service Department or sales representative.

1. Sterilize the needle-guided bracket before and after use.
2. Confirm that the needle-guided bracket is free of damage, deformation, stripping, malfunction, loose or missing parts.
3. Confirm that the needle-guided bracket is securely mounted in the correct position.

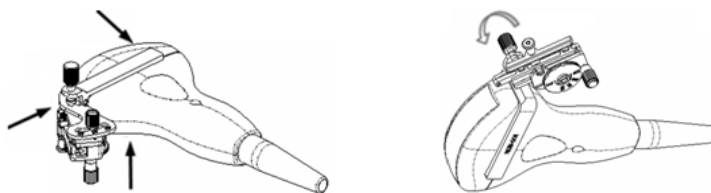
### Installing the Needle-guided Bracket

■ NGB-001, NGB-002, NGB-003 and NGB-005 metal/needle un-detachable needle-guided bracket (taking NGB-001 as example)

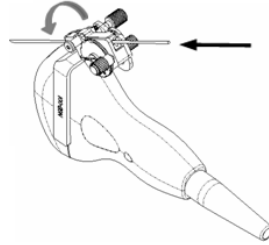
- (1) Put on the sterile transducer sheath.
- (2) Inoculate the locating groove on the clamp with the two raised edges on the transducer head and aligning the locating pit of the clamp to the convex point on the transducer head.
- (3) Turn the grip knob at the tail of the needle-guided bracket tightly.

■ NGB-001

1. Put on the sterile transducer sheath.
2. Hold the transducer by one hand, select the proper needle-guided bracket, and hold it with the other hand. Match the groove of the bracket with the tab of the transducer. Amount the bracket onto the transducer.

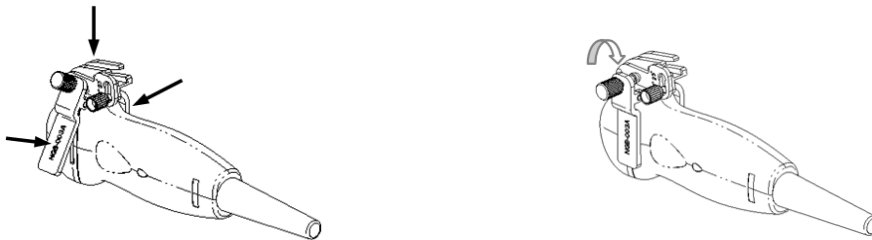


3. Screw the pinch nut of the needle-guided bracket to confirm that the needle-guided bracket is properly installed on the transducer.
4. Adjust the dial scale to the required needle type shift, and then screw the needle fixing nut to lock the dial scale (To adjust the dial scale you have to loose the needle fixing nut first.)
5. Pull the lock pin and close the V-shaped cover to fix the lock pin in the groove of the needle type adjusting base, so as to install the needle into the guiding hole.



■ NGB-003 metal/needle detachable needle-guided bracket

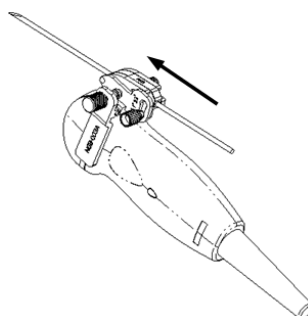
- (1) Put on the transducer sheath.
- (2) Select a proper needle-guided bracket, and match the groove with the tab of the transducer respectively. Mount the bracket onto the transducer.



- (3) Screw the pinch nut of the needle-guided bracket to confirm that the needle-guided bracket is properly installed on the transducer.
- (4) Select a proper guiding block and push it into the groove above the angle block.

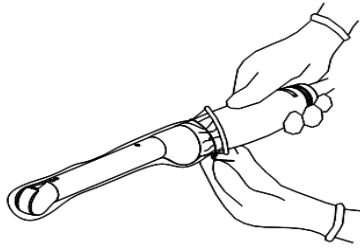


- (5) Screw the nut of the block to secure the block.
- (6) Insert a biopsy needle with the same specification as that of the guiding block into the hole of the guiding block.

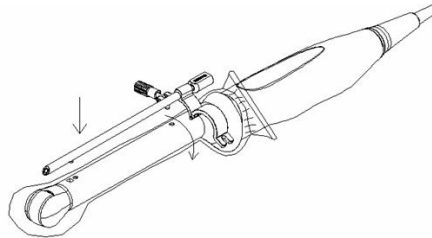


■ NGB-004

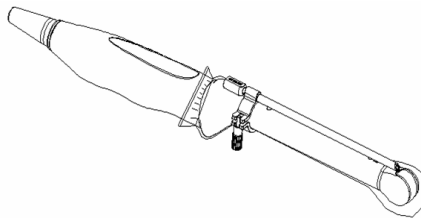
1. Put on the sterile probe sheath.



2. Open the retaining clamp, align the needle-guided bracket with the transducer to locate the locating bulge on the needle guide to the locating grooves on the transducer, and then turn the retaining clamp to match it with the transducer.



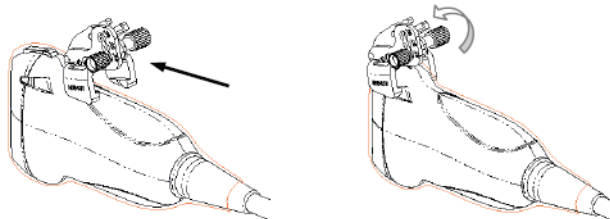
3. When the retaining clamp is turned to the right position, the locking nut will lock the retaining clamp and the needle-guided bracket is then mounted to the right position.



■ NGB-007

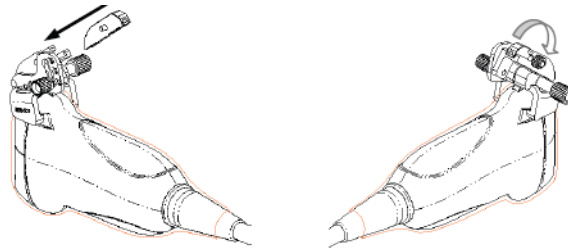
● Metal

- 1) Put on the sterile transducer sheath.
- 2) Hold the transducer by one hand, select the proper needle-guided bracket, and hold it with the other hand. Match the groove and tab with the tab and groove of the transducer respectively. Amount the bracket onto the transducer.

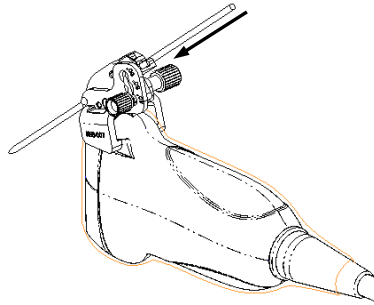


- 3) Screw the pinch nut of the needle-guided bracket to confirm that the needle-guided bracket is properly installed on the transducer.

- 4) Select a proper guiding block and push it into the groove above the angle block, and clamp it tightly.

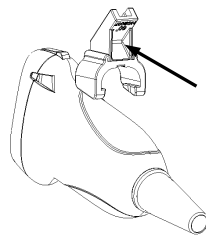


- 5) Screw the nut of the block to secure the block.
- 6) Insert a biopsy needle with the same specification as that of the guiding block into the hole of the guiding block.

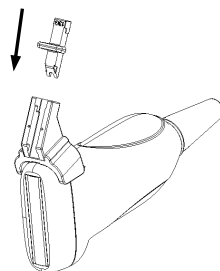


- Plastic

- 1) Put on the sterile transducer sheath.
- 2) Hold the transducer by one hand, select proper needle-guided bracket, and hold it with the other hand. Align the narrow end tab of the needle-guided bracket with the groove of the transducer, then push the needle-guided bracket forward, making the tabs and the grooves of the needle-guided bracket to match with the grooves and tabs of the transducer.

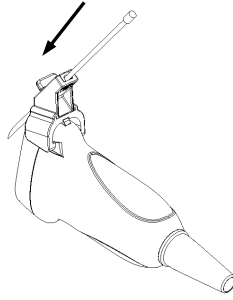


- 3) Check manually to confirm that the needle-guided bracket is securely installed on the transducer.
- 4) Select a proper guiding block and push it into the groove above the angle block, and clamp it tightly.



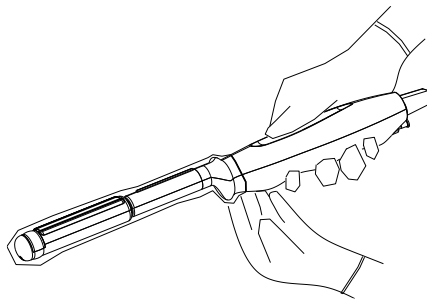


- 5) Insert a biopsy needle with the same specification as that of the guiding block into the hole of the guiding block.

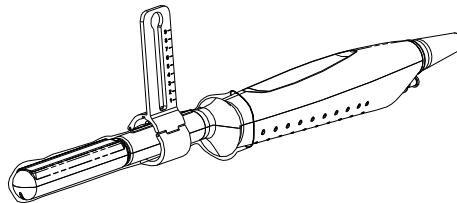


■ NGB-009 metal/needle detachable needle-guided bracket

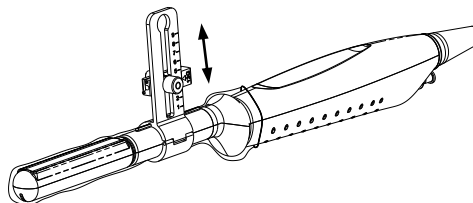
- (1) Put on the transducer cover.



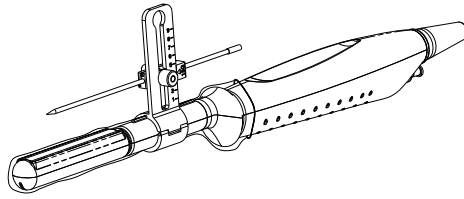
- (2) Cover the support of needle-guided bracket on the transducer, making the groove of the needle-guided bracket to match with the tab of the transducer. Set the needle-guided bracket at the desired position, turn tightly the knob of fixing needle-guided bracket to fix the needle-guided bracket.



- (3) Select a proper guiding block and thread the knob of fixing the guiding block through the hole of installing guiding block, move the guiding block to the desired position, then turn tightly the knob of fixing the guiding block to fix the guiding block on the support of needle-guided bracket.

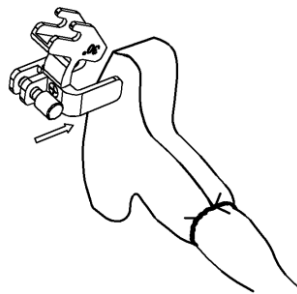


- (4) Insert a biopsy needle with the same specification as that of the guiding block into the hole of the guiding block and turn tightly the knob of fixing the needle.

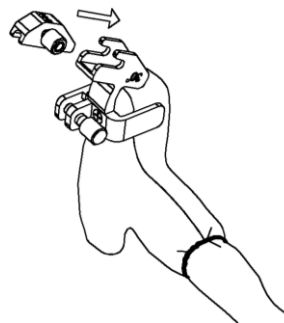


■ NGB-010 metal/needle detachable needle-guided bracket

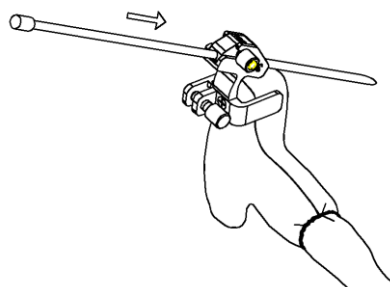
- (1) Put on the transducer cover.
- (2) Hold the transducer by one hand, select proper needle-guided bracket, and hold it with the other hand, and align the grooves of the needle-guided bracket with the tabs of the transducer, then push the needle-guided bracket forward, making the grooves of the needle-guided bracket to match with the tabs of the transducer. Set the needle-guided bracket at the desired position, turn tightly the knob of fixing needle-guided bracket to fix the needle-guided bracket.



- (3) Check manually to confirm the needle-guided bracket is securely installed on the transducer.
- (4) Select a proper guiding block and push it into the groove above the support of needle-guided bracket, then turn tightly the knob of fixing the guiding block to fix the guiding block on the support of needle-guided bracket.

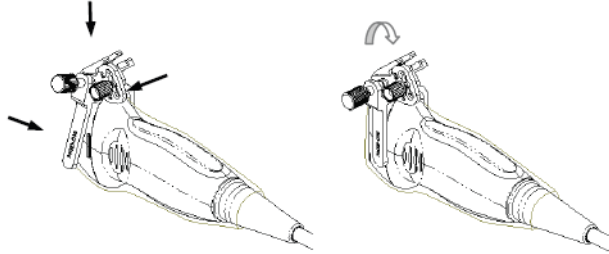


- (5) Insert a biopsy needle with the same specification as that of the guiding block into the hole of the guiding block.

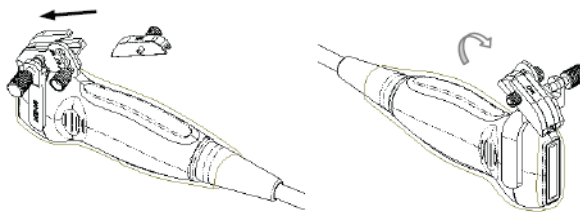


■ NGB-016

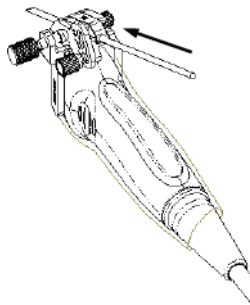
1. Put on the sterile transducer sheath.
2. Select a proper needle-guided bracket, and match the groove with the tab of the transducer. Mount the bracket onto the transducer.



3. Screw the pinch nut of the needle-guided bracket to confirm that the needle-guided bracket is properly installed on the transducer.
4. Select a proper guiding block and push it into the groove above the angle block, and clamp it tightly.



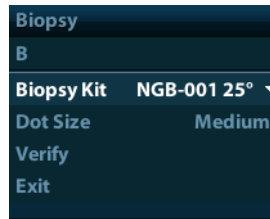
5. Screw the nut of the block to secure the block.
6. Insert a biopsy needle with the same specification as that of the guiding block into the hole of the guiding block.



**⚠ CAUTION:** Ensure that all guide parts are seated properly prior to performing a biopsy.

## 12.2.5 Biopsy Menu

Press <Biopsy> to show the biopsy menu.



- Select biopsy bracket angle  
If the needle-guided bracket supports more than one biopsy angle, you can select the angle from the drop-down list.
- Select Dot size  
Move the cursor onto [Dot Size], press <Set> to select the dot size among Small, Medium and Big.  
Tips:
  - The guide line is a dot line which consists of two kinds of dots, the distance between two dots is depth dependent. Move the cursor onto the big dot, a numeral, which represents the biopsy depth, is displayed.
  - The biopsy guidezone adjusts along with image adjustments, such as image inversion/rotations, zoom and depth changes.
  - When the imaging depth and area are changed, the guide line will be adjusted.
- Display or hide the guide line  
Set [Biopsy Kit] on the menu to “Off” to hide the guide line.  
Or, press <Biopsy> on the control panel to display or hide the guide line.
- In B mode image menu, you can also display, hide or select the needle-guide bracket via [Biopsy Kit] item.

## 12.2.6 Verify Biopsy Guide Line

**⚠ WARNING:**

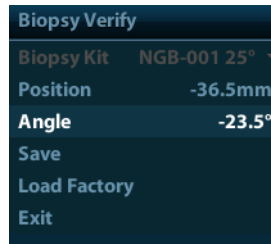
1. Prior to each biopsy procedure, be sure to verify the guide line.
2. If the needle is not consistent with the guide line, DO NOT perform the biopsy procedure.

**NOTE:**

1. You can perform guide line verification on a single live B image only, and all biopsy-irrelevant operations are forbidden.
2. For bi-planar probe applied biopsy, the verification is performed on the first guide line, the other guide lines can move together with the first one in parallel.

1. Confirm that the needle-guided bracket has been installed securely in the correct position.
2. Prepare a container filled with sterile water.
3. Place the head of the transducer in the sterile water, and get a biopsy needle into the needle guide.

4. When the biopsy needle appears on the image, please adjust the parameters of the menu on the screen to make the biopsy needle is displayed at almost the same position as the selected needle mark.



- Adjust guide line position  
Move the cursor onto [Position], press <Set> key to move it linearly, or press and rotate the multifunctional-knob. This is operative when there is only one guide line displayed.
- Adjust angle  
Move the cursor onto [Angle], press <Set> key to change the guide line angle, or press and rotate the multifunctional-knob. This is operative when there is only one guide line displayed.
- Save verified settings  
After the position and angle of the guide line are adjusted, click [Save], and the system will save the current settings of the guide line. When enter biopsy again, the displayed Position and Angle are the verified value.
- Restore the factory default settings  
Click [Load Factory], and the position and angle of the guide line will be restored to the factory default settings.
- Exit the biopsy verify status  
Click [Exit], and the system will exit the verification status of the guide line.

## 12.2.7 iNeedle (Needle Visualization Enhancement)

In the course of biopsy, the metal needle attached to the probe is punctured into the tissue with a certain angle; because of the needle acoustic impedance, the ultrasonic beam cannot penetrate the metal needle, a reflecting boundary is formed. As in Figure 1, if the deflection angle is very large, the needle display is not clear.

In the condition of deflected ultrasonic transmission, the beam direction is perpendicular to the needle direction, and the reflection direction will be the same with the needle, as shown in Figure 2, when the needle display in the ultrasound image is very clear. The system provides an additional deflection transmission that is approximately perpendicular to the metal needle, as the normal transmission (perpendicular to the transducer surface) is contained as well. And the deflection angel can be chosen by users.

iNeedle is an option.

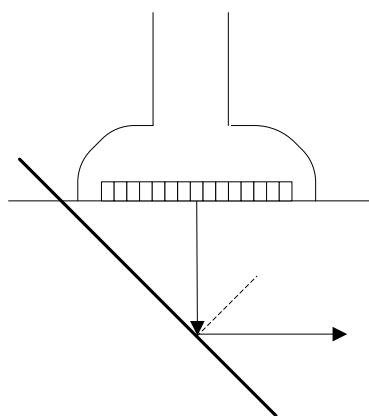


Figure 1

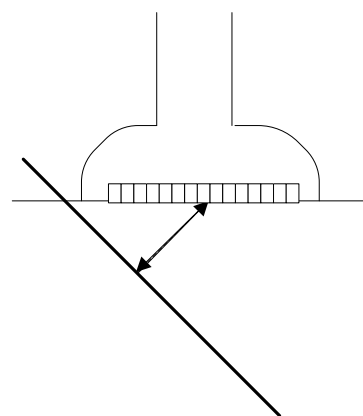


Figure 2

### To enter/exit iNeedle

- To enter iNeedle

Click [iNeedle] item in B page on the screen.

Or, you can assign a user-defined key for entering iNeedle.

- Open iNeedle in Biopsy status

1. Perform scanning and locate the target, press <Biopsy> to enter the screen.
2. Click [iNeedle] to enter the status; available adjusting parameters are displayed on the menu.

- To exit iNeedle

Press the user-defined key or click [iNeedle] to exit the status and enter B mode.

### Needle Steer

**Description** This function adjusts the biopsy needle angle via changing the steer angle of the scan line. The iNeedle affecting region changes correspondingly.

**Operation** Click [Needle Steer] item on the screen.

### B/iNeedle

**Description** This function is used to display B image and iNeedle image synchronously.

**Operation** To turn on or off the function, click [B/iNeedle] on the screen.

Tips: iZoom (full-screen magnification) is available on iNeedle status.

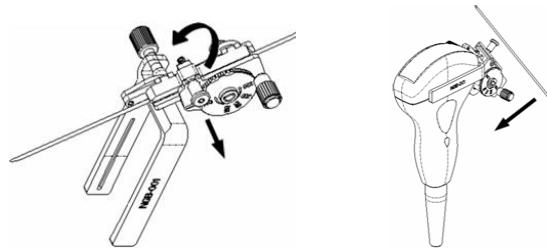
## 12.2.8 Removing the Needle-guided Bracket

- NGB-001/ NGB-002/ NGB-003/ NGB-005 metal/needle un-detachable needle-guided bracket:

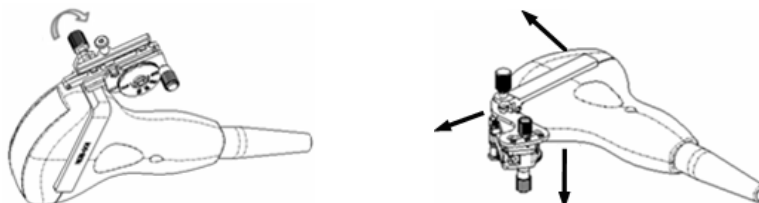
While holding the transducer and the needle-guided bracket, open the Grip knob of the needle-guided bracket.

- NGB-001 Metal-needle detachable

1. Pull the lock pin and open up the V-shaped cover to expose the needle.



2. Separate the bracket and the transducer from the needle.
3. Screw the pinch nut to release the needle-guided bracket.



4. Separate the bracket and the transducer.

■ NGB-003

Metal/needle detachable needle-guided bracket:

- (1) Screw the nut of the guiding block and remove the guiding block slightly along the direction of the needle's tail.



- (2) Separate the residual part of the needle-guide bracket and the transducer from the needle.



- (3) Screw the pinch nut of the bracket, and remove the needle-guided bracket from the transducer.

■ NGB-004

Hold the transducer in the left hand, unscrew the locking nut with the right hand to open the retaining clamp, and then raise the needle-guided bracket to separate the locating bulge from the locating grooves.

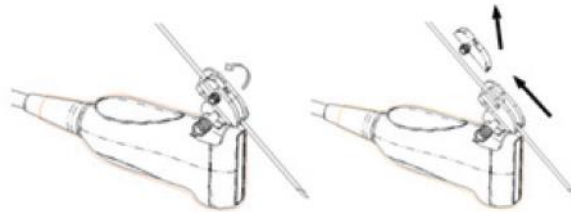
■ NGB-005

While holding the transducer and the needle-guided bracket, open the Grip knob of the needle-guided bracket.

■ NGB-007

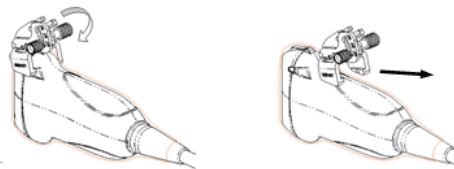
● Metal

- 1) Screw the nut of the guiding block and remove the guiding block slightly along the direction of the needle's tail.



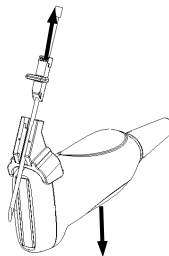
- 2) Separate the residual part of the needle-guide bracket and the transducer from the needle.

- 3) Screw the pinch nut of the bracket, and remove the needle-guided bracket from the transducer.

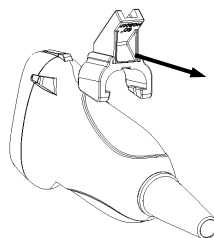


● Plastic

- 1) Remove the guiding block slightly along the direction of the needle's tail.
- 2) Separate the residual part of the needle-guide bracket and the transducer from the needle.



- 3) Remove the support of needle-guided bracket from the transducer.



■ NGB-009

- (1) Turn on the knob of fixing the needle and separate the needle from the needle-guided bracket.



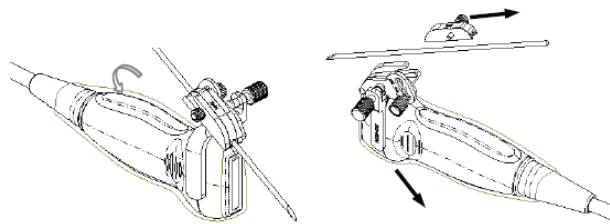
- (2) Turn on the knob of fixing guiding block and remove the guiding block from the hole of installing guiding block.
- (3) Turn on the knob of fixing needle-guided bracket and remove the needle-guided bracket.

■ NGB-010

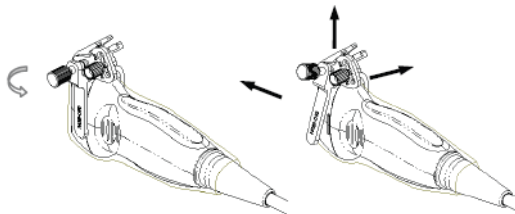
- (1) Remove the guiding block slightly along the direction of the needle's tail, and separate the residual part of the needle-guide bracket and the transducer from the needle.
- (2) Remove the support of needle-guided bracket from the transducer.

■ NGB-016

1. Screw the nut of the guiding block and remove the guiding block slightly along the direction of the needle's tail.



2. Separate the residual part of the needle-guide bracket and the transducer from the needle.
3. Screw the pinch nut of the bracket, and remove the needle-guided bracket from the transducer.



4. Separate the transducer and the needle-guided bracket.

## 12.2.9 Clean and Sterilize the Needle-guided Bracket

### Cleaning

1. Wear sterile gloves to prevent infection.
2. Or, wash with clean water or soapy water to remove all the foreign matters, or, wipe the bracket with a soft ethyl carbamate sponge.
3. Wipe off the water on the needle-guided bracket using sterile cloth or gauze after washing it.

Please follow the instructions in the manual for cleaning.

### Sterilization

1. Wear sterile gloves to prevent infection.

2. Clean the needle-guided bracket before sterilizing it. MINDRAY recommends the following solution or sterilizing system to sterilize the needle-guided bracket.
3. Follow local regulations when selecting and using the disinfectant.

■ Glutaraldehyde-based sterilant:

Chemical name	Trade name	Procedures
Glutaraldehyde (2.2-2.7%)	Cidex Activated Glutaraldehyde Solution	Please refer to the instructions provided by the manufacturer of the solution for details.  Soak the transducer into the activated solution for 10 hours (20-25°C)

Before safety and performance is affected, plastic bracket can be sterilized by Cidex Activated Glutaraldehyde Solution for at least 233 times (10 hours for one time).

■ Hydrogen Peroxide and Peroxyacetic Acid -based sterilant:

Trade Name	Chemical Name	Procedures
Minnicare® Cold Sterilant	22% Hydrogen Peroxide  4.5% Peroxyacetic Acid	Dilute the sterilant with sterilized purified water (1:20).  Immersed time: 11 hours.  Temperature: 20°C-25°C.  Please refer to the instructions provided by the manufacturer of the solution for details.

Before safety and performance is affected, plastic bracket can be sterilized by Minncare COLD STERILANT for at least 245 times (11 hours for one time).

- Refer to the instructions provided by the chemical manufacturer concerning concentration of the solution, and method of disinfections and dilution. Note that the glutaraldehyde disinfectant solution needs an activating solution.
- Rinse the needle-guided bracket thoroughly with sterile water to remove all chemical residues on it.
- Wipe off the water on the needle-guided bracket with sterile cloth or gauze after rinsing it.

■ STERRAD 100S low-temperature hydrogen peroxide gas plasma sterilization system

Chemical name	Trade name	Procedures
Hydrogen peroxide gas plasma	Hydrogen peroxide vapor	Please refer to the instructions provided by the producer of the solution for details.

- Refer to the instruction of STERRAD 100S sterilizing system provided by the manufacturer for operation instructions and cautions.
- The STERRAD 100S low-temperature hydrogen peroxide gas plasma sterilization system is available for metal needle-guided brackets.

■ High-pressure steam sterilization (only applicable for metal guided-bracket)  
Autoclaving (moist heat) 121° C for 20 minutes.

**NOTE:** The high-pressure steam/ immersion sterilization do not affect the bracket duration life, and the duration life is affected by the daily application of the bracket. Please check the appearance of the bracket before using.

## 12.2.10 Storage and Transportation

- Don't use the carrying case for storing the needle-guided bracket. If the carrying case is used for storage, it may become a source of infection.
- Between examinations, keep the needle-guided bracket in a sterile environment.
- When the needle-guided bracket is sent to your MINDRAY representative for repair, be sure to disinfect or sterilize it and keep it in the carrying case to prevent infection.
- Sterilize the carrying case as necessary.
- Store or transport the needle-guided bracket under the following ambient conditions:
  - Ambient temperature: -20°C ~ 55°C
  - Relative humidity: 30% to 95% (no condensation)

## 12.2.11 Disposal

Be sure to dispose the needle-guided bracket only after sterilizing it.  
Contact your MINDRAY representative when disposing of this device.

## 12.3 Middle Line

“Middle Line” helps to locate the focus point of lithotripsy wave during lithotripsy treatment. By watching the procedure of lithotripsy in real-time and adjusting the intensity and frequency of the lithotripsy wave, the harm to the animals can be reduced to the least.

- To enter lithotripsy mode: in B mode, click [Middle Line] in the image menu at the left side of the screen to turn on the lithotripsy.
- In middle line mode:
  - The middle line is a vertical straight line located in the middle of the screen, the position and direction of which cannot be changed.
  - The middle line mark is a “x” mark located on the middle line, which can be moved up and down along the middle line by rolling the track ball.
  - The depth of the mark is displayed in the image parameter area at the right side of the screen.



# 13 Battery

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## **WARNING:**

1. **DO NOT** install or detach the battery ad arbitrium  
The batteries have protective mechanism and circuit.  
**DO NOT** disassemble or alter the battery.
2. **DO NOT** short-circuit the batteries by directly connecting the negative terminals with metal objects.
3. **DO NOT** heat the battery or discard it in a fire.
4. **Keep** the batteries away from fire and other heat sources.
5. **DO NOT** immerse the batteries in water or allow them to get wet.
6. **DO NOT** charge the batteries near a heat source or in direct sunlight.
7. **DO NOT** pierce the batteries with a sharp object, hit or step on them.
8. **DO NOT** use the batteries mixed with other battery models.
9. **DO NOT** put the batteries into a microwave oven or pressurized container.
10. **If** the batteries emit an odor or heat, are deformed or discolored, or in a way appear abnormal during use, charging or storage, immediately remove them and stop using them.

## 13.1 Overview

The battery charges when the system is connected to the AC power supply.

- Generally, if the system is turned off, a completely discharged battery will fully charge in less than 3 hours; or generally a battery has been charged for 2 hours, it can restore the quality of electric charge to above 95%.

- NOTE:**
1. It is recommended to charge the batteries when the system is turned off, thus you can quickly charge the battery and save time.
  2. Power off the system if you will not use the system for a long period of time (including storage/ transportation condition), and you should not allow the system in standby status, otherwise the batteries will be out of power and permanently damaged.

When the external power supply is not connected, a lithium-ion battery will provide the power.


The model of the chargeable lithium-ion battery (hereinafter called battery for short) is LI34I002A.

**NOTE:** 1. Only use the specified batteries.  
2. If there is only one battery in the system, it cannot supply power and cannot be charged.

## 13.2 Precautions

1. Before using the battery, carefully read the description in the label on the surface of the battery.
2. When you use the battery at the first time and find that it is dirty or emit an odor, do not use it.
3. Do not expose the battery to heat sources or high pressure.
4. Do not leave the battery in direct sunlight.
5. Store the battery out of the reach of children. Store the battery out of the reach of children.
6. The battery is designed to be charged only in this system; charge the battery only when the ambient temperature is between 0 and 40 °C.
7. When the battery is out of power, please charge it immediately.
8. When the battery will not be used for 10 days or over, take it out of the system and store it with caution. DO NOT wrap it with conductive material; store it in shady, cool and dry place.
9. Do not knock the battery.

## 13.3 Installing and Removing the Batteries

 **WARNING:** Turn off the system and disconnect the adapter from the main unit before installing or removing batteries. DO NOT install or remove batteries when the system is turned on or the system is turned off but the adapter is connected with the system.

The battery is put in the battery bays at the back side of the system. You can install or remove it when the system is turned off and the power cord is disconnected from the main unit.

To install the battery:

1. Turn off the unit and detach the power cord from the main unit.
2. You can see a battery bay at the back of the system. (Note that the battery shall be put in correct direction). Put the battery into the bay and push to the right side until it's tightly locked.
3. Close the battery cover.

To remove the battery:

1. Turn off the unit and detach the power cord from the main unit.
2. Open the battery cover.
3. Push the battery to left until it's released.
4. Take out the battery from the bay.

## 13.4 Battery Status Indicator

The battery status indicator is located in the lower right corner of the screen, indicating the battery capacity.



: indicates the battery capacity is empty.



: indicates the battery capacity is full.

When the power capacity is not enough, the system will pop up a prompt:

Warning! Battery is out of power! Please connect to power supply or system will be shut down in one minute. Connect the power supply to afford normal work.

## 13.5 One Full Discharge / Charge Cycle

If the battery has not been used for over 2 months, you are recommended to perform one full discharge / charge cycle. It is also recommended that the battery is stored in the shady and cool area with FCC (full current capacity).

### ■ One Full Discharge / Charge Cycle:

1. Full discharge of the battery to let the system automatically shut down.
2. Charge the system to 100% FCC (full current capacity).
3. Discharge of the system for complete shutdown.

## 13.6 Checking Battery Performance

The battery performance may be degraded over time, so you need to check the battery performance periodically. The checking procedures are shown as follows:

1. Stop the ultrasound exam.
2. Connect the system to the AC power supply to charge the batteries until current capacity is full.
3. Disconnect the system from the AC power supply to power the system by the batteries until the system automatically shuts down.
4. The powering time of the batteries indicates the battery performance.

If the powering time of the battery is much shorter than that specified in the Specification Manual, you may replace the battery or contact the service personnel.

## 13.7 Battery Disposal

You need to dispose of the battery when it is damaged, severely degraded or used for 3 years.

**NOTE:** You should observe the local regulations when disposing of the battery.





# 14 Acoustic Output

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This section of the operator's manual applies to the overall system including the main unit, probes, accessories and peripherals. This section contains important safety information for operators of the device, pertaining to acoustic output and how to control animal exposure through use of the ALARA (as low as reasonably achievable) principle. Also this section contains information regarding the acoustic output testing and the real-time output display. Read this information carefully before using the system.

## 14.1 Concerns with Bioeffects

Diagnostic ultrasound is recognized as being safe. In fact, there have been no reports of injuries to animals caused by diagnostic ultrasound.

It cannot be stated categorically that ultrasound is 100% safe. Studies have revealed that ultrasound with extremely high intensity is harmful to body tissues.

Diagnostic ultrasound technology has made a great leap forward during the last several years. This rapid advance has generated concerns about the potential risk of bioeffects when new applications or diagnostic technologies become available.

## 14.2 Prudent Use Statement

Although there are no confirmed biological effects on animals caused by exposures from present diagnostic ultrasound instruments, the possibility exists that such biological effects may be identified in the future. Thus ultrasound should be used in a prudent manner to provide medical benefit to the animal. High exposure levels and long exposure times should be avoided while acquiring necessary clinical information.

## 14.3 ALARA Principle (As Low As Reasonably Achievable)

It is required to practice ALARA when using ultrasound energy. Practicing ALARA ensures that the total energy level is controlled below a low enough level at which bioeffects are not generated while diagnostic information is being accumulated. The total energy is controlled by output intensity and total radiation time. The output intensity necessary for examinations differs depending on the animal and the clinical case.

Not all examinations can be performed with an extremely low level of acoustic energy. Controlling the acoustic level at an extremely low level leads to low-quality images or insufficient Doppler signals, adversely affecting the reliability of the diagnosis. However, increasing the acoustic power more than necessary does not always contribute to an increase in quality of information required for diagnosis, rather increasing the risk of generating bioeffects.

Users must take responsibility for the safety of animals and utilize ultrasound deliberately. Deliberate use of ultrasound means that output power of ultrasound must be selected based on ALARA.

Additional information regarding the concept of ALARA and the possible bioeffects of Ultrasound is available in a document from the AIUM (American Institute of Ultrasound Medicine) title “*Medical Ultrasound Safety*”.

## 14.4 MI/TI Explanation

### 14.4.1 Basic Knowledge of MI and TI

The relationship of various ultrasound output parameters (frequency, acoustic pressure and intensity, etc) to bioeffects is not fully understood presently. It is recognized that two fundamental mechanisms may induce bioeffects. One is a thermal bioeffect with tissue absorption of ultrasound, and another one is a mechanical bioeffect based on cavitations. Thermal Index (TI) gives the relative index of temperature increase by thermal bioeffect, and Mechanical Index (MI) gives the relative index of mechanical bioeffect. TI and MI indices reflect instantaneous output conditions, so they DO NOT consider the cumulative effects of the total examination time.

#### ■ MI (Mechanical Index):

The mechanical bioeffects are the result of compression and decompression of insonated tissues with the formation of micro bubbles that may be referred to as cavitations.

MI is an index that shows the possibility of the cavitations generation based on acoustic pressure, and the value in which the peak-rarefactional acoustic pressure is divided by the square root of the frequency. Therefore MI value becomes smaller when the frequency is higher or the peak-rarefactional acoustic pressure is lower, it becomes difficult to generate the cavitations.

$$MI = \frac{P_{r, \alpha}}{\sqrt{f_{\text{awf}}} \times C_{MI}}$$

Wherein,  $C_{MI} = 1 \text{ (MPa} / \sqrt{\text{MHz}} \text{)}$

For the frequency 1 MHz and the peak-rarefactional acoustic pressure 1 MPa, MI becomes 1. It is possible to think MI to be one threshold of the cavitations generation. Especially, it is important to keep MI value to be low when both gases and the soft tissues exist together, for such as lung exposure in cardiac scanning and bowel gas in abdominal scanning.

#### ■ TI (Thermal Index):

TI is determined by the ratio of the total acoustic power to the acoustic power required to raise the tissue temperature by 1 degree C. In addition, because the temperature rises is greatly different according to tissue structures, TI is divided three kinds: TIS (Soft-tissue Thermal Index), TIB (Bone Thermal Index) and TIC (Cranial-bone Thermal Index).

- TIS: Thermal index related to soft tissues, such as abdominal and cardiac applications.
- TIB: Thermal index for applications, such as fetal (second and third trimester) or neonatal cephalic (through the fontanel), in which the ultrasound beam passes through soft tissue and a focal region is in the immediate vicinity of bone.

- TIC: Thermal index for applications, such as pediatric and adult cranial applications, in which the ultrasound beam passes through bone near the beam entrance into the body.

WFUMB (World Federation for Ultrasound in Medicine and Biology) guidelines: state that temperature increase of 4 degree C for 5 min or more should be considered as potentially hazardous to embryonic and fetal tissue.

The smaller the MI/TI values, the lower the bioeffects.

## 14.4.2 MI/TI Display

TI and MI values are displayed in the upper part of the screen in real-time. The operator should monitor these index values during examinations and ensure that exposure time and output values are maintained at the minimum amounts needed for effective diagnosis.

**NOTE:** If there is a value of MI or TI exceeds 1.0, you must be careful to practice the ALARA principle.

The display precision is 0.1

## 14.5 Acoustic Power Setting

### ■ Acoustic power adjustment

Click [A. power] in the menu to adjust the acoustic power percentage, and the value is displayed on the screen. The greater the acoustic power percentage, the greater the current acoustic output.

When the image is frozen, the system stops transmitting acoustic power.

### ■ Default setting of acoustic power

Selection of diagnostic applications is the most important factor for controlling ultrasound output.

The permissible level of intensity of ultrasound differs depending on the region of interest. For fetal examinations, in particular, much care must be exercised.

In this system, imaging setups can be created using the ultrasound output set by you. At this time, the default function is disabled. It is the user's responsibility for any change to the default settings.

Default choices

Initial power	7% to 100%*
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\* Definition of 100%:

The maximum acoustic power of a transducer determined by the increase in transducer surface temperature in the selected mode and the acoustic power restrictions specified by the FDA.

**NOTE:** This system automatically returns to the settings whenever changes are made to the values (when you turn on the power, switch between probes, press [End Exam], or select Return in the Setup menu). In the factory default settings, the Acoustic Output is limited below settings. Following the ALARA restriction, you are allowed to increase the acoustic power under FDA 510(k) Guidance-Track3 limits and to set it in the image preset screen.

The acoustic output of the system has been measured and calculated in accordance with IEC60601-2-37: 2015, FDA 510(K) GUIDANCE, IEC 62359: 2017, Ultrasonics-Field

characterization-Test methods for the determination of thermal and mechanical indices related to medical diagnostic ultrasonic fields.

## 14.6 Acoustic Power Control

The qualified operator may use the system controls to limit the ultrasound output and to adjust the quality of the images. There are three categories of system controls relative to output. They are controls that have direct effect on the output, controls that indirectly control output and controls that are receiver controls.

### ■ Direct Controls

It is possible to control, if necessary, the acoustic output with the menu control. In this case, the maximum value of the acoustic output never exceeds an MI of 1.9, TI of 6 and an  $I_{SPTA,3}$  of 720 mW/cm<sup>2</sup> in any mode of operation.

### ■ Indirect Controls

The controls that indirectly affect output are many imaging parameters. These are operating modes, frequency, focal point positions, image depth and pulse repetition frequency (PRF).

The operating mode determines whether the ultrasound beam is scanning or non-scanning. Thermal bioeffect is closely connected to M mode.

Acoustic attenuation of tissue is directly related to transducer frequency.

The focal point is related to active aperture of transducer and beam width.

For the higher PRF (pulse repetition frequency), the more output pulses occur over a period of time.

### ■ Receiver Controls

The receiver controls (for example, gain, dynamic range, and image post-processing, etc.) do not affect output. These controls should be used, when possible, to improve the image quality before using controls that directly or indirectly affect output.

## 14.7 Acoustic Output

### 14.7.1 Derated Ultrasonic Output Parameters

In order to determine the relevant Ultrasonic Output Parameters, a method is used which allows for the comparison of ultrasound systems which operate at different frequencies and are focused at different depths. This approach, called "derating" or "attenuating", adjusts the acoustic output as measured in a water tank to account for the effect of ultrasound propagation through tissue. By convention, a specific average intensity attenuation value is used, which corresponds to a loss of 0.3 dB/cm/MHz. That is, the intensity of ultrasound will be reduced by 0.3 dB/MHz for every centimeter of travel from the transducer. This can be expressed by the following equation:

$$I_{atten} = I_{water} \times 10^{(-0.3/10 \times f_c \times z)}$$

Where  $I_{atten}$  is the attenuated intensity,  $I_{water}$  is the intensity measured in a water tank (at distance  $z$ ),  $f_c$  is the center frequency of the ultrasound wave (as measured in water), and  $z$  is the distance from the transducer. The equation for attenuating pressure values is similar except that the attenuation coefficient is 0.15 dB/cm/MHz, or one-half the intensity coefficient. The intensity coefficient is double the pressure coefficient because intensity is proportional to the square of pressure.

Although the attenuation coefficient chosen, 0.3 dB/cm/MHz, is significantly lower than any specific solid tissue in the body, this value was chosen to account for fetal examinations. In early trimester ultrasound fetal examinations, there may be a significant fluid path between the transducer and the fetus, and the attenuation of fluid is very small. Therefore the attenuation coefficient was lowered to account for this case.

## 14.7.2 Limits of Acoustic Output

In accordance with the FDA Track 3 requirements, the derating (or attenuated) approach was incorporated into the FDA Acoustic Output Limits, as listed below. The maximum acoustic output level from any transducer in any operating mode is expected to fall below these limits.

FDA Maximum Acoustic Output Limits for Track 3 (Attenuated Values)

Application	$I_{spta.3}$ (mW/cm <sup>2</sup> )	$I_{sppa.3}$ (W/cm <sup>2</sup> )	MI
Regions (except eyes)	720	≤ 190	≤ 1.9

## 14.7.3 Differences between Actual and Displayed MI and TI

In operation, the system will display to the operator the Acoustic Output Parameters Thermal Index, TI, or Mechanical Index, MI (or sometimes both parameters simultaneously). These parameters were developed as general indicators of risk from either thermal or mechanical action of the ultrasound wave. They serve to indicate to the operator whether a particular setting of the system increases or decreases the possibility of Thermal or Mechanical effect. More specifically, they were designed to assist in the implementation of the ALARA principle. As an operator changes a given system control, the potential effect of the change in output will be indicated. However, the Thermal Index is not the same as temperature rise in the body, for several reasons. First of all, in order to provide a single display index to you, a number of simplifying assumptions had to be made. The biggest assumption was the use of the attenuating formula described above, which is much lower than the actual value for most tissues within the body. Scanning through muscle or organ tissue, for example, will produce much higher attenuation than 0.3 dB/cm/MHz. There were also significant simplifications made for the thermal properties of tissue. Therefore, scanning through highly perfused tissue, such as the heart or vasculature, will produce significantly less thermal effect than that suggested by the Thermal Index.

Similarly, the Mechanical Index was derived to indicate the relative possibility of mechanical (cavitation) effects. The MI is based on the derated peak-rarefactional pressure and the center frequency of the ultrasound wave. The actual peak-rarefactional pressure is affected by the actual attenuation caused by tissue in the path between the transducer and the focal point. Again, all solid tissues within the body have higher attenuation than the proscribed 0.3 dB/cm/MHz value, and therefore, the actual peak-rarefactional pressure will be lower. Further, the actual peak-rarefactional pressure will change depending upon the region of the body being scanned.

For these reasons, the TI and MI displays should only be used to assist the operator in implementing ALARA at the time of the animal examination.

## 14.8 Measurement Uncertainty

Acoustic Quantities	Total Uncertainties (Standard)	
Power	31.97% for non-scan modes; 18.98% for scan modes.	
Frequency	0.22%	
Pressure	15.79%	
$I_{ta}$	31.97% for non-scan modes; 32.35% for scan modes.	
$I_{pa}$	31.98%	
Mechanical Index	15.79 %	
	Non-scan Modes	Scan-Modes
Total Uncertainty for TIS	31.97%	18.98%
Total Uncertainty for TIB	31.97% or 22.61%	18.98%
Total Uncertainty for TIC	31.97%	18.98%

## 14.9 References for Acoustic Power and Safety

1. "Bioeffects and Safety of Diagnostic Ultrasound" issued by AIUM in 1993
2. "Medical Ultrasound Safety" issued by AIUM in 1994
3. Marketing Clearance of Diagnostic Ultrasound Systems and Transducers, June 27, 2019. Center for Devices and Radiological Health.
4. Medical electrical equipment-Part 2-37: Particular requirements for the basic safety and essential performance of ultrasonic medical diagnostic and monitoring equipment issued by IEC in 2015
5. IEC 62359, Ultrasonics-Field characterization-Test methods for the determination of thermal and mechanical indices related to medical diagnostic ultrasonic fields, 2017.

# 15 EMC Guidance and Manufacturer's Declaration

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The system complies with the EMC standard IEC 60601-1-2: 2014.

Intended Environments: HOME HEALTHCARE ENVIRONMENT (except for near active HF SURGICAL EQUIPMENT and the RF shielded room of an ME SYSTEM for magnetic resonance imaging).

- WARNING:**
1. The use of unapproved accessories may diminish system performance.
  2. Use of components, accessories, probes, and cables other than those specified may result in increased emission or decreased immunity of system.
  3. Operation of system, in the case that the patient physiological signal is lower than the minimum amplitude or value specified in the product specifications, results may not be obtained (results can be obtained when the HR is in the range of 30-250 bmp or when the QRS wave amplitude is between 0.5-5 mV.)
  4. Use of this equipment adjacent to or stacked with other equipment should be avoided because it could result in improper operation. If such use is necessary, this equipment and the other equipment should be observed to verify that they are operating normally.
  5. Use of accessories, transducers and cables other than those specified or provided by the manufacturer of this equipment could result in increased electromagnetic emissions or decreased electromagnetic immunity of this equipment and result in improper operation.
  6. Portable RF communications equipment (including peripherals such as antenna cables and external antennas) should be used no closer than 30 cm (12 inches) to any part of the system, including cables specified by the manufacturer. Otherwise, degradation of the performance of this equipment could result.

- NOTE:**
- 1 The system needs special precautions regarding EMC and needs to be installed and put into service according to the EMC information provided below.
  - 2 Other devices may interfere with this system even though they meet the requirements of **CISPR**.
  - 3 Preventing conducted RF immunity. Due to technological limitations, the conducted RF immunity level are limited to 3Vrms level, conducted RF interference above 3Vrms may cause wrong diagnosis and measurements. We suggest that you position system further from sources of conducted RF noise.

4 Portable and mobile RF communications equipment can affect system. See tables 1, 2, 3, and 4 below.

If the system is operated within the electromagnetic environment listed in Table 2 and Table 3, the system will remain safe and will provide the following basic performances:

- Imaging;
- Doppler acoustic spectral displaying;
- Taking measurements;
- Patient information;
- Date/time information.

TABLE 1

<b>GUIDANCE AND MINDRAY DECLARATION—ELECTROMAGNETIC EMISSIONS</b>		
The system is intended for use in the electromagnetic environment specified below. The customer or the user of system should assure that it is used in such an environment.		
<b>EMISSIONS TEST</b>	<b>COMPLIANCE</b>	<b>ELECTROMAGNETIC ENVIRONMENT—GUIDANCE</b>
RF emissions CISPR 11	Group 1	The system uses RF energy only for its internal function. Therefore, its RF emissions are very low and are not likely to cause any interference in nearby electronic equipment.
RF emissions CISPR 11	Class B	The system is suitable for use in all establishments including domestic establishments and those directly connected to the public low-voltage power supply network that supplies buildings used for domestic purposes
Harmonic Emissions IEC 61000-3-2	Class A	
Voltage Fluctuations/ Flicker Emissions IEC 61000-3-3	Compliance	



TABLE 2

<b>GUIDANCE AND MINDRAY DECLARATION—ELECTROMAGNETIC IMMUNITY</b>			
The system is intended for use in the electromagnetic environment specified below. The customer or the user of system should assure that it is used in such an environment.			
<b>IMMUNITY TEST</b>	<b>IEC 60601 TEST LEVEL</b>	<b>COMPLIANCE LEVEL</b>	<b>ELECTROMAGNETIC ENVIRONMENT-GUIDANCE</b>
Electrostatic Discharge(ESD) IEC 61000-4-2	±8 kV contact; ±15 kV air	±8 kV contact; ±15kV air	Floors should be wood, concrete or ceramic tile. If floors are covered with synthetic material, the relative humidity should be at least 30%.
Electrical fast Transient / burst IEC 61000-4-4	±2 kV for power supply lines; ±1 kV for input/output lines	±2 kV for power supply lines; ±1 kV for input/output lines	Mains power quality should be that of a typical commercial or hospital environment.
Surge IEC 61000-4-5	±1 kV line(s) to line(s); ±2 kV line(s) to earth	±1 kV line(s) to line(s); ±2 kV line(s) to earth	Mains power quality should be that of a typical commercial or hospital environment.
Voltage dips, Short interruptions and voltage variation on power supply input voltage IEC 61000-4-11	0 % UT; 0,5 cycle At 0°, 45°, 90°, 135°, 180°, 225°, 270° and 315°  0 % UT; 1 cycle 70% UT for 25/30 cycle at 0°  0 % UT; 250/300 cycle	0 % UT; 0,5 cycle At 0°, 45°, 90°, 135°, 180°, 225°, 270° and 315°  0 % UT; 1 cycle 70% UT for 25/30 cycle at 0°  0 % UT; 250/300 cycle	Mains power quality should be that of a typical commercial or hospital environment. If you require continued operation during power mains interruptions, it is recommended that our product be powered from an uninterruptible power supply or a battery.
Power frequency (50/60 HZ) magnetic field IEC 61000-4-8	30 A/m	30 A/m	Power frequency magnetic fields should be at levels characteristic of a typical location in a typical commercial or hospital environment.
NOTE: $U_T$ is the A.C. mains voltage prior to application of the test level.			

TABLE 3


<b>GUIDANCE AND MINDRAY DECLARATION—ELECTROMAGNETIC IMMUNITY</b>			
The system is intended for use in the electromagnetic environment specified below. The customer or the user of system should assure that it is used in such an environment.			
<b>IMMUNITY TEST</b>	<b>IEC 60601 TEST LEVEL</b>	<b>COMPLIANCE LEVEL</b>	<b>ELECTROMAGNETIC ENVIRONMENT-GUIDANCE</b>
Conducted RF IEC 61000-4-6	3 Vrms 0,15 MHz – 80 MHz 6 Vrms in ISM and amateur radio bands between 0,15 MHz and 80 MHz	3 Vrms 0,15 MHz – 80 MHz 6 Vrms in ISM and amateur radio bands between 0,15 MHz and 80 MHz	Portable and mobile RF communications equipment should be used no closer to any part of system, including cables, than the recommended separation distance calculated from the equation applicable to the frequency of the transmitter. Recommended separation distance $d = 1.2 \times \sqrt{P}$
Radiated RF IEC 61000-4-3	10 V/m 80MHz - 2.7GHz	10 V/m 80MHz - 2.7GHz	$d = 1.2 \times \sqrt{P}$ 80 MHz to 800 MHz $d = 2.3 \times \sqrt{P}$ 800 MHz to 2.7GHz Where, P is the maximum output power rating of the transmitter in watts (W) according to the transmitter manufacturer and d is the recommended separation distance in meters (m).
Proximity fields from RF wireless communications equipment IEC 61000-4-3	27 V/m 380–390 MHz	27 V/m	Field strengths from fixed RF transmitters, as determined by an electromagnetic site survey, should be less than the compliance level in each frequency range. Interference may occur in the vicinity of equipment marked with the following symbol: 
	28 V/m 430–470 MHz, 800–960 MHz, 1700–1990 MHz, 2400–2570 MHz	28 V/m	
	9 V/m 704–787 MHz, 5100–5800 MHz	9 V/m	
<p><b>Note 1</b> At 80 MHz and 800 MHz, the higher frequency range applies.</p> <p><b>Note 2</b> These guidelines may not apply in all situations. Electromagnetic propagation is affected by absorption and reflection from structures, objects and people.</p>			
<p><b>a</b> Field strengths from fixed transmitters, such as base stations for radio (cellular /cordless) telephones and land mobile radios, amateur radio, AM and FM radio broadcast and TV broadcast cannot be predicted theoretically with accuracy. To assess the electromagnetic environment due to fixed RF transmitters, an electromagnetic site survey should be considered. If the measured field strength in the location in which system is used exceeds the applicable RF compliance level above, system should be observed to verify normal operation. If abnormal performance is observed, additional measures may be necessary, such as reorienting or relocating the system.</p> <p><b>b</b> Over the frequency range 150kHz to 80MHz, field strengths should be less than 3V/m.</p>			

TABLE 4

<b>RECOMMENDED SEPARATION DISTANCES BETWEEN PORTABLE AND MOBILE RF COMMUNICATION DEVICE AND THE SYSTEM</b>			
The system is intended for use in an electromagnetic environment in which radiated RF disturbance are controlled. The customer or the user of system can help prevent electromagnetic interference by maintaining a minimum distance between portable and mobile RF communication equipment (transmitters) and system as recommended below, according to the maximum output power of the communication equipment.			
<b>Rated Maximum Output power of Transmitter (W)</b>	<b>Separation Distance According to Frequency of Transmitter (m)</b>		
	150kHz -80MHz $d=1.2\sqrt{P}$	80MHz-800MHz $d=1.2\sqrt{P}$	800MHz-2.7GHz $d=2.3\sqrt{P}$
0.01	0.12	0.12	0.23
0.1	0.38	0.38	0.73
1	1.2	1.2	2.3
10	3.8	3.8	7.3
100	12	12	23
<p>For transmitters at a maximum output power not listed above, the recommended separation distance in meters (m) can be determined using the equation applicable to the frequency of the transmitter, where P is the maximum output power rating of the transmitter in watts (W) according to the transmitter manufacturer.</p> <p>If system image distortion occurs, it may be necessary to position system further from sources of conducted RF noise or to install external power source filter to minimize RF noise to an acceptable level.</p> <p>Note 1 At 80 MHz and 800 MHz, the separation distance for the higher frequency range applies.</p> <p>Note 2 These guidelines may not apply in all situations. Electromagnetic propagation is affected by absorption and reflection from structures, objects and people.</p>			

## Cable sample


No.	Name	Cable length (m)	Shield or not	Remarks
1	Power input	2.5m	Not shielded	/
2	SIP/SOP	<3.0m	Shielding	/
3	Probe Cable	<3.0m	Shielding	/
4	Footswitch Cable	2.9m	Shielding	/



# 16 System Maintenance

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Routine system maintenance shall be carried out by the user. Service maintenance will be provided by Mindray service engineers while the system is under warranty. System maintenance after the warranty has expired is the full responsibility of the owner / operator.

- |   |  |
|---|--|
|  <b>WARNING:</b> | <ol style="list-style-type: none"><li>1. Only an authorized Mindray service engineer can perform maintenance not specified in this operator's manual.</li><li>2. For the sake of the system performance and safety, you should perform periodical checks for the system.</li></ol> |
|---|--|

## 16.1 Daily Maintenance

You are responsible for daily maintenance.

### 16.1.1 Cleaning the System

- |   |  |
|---|--|
|  <b>WARNING:</b> | Before cleaning the system, be sure to turn off the power and disconnect the power cord from the outlet. If you clean the system while the power is "On", it may result in electric shock. |
|---|--|

- Cleaning the probe  
Please refer to the operator's manual of the corresponding transducer or "12.1.5 Probes Cleaning and Disinfection" to perform cleaning and disinfection.
- Cleaning the probe cable
  - a) Use soft dry cloth to wipe off stains from the probe cable.
  - b) If it is difficult to clean the stains thoroughly, use soft cloth dipped with mild detergent, and then let the cable air dry.
- Cleaning the monitor  
Using a soft cloth, apply a glass cleaner directly to the cloth and wipe down the monitor to remove finger marks, dust and smudges. Allow the monitor to air-dry.

- |              |  |
|--------------|--|
| <b>NOTE:</b> | <ol style="list-style-type: none"><li>1. Do not use hydrocarbon glass cleaner or cleaner for OA (Office Automation) equipment to clean the monitor. These substances may cause deterioration of the monitor.</li><li>2. Keyboard on the control panel should be cleaned periodically, otherwise, keys maybe blocked by dirt and buzzer dings, keys don't work.</li></ol> |
|--------------|--|

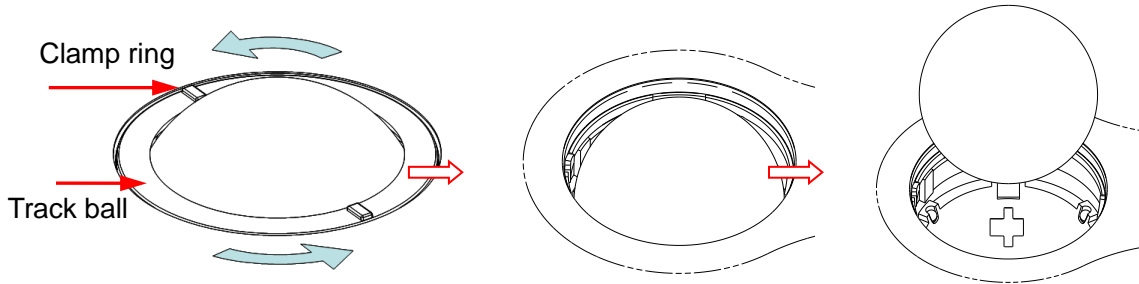
- Cleaning the control panel, cover and bracket  
Use dry soft cloth to clean the surface of the system. If the system is dirty, moisten the soft cloth with a mild or neutral detergent and wipe off any stains. Use dry soft cloth to remove any moisture and allow all hard surfaces to completely air-dry.
- Cleaning the trackball
  - Tool: tissue paper or dry cotton cloth

- Method:

The trackball on the control panel is used to move the cursor and plays an importance part in man-machine communication. As one of the most frequently used parts on the control panel, it may become ineffective due to dirt that enters into the trackball module.

a) Disassembling the trackball:

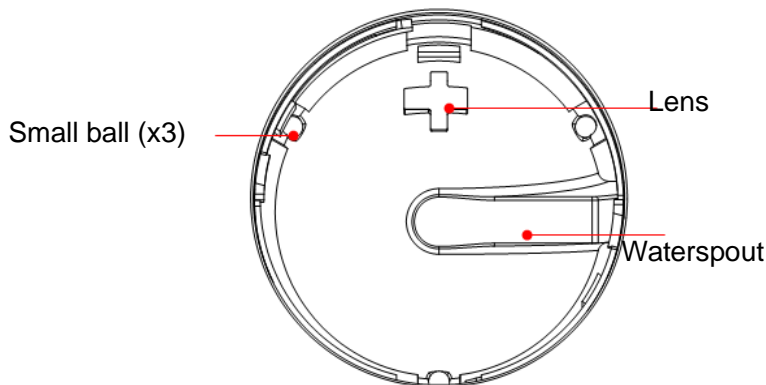
Rotate the trackball clamp ring 35 degrees anticlockwise. When the clamping ring lifts, remove the clamping ring and trackball. You can draw out the ball with the help of adhesive tape. See the figures below.



Rotate clamp ring 35 degrees anticlockwise    Remove clamp ring    Draw out the ball

b) Cleaning

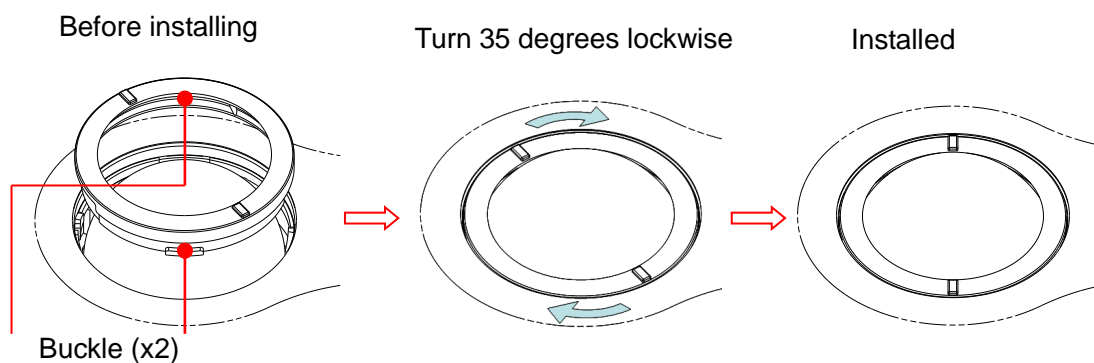
Clean the lens slightly using the tissue until there is no foreign matter. Then clean the other parts and the dust excluder. Make sure to exert force properly when clean the small ball, otherwise, the small ball may drop down. See the figure below. No system shutdown is required during the whole clean. Reinstall the ball and clamp ring after the clean is finished.



When liquid is spray onto the trackball area, most of the liquid can be discharged through the waterspout, besides, you can dry the leaving water using the tissue or cloth.

c) Installing the trackball

Put back the ball, align the buckle with gap of the front cover, press the clamp ring with both hands and rotate it 35 degrees clockwise to click the buckle. At this moment, the clamp ring cannot be moved any further, it indicates that the clamp ring clicks in position. See the figure below. See figure below.



### 16.1.2 Checking Transducer

Check the transducer connector for crack every time before use. DO NOT use the transducer if a crack is inspected. A thoroughly inspection to the transducer including cable and connector is required every time when you clean the transducer.

### 16.1.3 Backup of the System Hard Drive

To prevent deterioration or loss of data stored in the system hard drive, create a backup copy of the hard drive at regular intervals.

## 16.2 Maintenance Checks by Service Engineer

The following checks must be performed to ensure and maintain system safety and performance. Please contact Mindray Customer Service Department or sales representative to schedule and carry out these checks.

Check Category	Check Item
Cleaning	Interior of the system Peripherals
Electric safety	Ground leakage current Enclosure leakage current Patient leakage current Patient leakage current (110% supply voltage on applied part) Patient auxiliary leakage current
Mechanical safety	Monitor mounting mechanism Control panel Mounting mechanism for the peripheral devices Check other mechanical structures Check the transducer appearance
Image recording	Images in each mode Image recording by using the standard probe

## 16.3 Consumables and Periodic Part Replacement


This system contains some consumables and parts requiring periodic replacement.

Before replacing them, please contact Mindray Customer Service Department or sales representative for instructions.

## 16.4 Troubleshooting

To ensure proper system operation and function, it is recommended that a maintenance and inspection plan be established to periodically check the safety of the system. If any system malfunction is experienced, contact Mindray Customer Service Department or sales representative.

If any persistent system malfunction is experienced, e.g. an onscreen error message, blank imaging screen, absent menus, please refer to the following table below. If the failure cannot be eliminated, please contact Mindray Customer Service Department or sales representative.

- |   |  |
|---|--|
|  <b>CAUTION:</b> | <ol style="list-style-type: none"><li><b>1. Do not spill water or other liquid into the system while you perform the cleaning. Otherwise it may result in malfunction or electric shock.</b></li><li><b>2. When you want to clean probe connectors and TGC sliders, contact Mindray Customer Service Department or sales representative. Cleaning it yourself may result in malfunction or degradation of the performance.</b></li></ol> |
|---|--|



■ Troubleshooting Table

No.	Failure	Cause	Measure
1	After the power supply is turned on, the power indicator does not light on.	<ul style="list-style-type: none"> <li>■ Abnormal power system or incorrect connection of the power cord.</li> </ul>	<ul style="list-style-type: none"> <li>■ Verify that the plug has not become loosened or dislodged from the back of the system.</li> </ul>
2	When the power indicator of the monitor is on and image is blank.	<ul style="list-style-type: none"> <li>■ The interval between turnoff and restart is too short – wait a minimum time of 20 seconds.</li> <li>■ The monitor brightness or contrast may be improperly set.</li> </ul>	<ul style="list-style-type: none"> <li>■ Turn off the system and wait a minimum time of 1 minute, then restart the system.</li> <li>■ Adjust the Contrast</li> </ul>
3	The monitor displays the characters but no images.	<ul style="list-style-type: none"> <li>■ The transmission power, overall gain or TGC controls are improperly set.</li> <li>■ Verify that a probe is connected and / or fully connected.</li> <li>■ The system is in the frozen status.</li> </ul>	<ul style="list-style-type: none"> <li>■ Adjust the transmission power, gain or TGC control.</li> <li>■ Ensure proper probe connection.</li> <li>■ Unfreeze the image.</li> </ul>
4	The image quality has degraded	<ul style="list-style-type: none"> <li>■ The exam mode is not correct.</li> <li>■ The settings of the image post processing are not correct.</li> <li>■ The image presets are inappropriate</li> </ul>	<ul style="list-style-type: none"> <li>■ Select an appropriate exam type.</li> <li>■ Adjust the settings of the image via post processing or reset the post processing to the default values.</li> <li>■ Reset the factory default setups.</li> </ul>
5	The button is responseless with the system buzzing	<ul style="list-style-type: none"> <li>■ Button blocked by too much dirt</li> </ul>	<ul style="list-style-type: none"> <li>■ Check the control panel for the button being blocked and press it several times to release it.</li> <li>■ Clean the button</li> </ul>



# Appendix A Electrical Safety

## Inspection

The following electrical safety tests are recommended as part of a comprehensive preventive maintenance program. They are a proven means of detecting abnormalities that, if undetected, could prove dangerous to either the animal or the operator. Additional tests may be required according to local regulations.

All tests can be performed using commercially available safety analyzer test equipment. These procedures assume the use of a 601PROXL International Safety Analyzer or equivalent safety analyzer. Other popular testers complying with IEC 60601-1 used in Europe such as Fluke, Metron, or Gerb may require modifications to the procedure. Follow the instructions of the analyzer manufacturer.

**The electrical safety inspection should be periodically performed every two years.** The safety analyzer also proves to be an excellent troubleshooting tool to detect abnormalities of line voltage and grounding, as well as total current loads.

### A.1 Power Cord Plug

#### A.1.1 The Power Plug

Test Item		Acceptance Criteria
The power plug	The power plug pins	No broken or bent pin. No discolored pins.
	The plug body	No physical damage to the plug body.
	The strain relief	No physical damage to the strain relief. No plug warmth for device in use.
	The power plug	No loose connections.
The power cord		No physical damage to the cord. No deterioration to the cord.
		For devices with detachable power cords, inspect the connection at the device.
		For devices with non-detachable power cords, inspect the strain relief at the device.

## A.2 Device Enclosure and Accessories

### A.2.1 Visual Inspection

Test Item	Acceptance Criteria
The enclosure and accessories	No physical damage to the enclosure and accessories.
	No physical damage to meters, switches, connectors, etc.
	No residue of fluid spillage (e.g., water, coffee, chemicals, etc.).
	No loose or missing parts (e.g., knobs, dials, terminals, etc.).

### A.2.2 Contextual Inspection

Test Item	Acceptance Criteria
The enclosure and accessories	No unusual noises (e.g., a rattle inside the case).
	No unusual smells (e.g., burning or smoky smells, particularly from ventilation holes).
	No taped notes that may suggest device deficiencies or operator concerns.

## A.3 Device Labeling

Check the labels provided by the manufacturer or the healthcare facility are present and legible.

- Main unit label
- Integrated warning labels

## A.4 Protective Earth Resistance

a. Plug the probes of the analyzer into the device's protective earth terminal and protective earth terminal of the AC power cord.

b. Test the earth resistance with a current of 25 A.

c. Verify the resistance is less than limits.

### ■ LIMITS

ALL COUNTRIES R = 0.2  $\Omega$  Maximum

## A.5 Earth Leakage Test

Run an Earth Leakage test on the device being tested before performing any other leakage tests.

The following outlet conditions apply when performing the Earth Leakage test.

- normal polarity (Normal Condition);
- reverse polarity (Normal Condition);
- normal polarity with open neutral (Single Fault Condition);
- reverse polarity with open neutral (Single Fault Condition).

### ■ LIMITS

For UL60601-1,

- 300  $\mu$ A in Normal Condition.
- 1000  $\mu$ A in Single Fault Condition.

For IEC60601-1,

- 500  $\mu$ A in Normal Condition.
- 1000  $\mu$ A in Single Fault Condition.

## A.6 Enclosure Leakage Test

The following outlet conditions apply when performing the Enclosure Leakage test.

- normal polarity (Normal Condition);
- reverse polarity (Normal Condition);
- normal polarity with open neutral (Single Fault Condition);
- reverse polarity with open neutral (Single Fault Condition);
- normal polarity with open earth (Single Fault Condition);
- reverse polarity with open earth (Single Fault Condition).

### ■ LIMITS

For UL60601-1,

- 100 $\mu$ A in Normal Condition.
- 300  $\mu$ A in Single Fault Condition.

For IEC60601-1:

- 100 $\mu$ A in Normal Condition.
- 500  $\mu$ A in Single Fault Condition.

## A.7 Patient Leakage Current

Patient leakage currents are measured between a selected applied part and mains earth. All measurements have a true RMS only.

The following outlet conditions apply when performing the Patient Leakage Current test.

- normal polarity (Normal Condition);
- reverse polarity (Normal Condition);
- normal polarity with open neutral (Single Fault Condition);
- reverse polarity with open neutral (Single Fault Condition);
- normal polarity with open earth (Single Fault Condition);
- reverse polarity with open earth (Single Fault Condition).

■ LIMITS

For BF  applied parts,

- 100µA in Normal Condition.
- 500µA in Single Fault Condition.

## A.8 Mains on Applied Part Leakage

The Mains on Applied Part test applies a test voltage, which is 110% of the mains voltage, through a limiting resistance, to selected applied part terminals. Current measurements are then taken between the selected applied part and earth. Measurements are taken with the test voltage (110% of mains) to applied parts in the normal and reverse polarity conditions.

The following outlet conditions apply when performing the Mains on Applied Part test.

- Normal Polarity;
- Reversed Polarity.

■ LIMITS

- For BF  applied parts: 5000 µA.

## A.9 Patient Auxiliary Current

Patient Auxiliary currents are measured between any selected Applied Part connector and the remaining Applied Part connectors. All measurements may have a true RMS only response.

The following outlet conditions apply when performing the Patient Auxiliary Current test.

- normal polarity (Normal Condition);
- reverse polarity (Normal Condition);
- normal polarity with open neutral (Single Fault Condition);
- reverse polarity with open neutral (Single Fault Condition);
- normal polarity with open earth (Single Fault Condition);
- reverse polarity with open earth (Single Fault Condition).

■ LIMITS

For BF  applied parts,

- 100µA in Normal Condition.
- 500µA in Single Fault Condition.

**Note:** Make sure the safety analyzer is authorized comply with requirement of IEC60601-1. Follow the instructions of the analyzer manufacturer.

# Appendix B Transducer Maximum Surface Temperature

According to the requirements of the section 201.11 in the standard IEC 60601-2-37: 2015, the transducer surface temperature has been tested in two kinds of conditions: the transducer suspended in still air or transducer contacting human-tissue mimicking material.

\* The measurement data were obtained under the test conditions employed at Mindray.

Transducer model	Maximum surface temperature (°C) Contacting TMM	Maximum surface temperature (°C) Suspending in air
10L24EA	40.6	32.8
35C20EA	39.8	33.5
35C50EA	39.2	35.0
65C15EA	40.6	34.2
65EB10EA_T	41.4	30.3
65EB10EA_S	41.3	29.9
65EC10ED	41.1	29.5
65EL60EA	40.7	30.2
75L38EA	40.6	34.1
75L53EA	39.6	30.8
75LT38EA	39.8	28.3
50L60EAV	37.6	32.8
75L50EAV	40.4	31.6





# **Appendix C Acoustic Output Reporting Table (60601- 2-37)**



Transducer Model: 10L24EA

Imaging Mode: B-mode/Smart3D /iScape/Tissue Harmonic Imaging

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		1.06	0.09		0.21		0.21
Index component value			0.09	0.09	0.21	0.09	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	2.84					
	$P$ (mW)		10.00		10.00		10.00
	$P_{1 \times 1}$ (mW)		2.60		2.60		
	$Z_s$ (cm)			/			
	$Z_b$ (cm)					/	
	$Z_{MI}$ (cm)	0.98					
	$Z_{pii,\alpha}$ (cm)	0.98					
	$f_{awf}$ (MHz)	7.23	7.10		6.99		7.02
Other Information	$p_{rr}$ (Hz)	5,096.00					
	$s_{rr}$ (Hz)	41.00					
	$n_{pps}$	1.33					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ (W/cm <sup>2</sup> )	251.99					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	5.13					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ (mW/cm <sup>2</sup> )	9.20					
	$p_r$ at $Z_{pii}$ (MPa)	3.54					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	12.9cm	12.9cm		12.9cm		12.9cm
	Focus position	2.0cm	10.0cm		10.0cm		10.0cm
	Working Frequency	10	10		10		10
	PRF	5096	5096		5096		5096

Transducer Model: 10L24EA

Imaging Mode: B+M-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		1.06	0.16		0.51		0.32
Index component value			0.16	0.14	0.15	0.51	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	2.85					
	$P$ (mW)		13.65		12.59		13.66
	$P_{1 \times 1}$ (mW)		4.77		5.19		
	$Z_s$ (cm)			1.00			
	$Z_b$ (cm)					0.69	
	$Z_{MI}$ (cm)	0.88					
	$Z_{pii,\alpha}$ (cm)	0.88					
	$f_{awf}$ (MHz)	7.28	7.15		6.05		7.16
Other Information	$prr$ (Hz)	4,000.00					
	$srr$ (Hz)	32.00					
	$n_{pps}$	1.33					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ (W/cm <sup>2</sup> )	241.74					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	3.73					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ (mW/cm <sup>2</sup> )	6.70					
	$p_r$ at $Z_{pii}$ (MPa)	3.24					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	12.9cm	12.9cm		6.5cm		12.9cm
	B/M Focus position	2.0cm	10.0cm		1.0cm		10.0cm
	B/M Working Frequency	10	10		H12.0		10
	B PRF	4000	4000		6000		4000
	M PRF	1000	1000		3000		1000

Transducer Model: 10L24EA

Imaging Mode: PW-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		1.03	0.27		0.78		0.41
Index component value			0.27	0.18	0.43	0.78	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	2.62					
	$P$ (mW)		9.82		5.81		9.83
	$P_{1 \times 1}$ (mW)		9.82		5.81		
	$Z_s$ (cm)			1.00			
	$Z_b$ (cm)					0.79	
	$Z_{MI}$ (cm)	0.73					
	$Z_{pii,\alpha}$ (cm)	0.73					
	$f_{awf}$ (MHz)	6.48		5.73		5.77	
Other Information	$p_{rr}$ (Hz)	699.00					
	$s_{rr}$ (Hz)	/					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ ( $W/cm^2$ )	239.67					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ ( $mW/cm^2$ )	94.92					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ ( $mW/cm^2$ )	159.10					
	$p_r$ at $Z_{pii}$ (MPa)	3.09					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	12.9cm	12.9cm		6.5cm		12.9cm
	SV Position	2.5cm	10.0cm		1.0cm		10.0cm
	Working Frequency	6.6	5.7		5.7		5.7
	PRF	699	6300		14000		6300
	SV	0.5mm	0.5mm		0.5mm		0.5mm

Transducer Model: 10L24EA

Imaging Mode: B+PW-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.99	0.19		1.04		0.78
Index component value			0.19	0.15	0.23	1.04	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	2.36					
	$P$ (mW)		11.94		12.50		26.85
	$P_{1 \times 1}$ (mW)		6.03		8.07		
	$Z_s$ (cm)			1.00			
	$Z_b$ (cm)					0.79	
	$Z_{MI}$ (cm)	0.79					
	$Z_{pii,\alpha}$ (cm)	0.79					
	$f_{awf}$ (MHz)	5.75	7.05		7.11		7.15
Other Information	$p_{rr}$ (Hz)	699.00					
	$s_{rr}$ (Hz)	58.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ ( $W/cm^2$ )	251.55					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ ( $mW/cm^2$ )	111.04					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ ( $mW/cm^2$ )	157.37					
	$p_r$ at $Z_{pii}$ (MPa)	2.67					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	6.5cm	12.9cm		12.9cm		12.9cm
	B Focus Position	1.0cm	10.0cm		1.0cm		10.0cm
	SV Position	1.0cm	10.0cm		1.0cm		10.0cm
	B Working Frequency	8	10		8		8
	PW Working Frequency	5.7	6.6		5.7		5.7
	B PRF	7695	4199		1258		1258
	PW PRF	699	699		3595		3595
	PW SV	0.5mm	0.5mm		0.5mm		0.5mm

C-6 Acoustic Output Reporting Table (60601-2-37)

Transducer Model: 10L24EA

Imaging Mode: Color+B-Mode / Power+B-Mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		1.08	0.84		0.84		2.26
Index component value			0.84	0.84	0.84	0.84	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	2.60					
	$P$ (mW)		110.30		111.10		109.70
	$P_{1 \times 1}$ (mW)		28.72		28.93		
	$z_s$ (cm)			/			
	$z_b$ (cm)					/	
	$Z_{MI}$ (cm)	0.69					
	$Z_{pii,\alpha}$ (cm)	0.69					
	$f_{awf}$ (MHz)	5.74	7.15		7.03		7.25
Other Information	$p_{rr}$ (Hz)	4,174.00					
	$s_{rr}$ (Hz)	15.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ (W/cm <sup>2</sup> )	330.88					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	9.40					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ (mW/cm <sup>2</sup> )	12.38					
	$p_r$ at $Z_{pii}$ (MPa)	2.98					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	8.3cm	8.3cm		8.3cm		8.3cm
	B Focus Position	1.5cm	5.0cm		5.0cm		5.0cm
	Color Sampling Gate Position	1.5cm	5.0cm		5.0cm		5.0cm
	B Working Frequency	8	8		8		8
	C Working Frequency	5.7	5.7		5.7		5.7
	B PRF	5003	4295		4295		4295
	Color PRF	4174	3768		3768		3768

Transducer Model: 10L24EA

Imaging Mode: Color+B+PW-Mode/Power+B+PW-Mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.95	1.25		1.96		2.76
Index component value			1.25	1.18	1.25	1.96	
Acoustic Parameters	$p_{r,\alpha}$ at $z_{MI}$ (MPa)	2.28					
	$P$ (mW)		143.11		148.54		124.59
	$P_{1 \times 1}$ (mW)		41.64		42.93		
	$z_s$ (cm)			1.00			
	$z_b$ (cm)					0.69	
	$z_{MI}$ (cm)	0.60					
	$z_{pii,\alpha}$ (cm)	0.60					
	$f_{awf}$ (MHz)	5.76	6.86		7.05		6.80
Other Information	$p_{rr}$ (Hz)	4,321.00					
	$s_{rr}$ (Hz)	3.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $z_{pii,\alpha}$ (W/cm <sup>2</sup> )	217.09					
	$I_{spta,\alpha}$ at $z_{pii,\alpha}$ or $z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	590.81					
	$I_{spta}$ at $z_{pii}$ or $z_{sii}$ (mW/cm <sup>2</sup> )	769.74					
	$p_r$ at $z_{pii}$ (MPa)	2.53					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	8.3cm	8.3cm		8.3cm		8.3cm
	B Focus Position	1.0cm	5.0cm		1.0cm		5.0cm
	Color SG Position	1.0cm	5.0cm		1.0cm		5.0cm
	PW SV Position	1.0cm	5.0cm		1.0cm		5.0cm
	B Working Frequency	8	8		8		8
	C Working Frequency	5.7	5.7		5.7		5.7
	PW Working Frequency	5.7	6.6		5.7		5.7
	B PRF	1238	749		1238		749
	C PRF	943	1189		943		1189
	PW PRF	4321	4356		4321		4356
	PW SV	0.5mm	0.5mm		0.5mm		0.5mm

C-8 Acoustic Output Reporting Table (60601-2-37)



## C.2 35C20EA

Transducer Model: 35C20EA

Imaging Mode: M-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.84	0.27		1.11		0.60
Index component value			0.25	0.27	0.60	1.11	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	1.32					
	$P$ (mW)		33.77		33.97		34.04
	$P_{1 \times 1}$ (mW)		21.27		21.40		
	$z_s$ (cm)			2.32			
	$z_b$ (cm)					4.24	
	$Z_{MI}$ (cm)	4.63					
	$Z_{pii,\alpha}$ (cm)	4.63					
	$f_{awf}$ (MHz)	2.46	2.45		2.43		2.45
Other Information	$p_{rr}$ (Hz)	1,999.00					
	$s_{rr}$ (Hz)	/					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ ( $W/cm^2$ )	122.12					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ ( $mW/cm^2$ )	203.20					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ ( $mW/cm^2$ )	458.73					
	$p_r$ at $Z_{pii}$ (MPa)	1.95					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	16.6cm	16.6cm		16.6cm		16.6cm
	Focus position	6.0cm	6.0cm		6.0cm		6.0cm
	Working Frequency	H6.0	H6.0		H6.0		H6.0
	PRF	1999	1999		1999		1999

Transducer Model: 35C20EA

Imaging Mode: B-mode/Smart3D/ Tissue Harmonic Imaging

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.84	0.35		0.96		0.96
Index component value			0.35	0.35	0.96	0.35	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	1.32					
	$P$ (mW)		86.00		86.00		86.00
	$P_{1 \times 1}$ (mW)		21.67		21.67		
	$Z_s$ (cm)			/			
	$Z_b$ (cm)					/	
	$Z_{MI}$ (cm)	4.53					
	$Z_{pii,\alpha}$ (cm)	4.53					
	$f_{awf}$ (MHz)	2.45	3.37		3.39		3.38
Other Information	$p_{rr}$ (Hz)	4,073.00					
	$s_{rr}$ (Hz)	33.00					
	$n_{pps}$	1.33					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ ( $W/cm^2$ )	154.65					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ ( $mW/cm^2$ )	9.50					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ ( $mW/cm^2$ )	20.93					
	$p_r$ at $Z_{pii}$ (MPa)	1.84					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	16.6cm	6.5cm		6.5cm		6.5cm
	Focus position	6.0cm	4.0cm		4.0cm		4.0cm
	Working Frequency	H6.0	3.5		3.5		3.5
	PRF	4073	8992		8992		8992

Transducer Model: 35C20EA

Imaging Mode: B+M-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.84	0.52		0.67		1.23
Index component value			0.52	0.48	0.52	0.67	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	1.31					
	$P$ (mW)		100.25		100.42		100.24
	$P_{1 \times 1}$ (mW)		32.06		32.19		
	$Z_s$ (cm)			2.04			
	$Z_b$ (cm)					3.95	
	$Z_{MI}$ (cm)	4.63					
	$Z_{pii,\alpha}$ (cm)	4.63					
	$f_{awf}$ (MHz)	2.45	3.39		3.38		3.38
Other Information	$prr$ (Hz)	2,000.00					
	$srr$ (Hz)	16.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ (W/cm <sup>2</sup> )	150.22					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	187.14					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ (mW/cm <sup>2</sup> )	415.46					
	$p_r$ at $Z_{pii}$ (MPa)	1.75					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	16.6cm	6.5cm		6.5cm		6.5cm
	B/M Focus position	6.0cm	4.0cm		4.0cm		4.0cm
	B/M Working Frequency	H6.0	3.5		3.5		3.5
	B PRF	2000	8000		8000		8000
	M PRF	2000	1000		1000		1000

Transducer Model: 35C20EA

Imaging Mode: PW-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.42	0.37		0.47		1.31
Index component value			0.37	0.33	0.47	0.34	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	0.67					
	$P$ (mW)		38.69		18.38		32.19
	$P_{1 \times 1}$ (mW)		31.20		14.82		
	$Z_s$ (cm)			1.89			
	$Z_b$ (cm)					1.66	
	$Z_{MI}$ (cm)	1.00					
	$Z_{pii,\alpha}$ (cm)	1.00					
	$f_{awf}$ (MHz)	2.51	2.51		2.51		2.51
Other Information	$p_{rr}$ (Hz)	699.00					
	$s_{rr}$ (Hz)	/					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ ( $W/cm^2$ )	16.55					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ ( $mW/cm^2$ )	16.97					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ ( $mW/cm^2$ )	20.18					
	$p_r$ at $Z_{pii}$ (MPa)	0.73					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	16.6cm	16.6cm		16.6cm		6.5cm
	SV Position	14.0cm	16.0cm		10.0cm		4.0cm
	Working Frequency	2.5	2.5		2.5		2.5
	PRF	699	3900		6300		12001
	SV	0.5mm	0.5mm		0.5mm		0.5mm

Transducer Model: 35C20EA

Imaging Mode: B+PW-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.80	0.38		0.47		2.00
Index component value			0.38	0.38	0.30	0.47	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	1.31					
	$P$ (mW)		84.47		59.61		97.21
	$P_{1 \times 1}$ (mW)		23.77		24.79		
	$Z_s$ (cm)			1.08			
	$Z_b$ (cm)					1.66	
	$Z_{MI}$ (cm)	4.72					
	$Z_{pii,\alpha}$ (cm)	4.72					
	$f_{awf}$ (MHz)	2.67		3.37		2.66	
Other Information	$p_{rr}$ (Hz)	993.00					
	$s_{rr}$ (Hz)	7.00					
	$n_{pps}$	1.33					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ ( $W/cm^2$ )	123.18					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ ( $mW/cm^2$ )	1.34					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ ( $mW/cm^2$ )	3.22					
	$p_r$ at $Z_{pii}$ (MPa)	2.03					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	16.6cm	6.5cm		16.6cm		6.5cm
	B Focus Position	6.0cm	4.0cm		10.0cm		4.0cm
	SV Position	6.0cm	4.0cm		10.0cm		4.0cm
	B Working Frequency	2.5	3.5		2.5		2.5
	PW Working Frequency	2.5	3		2.5		2.5
	B PRF	993	7694		1007		2233
	PW PRF	2921	699		2921		6290
	PW SV	0.5mm	0.5mm		0.5mm		0.5mm

Transducer Model: 35C20EA

Imaging Mode: Color+B-Mode / Power+B-Mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.60	0.74		0.75		1.61
Index component value			0.74	0.74	0.75	0.75	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	0.99					
	$P$ (mW)		110.30		111.10		109.70
	$P_{1 \times 1}$ (mW)		49.55		49.86		
	$z_s$ (cm)			/			
	$z_b$ (cm)					/	
	$Z_{MI}$ (cm)	4.63					
	$Z_{pii,\alpha}$ (cm)	4.63					
	$f_{awf}$ (MHz)	2.71	3.50		3.48		2.74
Other Information	$p_{rr}$ (Hz)	2,489.00					
	$s_{rr}$ (Hz)	15.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ (W/cm <sup>2</sup> )	67.73					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	1.81					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ (mW/cm <sup>2</sup> )	4.30					
	$p_r$ at $Z_{pii}$ (MPa)	1.53					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	16.6cm	16.6cm		16.6cm		16.6cm
	B Focus Position	4.0cm	4.0cm		4.0cm		6.0cm
	Color Sampling Gate Position	4.0cm	4.0cm		4.0cm		6.0cm
	B Working Frequency	2.5	3.5		3.5		2.5
	C Working Frequency	2.5	3		3		2.5
	B PRF	2489	2383		2383		2194
	Color PRF	3564	3802		3802		3522

Transducer Model: 35C20EA

Imaging Mode: Color+B+PW-Mode/Power+B+PW-Mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.66	1.09		1.90		2.58
Index component value			1.09	1.05	1.20	1.90	
Acoustic Parameters	$p_{r,\alpha}$ at $z_{MI}$ (MPa)	1.08					
	$P$ (mW)		174.90		182.75		144.46
	$P_{1 \times 1}$ (mW)		91.00		100.99		
	$z_s$ (cm)			1.89			
	$z_b$ (cm)					3.67	
	$z_{MI}$ (cm)	5.01					
	$z_{pii,\alpha}$ (cm)	5.01					
	$f_{awf}$ (MHz)	2.66	2.62		2.62		2.67
Other Information	$p_{rr}$ (Hz)	1,091.00					
	$s_{rr}$ (Hz)	3.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $z_{pii,\alpha}$ (W/cm <sup>2</sup> )	75.17					
	$I_{spta,\alpha}$ at $z_{pii,\alpha}$ or $z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	0.40					
	$I_{spta}$ at $z_{pii}$ or $z_{sii}$ (mW/cm <sup>2</sup> )	1.05					
	$p_r$ at $z_{pii}$ (MPa)	1.61					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	16.6cm	16.6cm		16.6cm		16.6cm
	B Focus Position	6.0cm	16.0cm		14.0cm		6.0cm
	Color SG Position	6.0cm	16.0cm		14.0cm		6.0cm
	PW SV Position	6.0cm	16.0cm		14.0cm		6.0cm
	B Working Frequency	2.5	2.5		2.5		2.5
	C Working Frequency	2.5	2.5		2.5		2.5
	PW Working Frequency	2.5	2.5		2.5		2.5
	B PRF	1091	656		656		1083
	C PRF	957	708		708		957
	PW PRF	2355	2360		2360		2355
	PW SV	0.5mm	0.5mm		0.5mm		0.5mm

## C.3 35C50EA

Transducer Model: 35C50EA

Imaging Mode: M-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		1.04	0.25		0.87		0.52
Index component value			0.19	0.25	0.47	0.87	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	1.64					
	$P$ (mW)		30.81		27.84		41.00
	$P_{1 \times 1}$ (mW)		12.25		15.99		
	$z_s$ (cm)			2.89			
	$z_b$ (cm)					4.82	
	$Z_{MI}$ (cm)	4.72					
	$Z_{pii,\alpha}$ (cm)	4.72					
	$f_{awf}$ (MHz)	2.46	3.34		2.46		2.46
Other Information	$p_{rr}$ (Hz)	1,000.00					
	$s_{rr}$ (Hz)	/					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ ( $W/cm^2$ )	227.67					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ ( $mW/cm^2$ )	181.91					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ ( $mW/cm^2$ )	415.15					
	$p_r$ at $Z_{pii}$ (MPa)	2.24					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	14.8cm	14.8cm		14.8cm		14.8cm
	Focus position	6.0cm	14.0cm		6.0cm		14.0cm
	Working Frequency	H6.0	3.5		H6.0		H6.0
	PRF	1000	1000		1000		1000



Transducer Model: 35C50EA

Imaging Mode: B-mode /Smart3D/Tissue Harmonic Imaging

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.97	0.27		1.00		1.21
Index component value			0.27	0.27	1.00	0.26	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	1.53					
	$P$ (mW)		126.00		126.00		152.00
	$P_{1 \times 1}$ (mW)		16.28		16.28		
	$Z_s$ (cm)			/			
	$Z_b$ (cm)					/	
	$Z_{MI}$ (cm)	4.91					
	$Z_{pii,\alpha}$ (cm)	4.91					
	$f_{awf}$ (MHz)	2.46	3.42		3.39		2.46
Other Information	$p_{rr}$ (Hz)	4,531.00					
	$s_{rr}$ (Hz)	55.00					
	$n_{pps}$	1.33					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ (W/cm <sup>2</sup> )	202.84					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	27.00					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ (mW/cm <sup>2</sup> )	63.70					
	$p_r$ at $Z_{pii}$ (MPa)	2.23					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	14.8cm	14.8cm		14.8cm		14.8cm
	Focus position	6.0cm	13.0cm		13.0cm		14.0cm
	Working Frequency	H6.0	3.5		3.5		H6.0
	PRF	4531	4531		4531		4531

Transducer Model: 35C50EA

Imaging Mode: B+M-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.98	0.52		1.04		1.70
Index component value			0.46	0.52	0.33	1.04	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	1.54					
	$P$ (mW)		162.32		121.17		189.25
	$P_{1 \times 1}$ (mW)		29.12		28.65		
	$Z_s$ (cm)			2.89			
	$Z_b$ (cm)					4.91	
	$Z_{MI}$ (cm)	4.91					
	$Z_{pii,\alpha}$ (cm)	4.91					
	$f_{awf}$ (MHz)	2.46		3.36		2.46	
Other Information	$prr$ (Hz)	1,000.00					
	$srr$ (Hz)	37.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ (W/cm <sup>2</sup> )	212.55					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	172.25					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ (mW/cm <sup>2</sup> )	398.34					
	$p_r$ at $Z_{pii}$ (MPa)	2.23					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	14.8cm	14.8cm		14.8cm		14.8cm
	B/M Focus position	6.0cm	14.0cm		6.0cm		14.0cm
	B/M Working Frequency	H6.0	3.5		H6.0		H6.0
	B PRF	3000	3000		3000		3000
	M PRF	1000	1000		1000		1000

Transducer Model: 35C50EA

Imaging Mode: PW-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.87	0.24		1.02		1.57
Index component value			0.16	0.24	0.66	1.02	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	1.38					
	$P$ (mW)		33.22		34.43		54.04
	$P_{1 \times 1}$ (mW)		13.21		25.43		
	$Z_s$ (cm)			2.89			
	$Z_b$ (cm)					2.23	
	$Z_{MI}$ (cm)	0.50					
	$Z_{pii,\alpha}$ (cm)	0.50					
	$f_{awf}$ (MHz)	2.52	2.54		2.54		2.53
Other Information	$p_{rr}$ (Hz)	699.00					
	$s_{rr}$ (Hz)	/					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ ( $W/cm^2$ )	82.24					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ ( $mW/cm^2$ )	85.56					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ ( $mW/cm^2$ )	114.61					
	$p_r$ at $Z_{pii}$ (MPa)	1.25					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	14.8cm	14.8cm		14.8cm		4.6cm
	SV Position	6.0cm	15.0cm		6.0cm		2.0cm
	Working Frequency	2.5	2.5		2.5		2.5
	PRF	699	4399		10000		20000
	SV	0.5mm	0.5mm		0.5mm		0.5mm

Transducer Model: 35C50EA

Imaging Mode: B+PW-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.92	0.48		1.24		2.22
Index component value			0.48	0.45	0.43	1.24	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	1.46					
	$P$ (mW)		133.12		93.42		106.85
	$P_{1 \times 1}$ (mW)		31.51		34.87		
	$Z_s$ (cm)			1.65			
	$Z_b$ (cm)					2.32	
	$Z_{MI}$ (cm)	0.50					
	$Z_{pii,\alpha}$ (cm)	0.50					
	$f_{awf}$ (MHz)	2.53		3.39		2.77	
Other Information	$p_{rr}$ (Hz)	699.00					
	$s_{rr}$ (Hz)	41.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ (W/cm <sup>2</sup> )	92.57					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	96.03					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ (mW/cm <sup>2</sup> )	130.44					
	$p_r$ at $Z_{pii}$ (MPa)	1.21					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	14.8cm	4.6cm		14.8cm		14.8cm
	B Focus Position	6.0cm	4.0cm		6.0cm		2.0cm
	SV Position	6.0cm	4.0cm		6.0cm		2.0cm
	B Working Frequency	2	3.5		2		2
	PW Working Frequency	2.5	3		2.5		2.5
	B PRF	3499	8394		1137		1137
	PW PRF	699	699		3295		3295
	PW SV	0.5mm	0.5mm		0.5mm		0.5mm

Transducer Model: 35C50EA

Imaging Mode: Color+B-Mode / Power+B-Mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.57	0.17		0.17		0.87
Index component value			0.17	0.17	0.17	0.17	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	0.90					
	$P$ (mW)		110.30		111.10		109.70
	$P_{1 \times 1}$ (mW)		14.26		14.36		
	$z_s$ (cm)			/			
	$z_b$ (cm)					/	
	$Z_{MI}$ (cm)	3.86					
	$Z_{pii,\alpha}$ (cm)	3.86					
	$f_{awf}$ (MHz)	2.51	2.72		2.66		2.70
Other Information	$p_{rr}$ (Hz)	3,420.00					
	$s_{rr}$ (Hz)	14.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ (W/cm <sup>2</sup> )	46.99					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	2.88					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ (mW/cm <sup>2</sup> )	5.88					
	$p_r$ at $Z_{pii}$ (MPa)	1.16					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	16.6cm	16.6cm		16.6cm		16.6cm
	B Focus Position	4.0cm	15.0cm		15.0cm		15.0cm
	Color Sampling Gate Position	4.0cm	15.0cm		15.0cm		15.0cm
	B Working Frequency	2	2		2		2
	C Working Frequency	2.5	2.5		2.5		2.5
	B PRF	2388	1640		1640		1640
	Color PRF	3420	2470		2470		2470

Transducer Model: 35C50EA

Imaging Mode: Color+B+PW-Mode/Power+B+PW-Mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.62	0.60		1.85		2.04
Index component value			0.47	0.60	0.64	1.85	
Acoustic Parameters	$p_{r,\alpha}$ at $z_{MI}$ (MPa)	0.99					
	$P$ (mW)		190.68		190.06		160.89
	$P_{1 \times 1}$ (mW)		39.00		53.36		
	$z_s$ (cm)			2.89			
	$z_b$ (cm)					3.95	
	$z_{MI}$ (cm)	2.23					
	$z_{pii,\alpha}$ (cm)	2.23					
	$f_{awf}$ (MHz)	2.50	2.67		2.70		2.68
Other Information	$p_{rr}$ (Hz)	878.00					
	$s_{rr}$ (Hz)	4.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $z_{pii,\alpha}$ (W/cm <sup>2</sup> )	42.40					
	$I_{spta,\alpha}$ at $z_{pii,\alpha}$ or $z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	0.75					
	$I_{spta}$ at $z_{pii}$ or $z_{sii}$ (mW/cm <sup>2</sup> )	1.18					
	$p_r$ at $z_{pii}$ (MPa)	1.09					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	16.6cm	16.6cm		16.6cm		16.6cm
	B Focus Position	4.0cm	16.0cm		6.0cm		4.0cm
	Color SG Position	4.0cm	16.0cm		6.0cm		4.0cm
	PW SV Position	4.0cm	16.0cm		6.0cm		4.0cm
	B Working Frequency	2	2		2		2
	C Working Frequency	2.5	2.5		2.5		2.5
	PW Working Frequency	2.5	2.5		2.5		2.5
	B PRF	1107	677		843		1107
	C PRF	878	552		898		878
	PW PRF	2406	2453		2444		2406
	PW SV	0.5mm	0.5mm		0.5mm		0.5mm

## C.4 65C15EA

Transducer Model: 65C15EA

Imaging Mode: M-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.78	0.05		0.23		0.22
Index component value			0.05	0.03	0.13	0.23	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	1.71					
	$P$ (mW)		2.33		3.37		7.62
	$P_{1 \times 1}$ (mW)		2.27		3.37		
	$z_s$ (cm)			1.44			
	$z_b$ (cm)					1.08	
	$Z_{MI}$ (cm)	1.65					
	$Z_{pii,\alpha}$ (cm)	1.65					
	$f_{awf}$ (MHz)	4.86	4.67		4.76		4.66
Other Information	$p_{rr}$ (Hz)	2,999.00					
	$s_{rr}$ (Hz)	/					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ ( $W/cm^2$ )	132.42					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ ( $mW/cm^2$ )	169.14					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ ( $mW/cm^2$ )	298.60					
	$p_r$ at $Z_{pii}$ (MPa)	2.06					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	12.9cm	12.9cm		12.9cm		12.9cm
	Focus position	1.5cm	5.0cm		2.5cm		5.0cm
	Working Frequency	H9.0	H9.0		H9.0		H9.0
	PRF	2999	2999		2999		2999

Transducer Model: 65C15EA

Imaging Mode: B-mode/Smart3D/Tissue Harmonic Imaging

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.77	0.11		0.21		0.21
Index component value			0.11	0.11	0.21	0.11	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	1.69					
	$P$ (mW)		12.00		12.00		12.00
	$P_{1 \times 1}$ (mW)		4.69		4.69		
	$Z_s$ (cm)			/			
	$Z_b$ (cm)					/	
	$Z_{MI}$ (cm)	1.65					
	$Z_{pii,\alpha}$ (cm)	1.65					
	$f_{awf}$ (MHz)	4.84	4.81		4.81		4.72
Other Information	$p_{rr}$ (Hz)	5,096.00					
	$s_{rr}$ (Hz)	13.00					
	$n_{pps}$	1.33					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ ( $W/cm^2$ )	126.11					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ ( $mW/cm^2$ )	2.04					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ ( $mW/cm^2$ )	3.72					
	$p_r$ at $Z_{pii}$ (MPa)	2.19					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	12.9cm	12.9cm		12.9cm		12.9cm
	Focus position	1.5cm	10.0cm		10.0cm		5.0cm
	Working Frequency	H9.0	H9.0		H9.0		H9.0
	PRF	5096	5096		5096		5096



Transducer Model: 65C15EA

Imaging Mode: B+M-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.92	0.21		0.36		0.54
Index component value			0.21	0.19	0.25	0.36	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	2.03					
	$P$ (mW)		20.32		19.64		20.35
	$P_{1 \times 1}$ (mW)		9.30		11.11		
	$Z_s$ (cm)			1.44			
	$Z_b$ (cm)					1.75	
	$Z_{MI}$ (cm)	1.56					
	$Z_{pii,\alpha}$ (cm)	1.56					
	$f_{awf}$ (MHz)	4.83		4.70		4.75	4.82
Other Information	$prr$ (Hz)	750.00					
	$srr$ (Hz)	10.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ (W/cm <sup>2</sup> )	193.95					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	59.84					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ (mW/cm <sup>2</sup> )	103.13					
	$p_r$ at $Z_{pii}$ (MPa)	2.25					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	12.9cm	12.9cm		6.5cm		6.5cm
	B/M Focus position	1.5cm	5.0cm		1.0cm		1.0cm
	B/M Working Frequency	H9.0	H9.0		H9.0		H9.0
	B PRF	4250	4250		6000		6000
	M PRF	750	750		3000		3000

Transducer Model: 65C15EA

Imaging Mode: PW-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		1.16	0.04		0.13		0.07
Index component value			0.04	0.02	0.09	0.13	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	2.60					
	$P$ (mW)		1.56		2.04		1.39
	$P_{1 \times 1}$ (mW)		1.52		2.04		
	$Z_s$ (cm)			1.44			
	$Z_b$ (cm)					1.56	
	$Z_{MI}$ (cm)	1.36					
	$Z_{pii,\alpha}$ (cm)	1.36					
	$f_{awf}$ (MHz)	5.02	5.01		5.03		5.03
Other Information	$p_{rr}$ (Hz)	699.00					
	$s_{rr}$ (Hz)	/					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ ( $W/cm^2$ )	342.45					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ ( $mW/cm^2$ )	180.40					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ ( $mW/cm^2$ )	308.55					
	$p_r$ at $Z_{pii}$ (MPa)	2.91					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	6.5cm	12.9cm		6.5cm		6.5cm
	SV Position	1.0cm	10.0cm		1.0cm		0.5cm
	Working Frequency	5	5		5		5
	PRF	699	6300		23995		23995
	SV	0.5mm	0.5mm		0.5mm		0.5mm

Transducer Model: 65C15EA

Imaging Mode: B+PW-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.48	0.15		0.09		0.13
Index component value			0.15	0.14	0.05	0.09	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	1.17					
	$P$ (mW)		11.53		3.15		5.14
	$P_{1 \times 1}$ (mW)		5.40		1.93		
	$Z_s$ (cm)			1.44			
	$Z_b$ (cm)					1.75	
	$Z_{MI}$ (cm)	1.84					
	$Z_{pii,\alpha}$ (cm)	1.84					
	$f_{awf}$ (MHz)	6.00	6.15		6.22		5.64
Other Information	$p_{rr}$ (Hz)	7,694.00					
	$s_{rr}$ (Hz)	58.00					
	$n_{pps}$	1.33					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ (W/cm <sup>2</sup> )	98.11					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	3.65					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ (mW/cm <sup>2</sup> )	7.83					
	$p_r$ at $Z_{pii}$ (MPa)	1.71					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	6.5cm	12.9cm		12.9cm		12.9cm
	B Focus Position	1.0cm	5.0cm		1.0cm		0.5cm
	SV Position	1.0cm	5.0cm		1.0cm		0.5cm
	B Working Frequency	6.5	6.5		6.5		6.5
	PW Working Frequency	5	5		5		5
	B PRF	7694	1276		1276		1276
	PW PRF	699	3595		3595		3595
	PW SV	0.5mm	0.5mm		0.5mm		0.5mm

Transducer Model: 65C15EA

Imaging Mode: Color+B-Mode / Power+B-Mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		1.10	0.10		0.13		0.25
Index component value			0.10	0.10	0.13	0.13	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	2.49					
	$P$ (mW)		10.00		12.00		14.00
	$P_{1 \times 1}$ (mW)		3.91		4.69		
	$z_s$ (cm)			/			
	$z_b$ (cm)					/	
	$Z_{MI}$ (cm)	0.50					
	$Z_{pii,\alpha}$ (cm)	0.50					
	$f_{awf}$ (MHz)	5.07	5.99		5.95		5.40
Other Information	$p_{rr}$ (Hz)	1,906.00					
	$s_{rr}$ (Hz)	9.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ (W/cm <sup>2</sup> )	317.09					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	6.37					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ (mW/cm <sup>2</sup> )	7.59					
	$p_r$ at $Z_{pii}$ (MPa)	2.72					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	11.1cm	11.1cm		11.1cm		11.1cm
	B Focus Position	1.0cm	2.5cm		2.5cm		2.5cm
	Color Sampling Gate Position	1.0cm	2.5cm		2.5cm		2.5cm
	B Working Frequency	6.5	6.5		6.5		5
	C Working Frequency	5	5		5		4.4
	B PRF	4756	4756		4756		5001
	Color PRF	1906	1906		1906		2086

Transducer Model: 65C15EA

Imaging Mode: Color+B+PW-Mode/Power+B+PW-Mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.94	0.41		1.53		0.98
Index component value			0.41	0.31	0.56	1.53	
Acoustic Parameters	$p_{r,\alpha}$ at $z_{MI}$ (MPa)	2.10					
	$P$ (mW)		25.99		31.31		28.55
	$P_{1 \times 1}$ (mW)		17.18		22.78		
	$z_s$ (cm)			1.44			
	$z_b$ (cm)					0.88	
	$z_{MI}$ (cm)	1.08					
	$z_{pii,\alpha}$ (cm)	1.08					
	$f_{awf}$ (MHz)	5.03	5.26		5.99		6.08
Other Information	$p_{rr}$ (Hz)	3,474.00					
	$s_{rr}$ (Hz)	3.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $z_{pii,\alpha}$ (W/cm <sup>2</sup> )	249.29					
	$I_{spta,\alpha}$ at $z_{pii,\alpha}$ or $z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	645.86					
	$I_{spta}$ at $z_{pii}$ or $z_{sii}$ (mW/cm <sup>2</sup> )	962.79					
	$p_r$ at $z_{pii}$ (MPa)	2.44					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	11.1cm	11.1cm		11.1cm		11.1cm
	B Focus Position	1.0cm	5.0cm		1.0cm		1.0cm
	Color SG Position	1.0cm	5.0cm		1.0cm		1.0cm
	PW SV Position	1.0cm	5.0cm		1.0cm		1.0cm
	B Working Frequency	6.5	5		6.5		6.5
	C Working Frequency	5	4.4		5		5
	PW Working Frequency	5	5		5		5
	B PRF	1876	1860		1876		1876
	C PRF	635	630		635		635
	PW PRF	3474	3445		3474		3474
	PW SV	0.5mm	0.5mm		0.5mm		0.5mm

# C.5 65EB10EA\_T

Transducer Model: 65EB10EA\_T

Imaging Mode: M-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.79	0.17		0.37		0.25
Index component value			0.17	0.11	0.26	0.37	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	1.94					
	$P$ (mW)		7.37		5.51		7.63
	$P_{1 \times 1}$ (mW)		7.37		5.51		
	$z_s$ (cm)			1.33			
	$z_b$ (cm)					1.78	
	$Z_{MI}$ (cm)	1.75					
	$Z_{pii,\alpha}$ (cm)	1.75					
	$f_{awf}$ (MHz)	6.04	4.70		4.64		4.31
Other Information	$p_{rr}$ (Hz)	1,000.00					
	$s_{rr}$ (Hz)	/					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ ( $W/cm^2$ )	157.39					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ ( $mW/cm^2$ )	36.57					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ ( $mW/cm^2$ )	76.23					
	$p_r$ at $Z_{pii}$ (MPa)	2.79					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	12.9cm	12.9cm		12.9cm		12.9cm
	Focus position	2.0cm	5.5cm		2.0cm		5.0cm
	Working Frequency	6.5	H8.0		H9.0		H9.0
	PRF	1000	2999		2999		2999

Transducer Model: 65EB10EA T

Imaging Mode: B-mode /Smart3D/Tissue Harmonic Imaging

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.83	0.04		0.04		0.04
Index component value			0.04	0.04	0.04	0.02	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	2.04					
	$P$ (mW)		4.00		2.00		2.00
	$P_{1x1}$ (mW)		1.79		0.89		
	$Z_s$ (cm)			/			
	$Z_b$ (cm)					/	
	$Z_{MI}$ (cm)	1.65					
	$Z_{pii,\alpha}$ (cm)	1.65					
	$f_{awf}$ (MHz)	6.04	5.14		5.04		5.04
Other Information	$p_{rr}$ (Hz)	5,096.00					
	$s_{rr}$ (Hz)	41.00					
	$n_{pps}$	1.33					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ (W/cm <sup>2</sup> )	158.75					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	4.50					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ (mW/cm <sup>2</sup> )	9.36					
	$p_r$ at $Z_{pii}$ (MPa)	2.75					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	12.9cm	6.5cm		6.5cm		6.5cm
	Focus position	2.0cm	0.5cm		0.5cm		0.5cm
	Working Frequency	6.5	5		5		5
	PRF	5096	8992		8992		8992

Transducer Model: 65EB10EA T

Imaging Mode: B+M-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.86	0.05		0.10		0.11
Index component value			0.05	0.05	0.07	0.10	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	2.11					
	$P$ (mW)		4.46		6.45		4.45
	$P_{1 \times 1}$ (mW)		2.24		3.12		
	$Z_s$ (cm)			0.79			
	$Z_b$ (cm)					0.79	
	$Z_{MI}$ (cm)	1.65					
	$Z_{pii,\alpha}$ (cm)	1.65					
	$f_{awf}$ (MHz)	6.03	5.03		4.99		5.00
Other Information	$prr$ (Hz)	1,000.00					
	$srr$ (Hz)	32.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ (W/cm <sup>2</sup> )	169.87					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	39.05					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ (mW/cm <sup>2</sup> )	81.87					
	$p_r$ at $Z_{pii}$ (MPa)	2.75					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	12.9cm	6.5cm		6.5cm		6.5cm
	B/M Focus position	2.0cm	0.5cm		0.5cm		0.5cm
	B/M Working Frequency	6.5	5		5		5
	B PRF	4000	8000		8000		8000
	M PRF	1000	1000		1000		1000



Transducer Model: 65EB10EA T

Imaging Mode: PW-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.89	0.09		0.30		0.20
Index component value			0.09	0.06	0.20	0.30	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	1.99					
	$P$ (mW)		3.94		4.25		4.26
	$P_{1 \times 1}$ (mW)		3.94		4.25		
	$Z_s$ (cm)			1.22			
	$Z_b$ (cm)					1.55	
	$Z_{MI}$ (cm)	1.46					
	$Z_{pii,\alpha}$ (cm)	1.46					
	$f_{awf}$ (MHz)	4.95	4.89		5.00		5.00
Other Information	$p_{rr}$ (Hz)	699.00					
	$s_{rr}$ (Hz)	/					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ ( $W/cm^2$ )	220.59					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ ( $mW/cm^2$ )	113.08					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ ( $mW/cm^2$ )	190.14					
	$p_r$ at $Z_{pii}$ (MPa)	2.46					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	12.9cm	12.9cm		12.9cm		12.9cm
	SV Position	2.0cm	5.0cm		2.5cm		2.5cm
	Working Frequency	5	5		5		5
	PRF	699	699		16000		16000
	SV	0.5mm	0.5mm		0.5mm		0.5mm

Transducer Model: 65EB10EA T

Imaging Mode: B+PW-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.68	0.04		0.41		0.15
Index component value			0.04	0.04	0.14	0.41	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{Ml}$ (MPa)	1.39					
	$P$ (mW)		3.01		6.82		5.02
	$P_{1x1}$ (mW)		1.91		5.72		
	$Z_s$ (cm)			0.69			
	$Z_b$ (cm)					1.46	
	$Z_{Ml}$ (cm)	1.46					
	$Z_{pii,\alpha}$ (cm)	1.46					
	$f_{awf}$ (MHz)	4.11	5.02		6.42		5.01
Other Information	$p_{rr}$ (Hz)	699.00					
	$s_{rr}$ (Hz)	33.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ (W/cm <sup>2</sup> )	76.52					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	50.27					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ (mW/cm <sup>2</sup> )	77.30					
	$p_r$ at $Z_{pii}$ (MPa)	1.69					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	12.9cm	6.5cm		12.9cm		6.5cm
	B Focus Position	2.0cm	0.5cm		2.0cm		0.5cm
	SV Position	2.0cm	0.5cm		2.0cm		0.5cm
	B Working Frequency	5	5		6.5		5
	PW Working Frequency	4	4		5		4
	B PRF	4199	7694		1276		7694
	PW PRF	699	699		3595		699
	PW SV	0.5mm	0.5mm		0.5mm		0.5mm

Transducer Model: 65EB10EA T

Imaging Mode: Color+B-Mode / Power+B-Mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.27	0.16		0.11		0.29
Index component value			0.16	0.16	0.11	0.11	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	0.55					
	$P$ (mW)		14.00		10.00		14.00
	$P_{1 \times 1}$ (mW)		6.25		4.46		
	$z_s$ (cm)			/			
	$z_b$ (cm)					/	
	$Z_{MI}$ (cm)	0.98					
	$Z_{pii,\alpha}$ (cm)	0.98					
	$f_{awf}$ (MHz)	4.06	5.40		5.65		4.53
Other Information	$p_{rr}$ (Hz)	2,332.00					
	$s_{rr}$ (Hz)	13.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ (W/cm <sup>2</sup> )	9.44					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	0.34					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ (mW/cm <sup>2</sup> )	0.45					
	$p_r$ at $Z_{pii}$ (MPa)	0.63					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	8.3cm	8.3cm		8.3cm		8.3cm
	B Focus Position	2.0cm	2.5cm		2.5cm		2.5cm
	Color Sampling Gate Position	2.0cm	2.5cm		2.5cm		2.5cm
	B Working Frequency	5	6.5		6.5		5
	C Working Frequency	4	5		5		4
	B PRF	4889	3320		3320		2919
	Color PRF	2332	4750		4750		4177

Transducer Model: 65EB10EA T

Imaging Mode: Color+B+PW-Mode/Power+B+PW-Mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.30	0.12		0.24		0.33
Index component value			0.12	0.11	0.14	0.24	
Acoustic Parameters	$p_{r,\alpha}$ at $z_{MI}$ (MPa)	0.68					
	$P$ (mW)		9.95		12.01		13.38
	$P_{1 \times 1}$ (mW)		5.52		6.47		
	$z_s$ (cm)			0.96			
	$z_b$ (cm)					0.98	
	$z_{MI}$ (cm)	0.98					
	$z_{pii,\alpha}$ (cm)	0.98					
	$f_{awf}$ (MHz)	4.94	4.92		4.92		5.00
Other Information	$p_{rr}$ (Hz)	739.00					
	$s_{rr}$ (Hz)	4.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $z_{pii,\alpha}$ (W/cm <sup>2</sup> )	14.27					
	$I_{spta,\alpha}$ at $z_{pii,\alpha}$ or $z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	0.13					
	$I_{spta}$ at $z_{pii}$ or $z_{sii}$ (mW/cm <sup>2</sup> )	0.18					
	$p_r$ at $z_{pii}$ (MPa)	0.80					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	8.3cm	8.3cm		8.3cm		8.3cm
	B Focus Position	2.0cm	2.5cm		2.0cm		1.0cm
	Color SG Position	2.0cm	2.5cm		2.0cm		1.0cm
	PW SV Position	2.0cm	2.5cm		2.0cm		1.0cm
	B Working Frequency	6.5	5		5		5
	C Working Frequency	5	4		4		4
	PW Working Frequency	4	5		5		5
	B PRF	2243	1493		2201		1493
	C PRF	739	1459		725		1459
	PW PRF	3498	3453		3432		3453
	PW SV	0.5mm	0.5mm		0.5mm		0.5mm

# C.6 65EB10EA\_S

Transducer Model: 65EB10EA\_S

Imaging Mode: M-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.79	0.17		0.37		0.25
Index component value			0.17	0.11	0.26	0.37	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	1.94					
	$P$ (mW)		7.37		5.51		7.63
	$P_{1 \times 1}$ (mW)		7.37		5.51		
	$z_s$ (cm)			1.33			
	$z_b$ (cm)					1.78	
	$Z_{MI}$ (cm)	1.75					
	$Z_{pii,\alpha}$ (cm)	1.75					
	$f_{awf}$ (MHz)	6.04	4.70		4.64		4.31
Other Information	$p_{rr}$ (Hz)	1,000.00					
	$s_{rr}$ (Hz)	/					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ ( $W/cm^2$ )	157.39					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ ( $mW/cm^2$ )	36.57					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ ( $mW/cm^2$ )	76.23					
	$p_r$ at $Z_{pii}$ (MPa)	2.79					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	12.9cm	12.9cm		12.9cm		12.9cm
	Focus position	2.0cm	5.5cm		2.0cm		5.0cm
	Working Frequency	6.5	H8.0		H9.0		H9.0
	PRF	1000	2999		2999		2999

Transducer Model: 65EB10EA S

Imaging Mode: B-mode /Smart3D/Tissue Harmonic Imaging

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.83	0.04		0.04		0.04
Index component value			0.04	0.04	0.04	0.02	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	2.04					
	$P$ (mW)		4.00		2.00		2.00
	$P_{1 \times 1}$ (mW)		1.79		0.89		
	$Z_s$ (cm)			/			
	$Z_b$ (cm)					/	
	$Z_{MI}$ (cm)	1.65					
	$Z_{pii,\alpha}$ (cm)	1.65					
	$f_{awf}$ (MHz)	6.04	5.14		5.04		5.04
Other Information	$p_{rr}$ (Hz)	5,096.00					
	$s_{rr}$ (Hz)	41.00					
	$n_{pps}$	1.33					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ ( $W/cm^2$ )	158.75					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ ( $mW/cm^2$ )	4.50					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ ( $mW/cm^2$ )	9.36					
	$p_r$ at $Z_{pii}$ (MPa)	2.75					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	12.9cm	6.5cm		6.5cm		6.5cm
	Focus position	2.0cm	0.5cm		0.5cm		0.5cm
	Working Frequency	6.5	5		5		5
	PRF	5096	8992		8992		8992

Transducer Model: 65EB10EA S

Imaging Mode: B+M-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.86	0.05		0.10		0.11
Index component value			0.05	0.05	0.07	0.10	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	2.11					
	$P$ (mW)		4.46		6.45		4.45
	$P_{1 \times 1}$ (mW)		2.24		3.12		
	$Z_s$ (cm)			0.79			
	$Z_b$ (cm)					0.79	
	$Z_{MI}$ (cm)	1.65					
	$Z_{pii,\alpha}$ (cm)	1.65					
	$f_{awf}$ (MHz)	6.03		5.03		4.99	
Other Information	$prr$ (Hz)	1,000.00					
	$srr$ (Hz)	32.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ (W/cm <sup>2</sup> )	169.87					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	39.05					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ (mW/cm <sup>2</sup> )	81.87					
	$p_r$ at $Z_{pii}$ (MPa)	2.75					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	12.9cm	6.5cm		6.5cm		6.5cm
	B/M Focus position	2.0cm	0.5cm		0.5cm		0.5cm
	B/M Working Frequency	6.5	5		5		5
	B PRF	4000	8000		8000		8000
	M PRF	1000	1000		1000		1000

Transducer Model: 65EB10EA S

Imaging Mode: PW-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.89	0.09		0.30		0.20
Index component value			0.09	0.06	0.20	0.30	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	1.99					
	$P$ (mW)		3.94		4.25		4.26
	$P_{1 \times 1}$ (mW)		3.94		4.25		
	$Z_s$ (cm)			1.22			
	$Z_b$ (cm)					1.55	
	$Z_{MI}$ (cm)	1.46					
	$Z_{pii,\alpha}$ (cm)	1.46					
	$f_{awf}$ (MHz)	4.95	4.89		5.00		5.00
Other Information	$p_{rr}$ (Hz)	699.00					
	$s_{rr}$ (Hz)	/					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ ( $W/cm^2$ )	220.59					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ ( $mW/cm^2$ )	113.08					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ ( $mW/cm^2$ )	190.14					
	$p_r$ at $Z_{pii}$ (MPa)	2.46					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	12.9cm	12.9cm		12.9cm		12.9cm
	SV Position	2.0cm	5.0cm		2.5cm		2.5cm
	Working Frequency	5	5		5		5
	PRF	699	699		16000		16000
	SV	0.5mm	0.5mm		0.5mm		0.5mm



Transducer Model: 65EB10EA S

Imaging Mode: B+PW-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.68	0.04		0.41		0.15
Index component value			0.04	0.04	0.14	0.41	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	1.39					
	$P$ (mW)		3.01		6.82		5.02
	$P_{1 \times 1}$ (mW)		1.91		5.72		
	$Z_s$ (cm)			0.69			
	$Z_b$ (cm)					1.46	
	$Z_{MI}$ (cm)	1.46					
	$Z_{pii,\alpha}$ (cm)	1.46					
	$f_{awf}$ (MHz)	4.11	5.02		6.42		5.01
Other Information	$p_{rr}$ (Hz)	699.00					
	$s_{rr}$ (Hz)	33.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ ( $W/cm^2$ )	76.52					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ ( $mW/cm^2$ )	50.27					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ ( $mW/cm^2$ )	77.30					
	$p_r$ at $Z_{pii}$ (MPa)	1.69					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	12.9cm	6.5cm		12.9cm		6.5cm
	B Focus Position	2.0cm	0.5cm		2.0cm		0.5cm
	SV Position	2.0cm	0.5cm		2.0cm		0.5cm
	B Working Frequency	5	5		6.5		5
	PW Working Frequency	4	4		5		4
	B PRF	4199	7694		1276		7694
	PW PRF	699	699		3595		699
	PW SV	0.5mm	0.5mm		0.5mm		0.5mm

Transducer Model: 65EB10EA S

Imaging Mode: Color+B-Mode / Power+B-Mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.27	0.16		0.11		0.29
Index component value			0.16	0.16	0.11	0.11	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	0.55					
	$P$ (mW)		14.00		10.00		14.00
	$P_{1 \times 1}$ (mW)		6.25		4.46		
	$z_s$ (cm)			/			
	$z_b$ (cm)					/	
	$Z_{MI}$ (cm)	0.98					
	$Z_{pii,\alpha}$ (cm)	0.98					
	$f_{awf}$ (MHz)	4.06	5.40		5.65		4.53
Other Information	$p_{rr}$ (Hz)	2,332.00					
	$s_{rr}$ (Hz)	13.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ (W/cm <sup>2</sup> )	9.44					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	0.34					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ (mW/cm <sup>2</sup> )	0.45					
	$p_r$ at $Z_{pii}$ (MPa)	0.63					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	8.3cm	8.3cm		8.3cm		8.3cm
	B Focus Position	2.0cm	2.5cm		2.5cm		2.5cm
	Color Sampling Gate Position	2.0cm	2.5cm		2.5cm		2.5cm
	B Working Frequency	5	6.5		6.5		5
	C Working Frequency	4	5		5		4
	B PRF	4889	3320		3320		2919
	Color PRF	2332	4750		4750		4177

Transducer Model: 65EB10EA S

Imaging Mode: Color+B+PW-Mode/Power+B+PW-Mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.30	0.12		0.24		0.33
Index component value			0.12	0.11	0.14	0.24	
Acoustic Parameters	$p_{r,\alpha}$ at $z_{MI}$ (MPa)	0.68					
	$P$ (mW)		9.95		12.01		13.38
	$P_{1 \times 1}$ (mW)		5.52		6.47		
	$z_s$ (cm)			0.96			
	$z_b$ (cm)					0.98	
	$z_{MI}$ (cm)	0.98					
	$z_{pii,\alpha}$ (cm)	0.98					
	$f_{awf}$ (MHz)	4.94	4.92		4.92		5.00
Other Information	$p_{rr}$ (Hz)	739.00					
	$s_{rr}$ (Hz)	4.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $z_{pii,\alpha}$ (W/cm <sup>2</sup> )	14.27					
	$I_{spta,\alpha}$ at $z_{pii,\alpha}$ or $z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	0.13					
	$I_{spta}$ at $z_{pii}$ or $z_{sii}$ (mW/cm <sup>2</sup> )	0.18					
	$p_r$ at $z_{pii}$ (MPa)	0.80					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	8.3cm	8.3cm		8.3cm		8.3cm
	B Focus Position	2.0cm	2.5cm		2.0cm		1.0cm
	Color SG Position	2.0cm	2.5cm		2.0cm		1.0cm
	PW SV Position	2.0cm	2.5cm		2.0cm		1.0cm
	B Working Frequency	6.5	5		5		5
	C Working Frequency	5	4		4		4
	PW Working Frequency	4	5		5		5
	B PRF	2243	1493		2201		1493
	C PRF	739	1459		725		1459
	PW PRF	3498	3453		3432		3453
	PW SV	0.5mm	0.5mm		0.5mm		0.5mm

## C.7 65EC10ED

Transducer Model: 65EC10ED

Imaging Mode: M-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		1.24	0.13		0.57		0.24
Index component value			0.13	0.09	0.29	0.57	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	3.03					
	$P$ (mW)		6.39		6.56		7.26
	$P_{1 \times 1}$ (mW)		6.39		6.56		
	$z_s$ (cm)			1.33			
	$z_b$ (cm)					1.08	
	$Z_{MI}$ (cm)	1.08					
	$Z_{pii,\alpha}$ (cm)	1.08					
	$f_{awf}$ (MHz)	6.00	4.40		4.74		4.75
Other Information	$p_{rr}$ (Hz)	1,000.00					
	$s_{rr}$ (Hz)	/					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ ( $W/cm^2$ )	318.85					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ ( $mW/cm^2$ )	73.27					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ ( $mW/cm^2$ )	115.18					
	$p_r$ at $Z_{pii}$ (MPa)	3.51					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	12.9cm	12.9cm		12.9cm		12.9cm
	Focus position	2.0cm	5.0cm		2.0cm		5.0cm
	Working Frequency	6.5	H8.0		H9.0		H9.0
	PRF	1000	2999		2999		2999

Transducer Model: 65EC10ED

Imaging Mode: B-mode/Smart3D/Tissue Harmonic Imaging

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		1.17	0.09		0.16		0.12
Index component value			0.09	0.09	0.16	0.09	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	2.88					
	$P$ (mW)		8.00		8.00		6.00
	$P_{1 \times 1}$ (mW)		3.21		3.21		
	$Z_s$ (cm)			/			
	$Z_b$ (cm)					/	
	$Z_{MI}$ (cm)	1.17					
	$Z_{pii,\alpha}$ (cm)	1.17					
	$f_{awf}$ (MHz)	6.04	5.81		5.88		5.27
Other Information	$p_{rr}$ (Hz)	5,096.00					
	$s_{rr}$ (Hz)	41.00					
	$n_{pps}$	1.33					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ ( $W/cm^2$ )	334.81					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ ( $mW/cm^2$ )	9.34					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ ( $mW/cm^2$ )	15.53					
	$p_r$ at $Z_{pii}$ (MPa)	3.68					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	12.9cm	12.9cm		12.9cm		12.9cm
	Focus position	2.0cm	6.0cm		6.0cm		5.0cm
	Working Frequency	6.5	6.5		6.5		5
	PRF	5096	5096		5096		5096

Transducer Model: 65EC10ED

Imaging Mode: B+M-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		1.22	0.08		0.41		0.32
Index component value			0.08	0.06	0.13	0.41	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	3.02					
	$P$ (mW)		4.22		7.11		7.54
	$P_{1 \times 1}$ (mW)		3.02		5.91		
	$Z_s$ (cm)			1.33			
	$Z_b$ (cm)					0.88	
	$Z_{MI}$ (cm)	1.08					
	$Z_{pii,\alpha}$ (cm)	1.08					
	$f_{awf}$ (MHz)	6.12	5.88		4.77		4.79
Other Information	$prr$ (Hz)	4,000.00					
	$srr$ (Hz)	32.00					
	$n_{pps}$	1.33					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ (W/cm <sup>2</sup> )	329.76					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	7.27					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ (mW/cm <sup>2</sup> )	11.47					
	$p_r$ at $Z_{pii}$ (MPa)	3.70					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	12.9cm	12.9cm		6.5cm		6.5cm
	B/M Focus position	2.0cm	6.0cm		0.5cm		1.0cm
	B/M Working Frequency	6.5	6.5		H9.0		H9.0
	B PRF	4000	4000		6000		6000
	M PRF	1000	1000		3000		3000

Transducer Model: 65EC10ED  
 Imaging Mode: PW-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		1.14	0.13		0.52		0.30
Index component value			0.13	0.09	0.34	0.52	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	2.55					
	$P$ (mW)		5.37		6.08		5.31
	$P_{1 \times 1}$ (mW)		5.37		6.08		
	$Z_s$ (cm)			0.96			
	$Z_b$ (cm)					0.88	
	$Z_{MI}$ (cm)	1.31					
	$Z_{pii,\alpha}$ (cm)	1.31					
	$f_{awf}$ (MHz)	4.96	4.96		5.02		5.01
Other Information	$p_{rr}$ (Hz)	699.00					
	$s_{rr}$ (Hz)	/					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ ( $W/cm^2$ )	338.02					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ ( $mW/cm^2$ )	169.37					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ ( $mW/cm^2$ )	265.68					
	$p_r$ at $Z_{pii}$ (MPa)	3.19					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	12.9cm	12.9cm		6.5cm		6.5cm
	SV Position	2.5cm	2.5cm		1.0cm		1.0cm
	Working Frequency	5	5		5		5
	PRF	699	699		23995		23995
	SV	0.5mm	0.5mm		0.5mm		0.5mm

Transducer Model: 65EC10ED

Imaging Mode: B+PW-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.97	0.12		0.48		0.35
Index component value			0.12	0.09	0.15	0.48	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	2.18					
	$P$ (mW)		5.92		7.42		6.95
	$P_{1 \times 1}$ (mW)		4.72		6.22		
	$Z_s$ (cm)			0.96			
	$Z_b$ (cm)					1.17	
	$Z_{MI}$ (cm)	0.50					
	$Z_{pii,\alpha}$ (cm)	0.50					
	$f_{awf}$ (MHz)	5.01		6.02		6.23	
Other Information	$p_{rr}$ (Hz)	699.00					
	$s_{rr}$ (Hz)	33.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ ( $W/cm^2$ )	210.14					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ ( $mW/cm^2$ )	107.61					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ ( $mW/cm^2$ )	139.14					
	$p_r$ at $Z_{pii}$ (MPa)	2.26					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	12.9cm	12.9cm		12.9cm		12.9cm
	B Focus Position	0.5cm	2.5cm		2.0cm		0.5cm
	SV Position	0.5cm	2.5cm		2.0cm		0.5cm
	B Working Frequency	6.5	6.5		6.5		6.5
	PW Working Frequency	5	5		5		5
	B PRF	4199	4199		1276		1276
	PW PRF	699	699		3595		3595
	PW SV	0.5mm	0.5mm		0.5mm		0.5mm



Transducer Model: 65EC10ED

Imaging Mode: Color+B-Mode / Power+B-Mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.61	0.11		0.11		0.20
Index component value			0.11	0.11	0.11	0.11	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	1.53					
	$P$ (mW)		10.00		10.00		10.00
	$P_{1 \times 1}$ (mW)		4.01		4.01		
	$z_s$ (cm)			/			
	$z_b$ (cm)					/	
	$Z_{MI}$ (cm)	1.36					
	$Z_{pii,\alpha}$ (cm)	1.36					
	$f_{awf}$ (MHz)	6.33	6.43		6.34		6.39
Other Information	$p_{rr}$ (Hz)	5,461.00					
	$s_{rr}$ (Hz)	11.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ (W/cm <sup>2</sup> )	106.80					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	0.93					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ (mW/cm <sup>2</sup> )	1.69					
	$p_r$ at $Z_{pii}$ (MPa)	2.06					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	8.3cm	8.3cm		8.3cm		8.3cm
	B Focus Position	2.0cm	2.5cm		2.5cm		5.0cm
	Color Sampling Gate Position	2.0cm	2.5cm		2.5cm		5.0cm
	B Working Frequency	6.5	6.5		6.5		6.5
	C Working Frequency	5	5		5		5
	B PRF	5461	3593		3593		3593
	Color PRF	2546	5025		5025		5025

Transducer Model: 65EC10ED

Imaging Mode: Color+B+PW-Mode/Power+B+PW-Mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.49	0.27		0.53		0.47
Index component value			0.27	0.25	0.25	0.53	
Acoustic Parameters	$p_{r,\alpha}$ at $z_{MI}$ (MPa)	1.25					
	$P$ (mW)		21.06		21.63		19.45
	$P_{1 \times 1}$ (mW)		10.27		10.84		
	$z_s$ (cm)			0.96			
	$z_b$ (cm)					1.31	
	$z_{MI}$ (cm)	1.46					
	$z_{pii,\alpha}$ (cm)	1.46					
	$f_{awf}$ (MHz)	6.39	6.42		5.41		5.43
Other Information	$p_{rr}$ (Hz)	2,199.00					
	$s_{rr}$ (Hz)	4.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $z_{pii,\alpha}$ (W/cm <sup>2</sup> )	74.07					
	$I_{spta,\alpha}$ at $z_{pii,\alpha}$ or $z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	0.23					
	$I_{spta}$ at $z_{pii}$ or $z_{sii}$ (mW/cm <sup>2</sup> )	0.45					
	$p_r$ at $z_{pii}$ (MPa)	1.72					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	8.3cm	8.3cm		8.3cm		8.3cm
	B Focus Position	2.0cm	2.5cm		2.5cm		2.5cm
	Color SG Position	2.0cm	2.5cm		2.5cm		2.5cm
	PW SV Position	2.0cm	2.5cm		2.5cm		2.5cm
	B Working Frequency	6.5	6.5		5		5
	C Working Frequency	5	5		4		4
	PW Working Frequency	4	5		5		5
	B PRF	2199	1491		1871		1102
	C PRF	934	1879		795		1389
	PW PRF	3430	3448		3647		3824
	PW SV	0.5mm	0.5mm		0.5mm		0.5mm

## C.8 65EL60EA

Transducer Model: 65EL60EA

Imaging Mode: M-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.63	0.17		0.81		0.26
Index component value			0.13	0.17	0.29	0.81	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	1.34					
	$P$ (mW)		15.01		10.77		13.04
	$P_{1 \times 1}$ (mW)		6.21		7.91		
	$z_s$ (cm)			2.00			
	$z_b$ (cm)					2.32	
	$Z_{MI}$ (cm)	0.60					
	$Z_{pii,\alpha}$ (cm)	0.60					
	$f_{awf}$ (MHz)	4.62	4.43		4.65		4.45
Other Information	$p_{rr}$ (Hz)	2,999.00					
	$s_{rr}$ (Hz)	/					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ ( $W/cm^2$ )	47.35					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ ( $mW/cm^2$ )	56.46					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ ( $mW/cm^2$ )	84.29					
	$p_r$ at $Z_{pii}$ (MPa)	1.29					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	12.9cm	12.9cm		12.9cm		12.9cm
	Focus position	1.5cm	5.0cm		2.5cm		5.0cm
	Working Frequency	H9.0	H9.0		H9.0		H9.0
	PRF	2999	2999		2999		2999

Transducer Model: 65EL60EA

Imaging Mode: B-mode/Smart3D/Tissue Harmonic Imaging

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		1.23	0.04		0.10		0.03
Index component value			0.04	0.04	0.10	0.04	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	2.65					
	$P$ (mW)		8.00		8.00		2.00
	$P_{1 \times 1}$ (mW)		1.32		1.32		
	$Z_s$ (cm)			/			
	$Z_b$ (cm)					/	
	$Z_{MI}$ (cm)	1.56					
	$Z_{pii,\alpha}$ (cm)	1.56					
	$f_{awf}$ (MHz)	4.65	5.99		5.87		4.43
Other Information	$p_{rr}$ (Hz)	5,096.00					
	$s_{rr}$ (Hz)	13.00					
	$n_{pps}$	1.33					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ ( $W/cm^2$ )	343.78					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ ( $mW/cm^2$ )	5.24					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ ( $mW/cm^2$ )	8.64					
	$p_r$ at $Z_{pii}$ (MPa)	3.40					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	12.9cm	12.9cm		12.9cm		12.9cm
	Focus position	1.5cm	6.0cm		6.0cm		5.0cm
	Working Frequency	H9.0	6.5		6.5		H9.0
	PRF	5096	5096		5096		5096

Transducer Model: 65EL60EA

Imaging Mode: B+M-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		1.38	0.07		0.73		0.09
Index component value			0.06	0.07	0.22	0.73	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	2.99					
	$P$ (mW)		9.46		11.57		5.15
	$P_{1 \times 1}$ (mW)		2.42		9.90		
	$Z_s$ (cm)			2.00			
	$Z_b$ (cm)					1.27	
	$Z_{MI}$ (cm)	1.46					
	$Z_{pii,\alpha}$ (cm)	1.46					
	$f_{awf}$ (MHz)	4.67		5.94		4.66	
Other Information	$prr$ (Hz)	750.00					
	$srr$ (Hz)	10.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ (W/cm <sup>2</sup> )	426.40					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	125.38					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ (mW/cm <sup>2</sup> )	200.80					
	$p_r$ at $Z_{pii}$ (MPa)	3.78					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	12.9cm	12.9cm		6.5cm		12.9cm
	B/M Focus position	1.5cm	6.0cm		1.0cm		5.0cm
	B/M Working Frequency	H9.0	6.5		H9.0		H9.0
	B PRF	4250	4000		6000		4250
	M PRF	750	1000		3000		750

Transducer Model: 65EL60EA

Imaging Mode: PW-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		1.14	0.31		2.79		1.08
Index component value			0.25	0.31	0.95	2.79	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	2.55					
	$P$ (mW)		25.75		28.85		29.96
	$P_{1 \times 1}$ (mW)		10.64		28.85		
	$Z_s$ (cm)			2.00			
	$Z_b$ (cm)					1.27	
	$Z_{MI}$ (cm)	1.27					
	$Z_{pii,\alpha}$ (cm)	1.27					
	$f_{awf}$ (MHz)	4.96	4.93		5.02		5.01
Other Information	$p_{rr}$ (Hz)	699.00					
	$s_{rr}$ (Hz)	/					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ ( $W/cm^2$ )	277.85					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ ( $mW/cm^2$ )	146.63					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ ( $mW/cm^2$ )	235.44					
	$p_r$ at $Z_{pii}$ (MPa)	2.81					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	6.5cm	12.9cm		6.5cm		6.5cm
	SV Position	1.0cm	10.0cm		1.0cm		0.5cm
	Working Frequency	5	5		5		5
	PRF	699	6300		23995		23995
	SV	0.5mm	0.5mm		0.5mm		0.5mm

Transducer Model: 65EL60EA

Imaging Mode: B+PW-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		1.52	0.29		2.28		1.36
Index component value			0.24	0.29	0.74	2.28	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	3.40					
	$P$ (mW)		28.46		32.83		38.96
	$P_{1 \times 1}$ (mW)		10.28		31.17		
	$Z_s$ (cm)			2.00			
	$Z_b$ (cm)					1.27	
	$Z_{MI}$ (cm)	1.27					
	$Z_{pii,\alpha}$ (cm)	1.27					
	$f_{awf}$ (MHz)	5.00	5.42		6.09		5.95
Other Information	$p_{rr}$ (Hz)	699.00					
	$s_{rr}$ (Hz)	58.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ ( $W/cm^2$ )	666.21					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ ( $mW/cm^2$ )	352.01					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ ( $mW/cm^2$ )	545.25					
	$p_r$ at $Z_{pii}$ (MPa)	4.23					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	6.5cm	12.9cm		12.9cm		12.9cm
	B Focus Position	1.0cm	5.0cm		1.0cm		0.5cm
	SV Position	1.0cm	5.0cm		1.0cm		0.5cm
	B Working Frequency	6.5	6.5		6.5		6.5
	PW Working Frequency	5	5		5		5
	B PRF	7694	1276		1276		1276
	PW PRF	699	3595		3595		3595
	PW SV	0.5mm	0.5mm		0.5mm		0.5mm

Transducer Model: 65EL60EA

Imaging Mode: Color+B-Mode / Power+B-Mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.56	0.05		0.04		0.10
Index component value			0.05	0.05	0.04	0.04	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	1.39					
	$P$ (mW)		10.00		10.00		8.00
	$P_{1 \times 1}$ (mW)		1.65		1.65		
	$z_s$ (cm)			/			
	$z_b$ (cm)					/	
	$Z_{MI}$ (cm)	1.46					
	$Z_{pii,\alpha}$ (cm)	1.46					
	$f_{awf}$ (MHz)	6.12	6.28		6.10		6.27
Other Information	$p_{rr}$ (Hz)	5,461.00					
	$s_{rr}$ (Hz)	11.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ (W/cm <sup>2</sup> )	105.82					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	0.74					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ (mW/cm <sup>2</sup> )	1.37					
	$p_r$ at $Z_{pii}$ (MPa)	1.89					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	8.3cm	8.3cm		8.3cm		8.3cm
	B Focus Position	2.0cm	5.0cm		5.0cm		5.0cm
	Color Sampling Gate Position	2.0cm	5.0cm		5.0cm		5.0cm
	B Working Frequency	6.5	6.5		6.5		6.5
	C Working Frequency	5	5		5		5
	B PRF	5461	3593		3593		3593
	Color PRF	2546	5025		5025		5025



Transducer Model: 65EL60EA

Imaging Mode: Color+B+PW-Mode/Power+B+PW-Mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.46	0.12		0.38		0.33
Index component value			0.12	0.12	0.15	0.38	
Acoustic Parameters	$p_{r,\alpha}$ at $z_{MI}$ (MPa)	1.02					
	$P$ (mW)		21.19		19.96		21.40
	$P_{1 \times 1}$ (mW)		4.60		6.39		
	$z_s$ (cm)			1.89			
	$z_b$ (cm)					1.27	
	$z_{MI}$ (cm)	1.27					
	$z_{pii,\alpha}$ (cm)	1.27					
	$f_{awf}$ (MHz)	5.02	6.27		5.31		6.30
Other Information	$p_{rr}$ (Hz)	934.00					
	$s_{rr}$ (Hz)	4.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $z_{pii,\alpha}$ (W/cm <sup>2</sup> )	45.59					
	$I_{spta,\alpha}$ at $z_{pii,\alpha}$ or $z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	0.40					
	$I_{spta}$ at $z_{pii}$ or $z_{sii}$ (mW/cm <sup>2</sup> )	0.63					
	$p_r$ at $z_{pii}$ (MPa)	1.23					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	8.3cm	8.3cm		8.3cm		8.3cm
	B Focus Position	2.0cm	5.0cm		2.0cm		2.5cm
	Color SG Position	2.0cm	5.0cm		2.0cm		2.5cm
	PW SV Position	2.0cm	5.0cm		2.0cm		2.5cm
	B Working Frequency	6.5	6.5		5		6.5
	C Working Frequency	5	5		4.4		5
	PW Working Frequency	4.4	5		5		5
	B PRF	2199	1491		2281		1491
	C PRF	934	1879		965		1879
	PW PRF	3430	3448		3558		3448
	PW SV	0.5mm	0.5mm		0.5mm		0.5mm

# C.9 75L38EA

Transducer Model: 75L38EA

Imaging Mode: M-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.71	0.13		0.26		0.18
Index component value			0.13	0.10	0.11	0.26	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	1.78					
	$P$ (mW)		6.90		2.71		7.22
	$P_{1 \times 1}$ (mW)		4.49		2.71		
	$z_s$ (cm)			1.67			
	$z_b$ (cm)					1.27	
	$Z_{MI}$ (cm)	1.56					
	$Z_{pii,\alpha}$ (cm)	1.56					
	$f_{awf}$ (MHz)	6.19	6.04		5.88		5.82
Other Information	$p_{rr}$ (Hz)	1,999.00					
	$s_{rr}$ (Hz)	/					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ ( $W/cm^2$ )	181.07					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ ( $mW/cm^2$ )	73.05					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ ( $mW/cm^2$ )	147.78					
	$p_r$ at $Z_{pii}$ (MPa)	2.28					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	12.9cm	12.9cm		12.9cm		12.9cm
	Focus position	1.5cm	10.0cm		1.5cm		10.0cm
	Working Frequency	H10.0	H8.0		H8.0		H8.0
	PRF	1999	1999		1999		1999

Transducer Model: 75L38EA

Imaging Mode: B-mode/Smart3D/iScape/Tissue Harmonic Imaging

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.81	0.15		0.32		0.32
Index component value			0.15	0.15	0.32	0.14	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	2.01					
	$P$ (mW)		20.00		20.00		20.00
	$P_{1 \times 1}$ (mW)		5.21		5.21		
	$Z_s$ (cm)			/			
	$Z_b$ (cm)					/	
	$Z_{MI}$ (cm)	1.46					
	$Z_{pii,\alpha}$ (cm)	1.46					
	$f_{awf}$ (MHz)	6.15	5.86		5.76		5.80
Other Information	$p_{rr}$ (Hz)	5,094.00					
	$s_{rr}$ (Hz)	15.00					
	$n_{pps}$	1.33					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ (W/cm <sup>2</sup> )	273.67					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	2.29					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ (mW/cm <sup>2</sup> )	4.25					
	$p_r$ at $Z_{pii}$ (MPa)	2.74					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	12.9cm	12.9cm		12.9cm		12.9cm
	Focus position	1.5cm	10.0cm		10.0cm		10.0cm
	Working Frequency	H10.0	H8.0		H8.0		H8.0
	PRF	5094	5094		5094		5094

Transducer Model: 75L38EA

Imaging Mode: B+M-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		1.06	0.17		0.27		0.33
Index component value			0.17	0.16	0.11	0.27	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	2.55					
	$P$ (mW)		17.83		8.35		18.05
	$P_{1 \times 1}$ (mW)		6.14		3.91		
	$Z_s$ (cm)			1.67			
	$Z_b$ (cm)					0.98	
	$Z_{MI}$ (cm)	1.27					
	$Z_{pii,\alpha}$ (cm)	1.27					
	$f_{awf}$ (MHz)	5.84	5.88		5.91		5.87
Other Information	$prr$ (Hz)	1,000.00					
	$srr$ (Hz)	12.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ (W/cm <sup>2</sup> )	216.04					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	44.18					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ (mW/cm <sup>2</sup> )	73.67					
	$p_r$ at $Z_{pii}$ (MPa)	3.30					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	12.9cm	12.9cm		6.5cm		12.9cm
	B/M Focus position	1.5cm	10.0cm		1.0cm		10.0cm
	B/M Working Frequency	H10.0	H8.0		H8.0		H8.0
	B PRF	4000	4000		7000		4000
	M PRF	1000	1000		2000		1000

Transducer Model: 75L38EA

Imaging Mode: PW-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		1.30	0.55		0.98		0.79
Index component value			0.55	0.44	0.70	0.98	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	3.11					
	$P$ (mW)		31.08		20.82		31.06
	$P_{1 \times 1}$ (mW)		20.23		20.82		
	$Z_s$ (cm)			1.67			
	$Z_b$ (cm)					1.56	
	$Z_{MI}$ (cm)	1.27					
	$Z_{pii,\alpha}$ (cm)	1.27					
	$f_{awf}$ (MHz)	5.70	5.72		5.73		5.76
Other Information	$p_{rr}$ (Hz)	699.00					
	$s_{rr}$ (Hz)	/					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ ( $W/cm^2$ )	476.49					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ ( $mW/cm^2$ )	217.93					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ ( $mW/cm^2$ )	359.05					
	$p_r$ at $Z_{pii}$ (MPa)	3.99					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	6.5cm	12.9cm		12.9cm		12.9cm
	SV Position	1.0cm	10.0cm		3.0cm		10.0cm
	Working Frequency	5.7	5.7		5.7		5.7
	PRF	699	6300		14000		6300
	SV	0.5mm	0.5mm		0.5mm		0.5mm

Transducer Model: 75L38EA

Imaging Mode: B+PW-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		1.33	0.69		0.95		1.01
Index component value			0.69	0.58	0.48	0.95	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	3.17					
	$P$ (mW)		47.14		24.21		45.96
	$P_{1 \times 1}$ (mW)		24.44		19.77		
	$Z_s$ (cm)			1.67			
	$Z_b$ (cm)					2.56	
	$Z_{MI}$ (cm)	1.27					
	$Z_{pii,\alpha}$ (cm)	1.27					
	$f_{awf}$ (MHz)	5.71	7.07		5.55		7.24
Other Information	$p_{rr}$ (Hz)	699.00					
	$s_{rr}$ (Hz)	46.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ ( $W/cm^2$ )	561.33					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ ( $mW/cm^2$ )	254.96					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ ( $mW/cm^2$ )	420.43					
	$p_r$ at $Z_{pii}$ (MPa)	4.07					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	6.5cm	12.9cm		12.9cm		12.9cm
	B Focus Position	1.0cm	10.0cm		3.0cm		10.0cm
	SV Position	1.0cm	10.0cm		3.0cm		10.0cm
	B Working Frequency	7.5	7.5		5		7.5
	PW Working Frequency	5.7	5.7		5		5.7
	B PRF	7694	1276		1276		1276
	PW PRF	699	3594		3594		3594
	PW SV	0.5mm	0.5mm		0.5mm		0.5mm

Transducer Model: 75L38EA

Imaging Mode: Color+B-Mode / Power+B-Mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		1.00	0.11		0.09		0.32
Index component value			0.11	0.11	0.09	0.09	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	2.37					
	$P$ (mW)		14.00		12.00		20.00
	$P_{1 \times 1}$ (mW)		3.65		3.13		
	$z_s$ (cm)			/			
	$z_b$ (cm)					/	
	$Z_{MI}$ (cm)	1.17					
	$Z_{pii,\alpha}$ (cm)	1.17					
	$f_{awf}$ (MHz)	5.66	6.85		6.97		5.24
Other Information	$p_{rr}$ (Hz)	6,346.00					
	$s_{rr}$ (Hz)	23.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ (W/cm <sup>2</sup> )	351.83					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	15.29					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ (mW/cm <sup>2</sup> )	24.17					
	$p_r$ at $Z_{pii}$ (MPa)	2.98					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	8.3cm	8.3cm		8.3cm		8.3cm
	B Focus Position	1.5cm	5.0cm		5.0cm		5.0cm
	Color Sampling Gate Position	1.5cm	5.0cm		5.0cm		5.0cm
	B Working Frequency	7.5	7.5		7.5		5
	C Working Frequency	5.7	5.7		5.7		5
	B PRF	3803	3041		3041		2809
	Color PRF	6346	5336		5336		4928

Transducer Model: 75L38EA

Imaging Mode: Color+B+PW-Mode/Power+B+PW-Mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.95	0.41		1.31		0.73
Index component value			0.41	0.32	0.35	1.31	
Acoustic Parameters	$p_{r,\alpha}$ at $z_{MI}$ (MPa)	2.13					
	$P$ (mW)		31.35		23.33		31.91
	$P_{1 \times 1}$ (mW)		15.39		14.46		
	$z_s$ (cm)			1.56			
	$z_b$ (cm)					0.98	
	$z_{MI}$ (cm)	0.98					
	$z_{pii,\alpha}$ (cm)	0.98					
	$f_{awf}$ (MHz)	5.05	6.00		5.36		6.83
Other Information	$p_{rr}$ (Hz)	4,349.00					
	$s_{rr}$ (Hz)	3.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $z_{pii,\alpha}$ (W/cm <sup>2</sup> )	216.08					
	$I_{spta,\alpha}$ at $z_{pii,\alpha}$ or $z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	684.29					
	$I_{spta}$ at $z_{pii}$ or $z_{sii}$ (mW/cm <sup>2</sup> )	979.24					
	$p_r$ at $z_{pii}$ (MPa)	2.45					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	8.3cm	8.3cm		8.3cm		8.3cm
	B Focus Position	1.0cm	5.0cm		1.0cm		5.0cm
	Color SG Position	1.0cm	5.0cm		1.0cm		5.0cm
	PW SV Position	1.0cm	5.0cm		1.0cm		5.0cm
	B Working Frequency	7.5	7.5		5		7.5
	C Working Frequency	5.7	5.7		5		5.7
	PW Working Frequency	5	5.7		5		5.7
	B PRF	1246	944		1235		944
	C PRF	949	779		941		779
	PW PRF	4349	4391		4311		4391
	PW SV	0.5mm	0.5mm		0.5mm		0.5mm



# C.10 75L53EA

Transducer Model: 75L53EA

Imaging Mode: M-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.56	0.02		0.04		0.03
Index component value			0.02	0.02	0.02	0.04	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	1.28					
	$P$ (mW)		1.33		0.66		1.29
	$P_{1 \times 1}$ (mW)		0.71		0.66		
	$z_s$ (cm)			1.78			
	$z_b$ (cm)					1.36	
	$Z_{MI}$ (cm)	1.84					
	$Z_{pii,\alpha}$ (cm)	1.84					
	$f_{awf}$ (MHz)	5.23	5.23		5.23		5.19
Other Information	$p_{rr}$ (Hz)	2,000.00					
	$s_{rr}$ (Hz)	/					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ ( $W/cm^2$ )	43.28					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ ( $mW/cm^2$ )	19.93					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ ( $mW/cm^2$ )	41.43					
	$p_r$ at $Z_{pii}$ (MPa)	1.75					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	12.9cm	12.9cm		12.9cm		12.9cm
	Focus position	2.0cm	10.0cm		2.0cm		10.0cm
	Working Frequency	H10.0	H10.0		H10.0		H10.0
	PRF	2000	2000		2000		2000

Transducer Model: 75L53EA

Imaging Mode: B-mode/Tissue Harmonic Imaging

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.77	0.07		0.19		0.19
Index component value			0.07	0.07	0.19	0.06	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	1.86					
	$P$ (mW)		14.00		14.00		14.00
	$P_{1 \times 1}$ (mW)		2.64		2.64		
	$Z_s$ (cm)			/			
	$Z_b$ (cm)					/	
	$Z_{MI}$ (cm)	1.65					
	$Z_{pii,\alpha}$ (cm)	1.65					
	$f_{awf}$ (MHz)	5.75	5.31		5.17		5.67
Other Information	$p_{rr}$ (Hz)	5,091.00					
	$s_{rr}$ (Hz)	20.00					
	$n_{pps}$	1.33					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ (W/cm <sup>2</sup> )	98.87					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	1.36					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ (mW/cm <sup>2</sup> )	2.97					
	$p_r$ at $Z_{pii}$ (MPa)	1.86					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	12.9cm	12.9cm		12.9cm		12.9cm
	Focus position	2.0cm	10.0cm		10.0cm		10.0cm
	Working Frequency	H10.0	H10.0		H10.0		H10.0
	PRF	5091	5091		5091		5091

Transducer Model: 75L53EA

Imaging Mode: B+M-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.35	0.09		0.08		0.29
Index component value			0.09	0.09	0.07	0.08	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	0.80					
	$P$ (mW)		18.64		14.37		20.66
	$P_{1 \times 1}$ (mW)		3.74		3.01		
	$Z_s$ (cm)			1.78			
	$Z_b$ (cm)					2.13	
	$Z_{MI}$ (cm)	1.46					
	$Z_{pii,\alpha}$ (cm)	1.46					
	$f_{awf}$ (MHz)	5.27	5.34		5.12		5.37
Other Information	$prr$ (Hz)	4,000.00					
	$srr$ (Hz)	16.00					
	$n_{pps}$	1.33					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ (W/cm <sup>2</sup> )	15.20					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	0.17					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ (mW/cm <sup>2</sup> )	0.29					
	$p_r$ at $Z_{pii}$ (MPa)	1.04					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	12.9cm	12.9cm		6.5cm		12.9cm
	B/M Focus position	2.0cm	10.0cm		1.0cm		10.0cm
	B/M Working Frequency	H10.0	H10.0		H10.0		H10.0
	B PRF	4000	4000		7000		4000
	M PRF	1000	1000		2000		1000

Transducer Model: 75L53EA

Imaging Mode: PW-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.43	0.08		0.32		0.50
Index component value			0.08	0.08	0.32	0.30	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	0.96					
	$P$ (mW)		6.51		8.24		23.36
	$P_{1 \times 1}$ (mW)		3.07		8.24		
	$Z_s$ (cm)			1.89			
	$Z_b$ (cm)					1.08	
	$Z_{MI}$ (cm)	1.17					
	$Z_{pii,\alpha}$ (cm)	1.17					
	$f_{awf}$ (MHz)	4.98		5.61		5.63	
Other Information	$p_{rr}$ (Hz)	699.00					
	$s_{rr}$ (Hz)	/					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ ( $W/cm^2$ )	26.89					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ ( $mW/cm^2$ )	13.98					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ ( $mW/cm^2$ )	21.34					
	$p_r$ at $Z_{pii}$ (MPa)	1.19					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	12.9cm	12.9cm		6.5cm		12.9cm
	SV Position	1.5cm	10.0cm		1.0cm		10.0cm
	Working Frequency	5	5.7		5.7		5.7
	PRF	699	6300		23995		6300
	SV	0.5mm	0.5mm		0.5mm		0.5mm

Transducer Model: 75L53EA

Imaging Mode: B+PW-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.59	0.26		0.33		0.47
Index component value			0.25	0.26	0.22	0.33	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	1.32					
	$P$ (mW)		28.51		14.55		27.90
	$P_{1 \times 1}$ (mW)		8.91		8.06		
	$Z_s$ (cm)			1.89			
	$Z_b$ (cm)					1.08	
	$Z_{MI}$ (cm)	1.27					
	$Z_{pii,\alpha}$ (cm)	1.27					
	$f_{awf}$ (MHz)	5.00	6.61		6.21		6.52
Other Information	$p_{rr}$ (Hz)	699.00					
	$s_{rr}$ (Hz)	33.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ ( $W/cm^2$ )	54.54					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ ( $mW/cm^2$ )	28.38					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ ( $mW/cm^2$ )	45.38					
	$p_r$ at $Z_{pii}$ (MPa)	1.62					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	12.9cm	12.9cm		12.9cm		12.9cm
	B Focus Position	1.5cm	10.0cm		1.0cm		10.0cm
	SV Position	1.5cm	10.0cm		1.0cm		10.0cm
	B Working Frequency	5	7.5		7.5		7.5
	PW Working Frequency	5	5.7		5.7		5.7
	B PRF	4199	1276		1276		1276
	PW PRF	699	3595		3595		3595
	PW SV	0.5mm	0.5mm		0.5mm		0.5mm

Transducer Model: 75L53EA

Imaging Mode: Color+B-Mode / Power+B-Mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.94	0.13		0.13		0.35
Index component value			0.13	0.13	0.13	0.13	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	2.24					
	$P$ (mW)		24.00		24.00		26.00
	$P_{1 \times 1}$ (mW)		4.52		4.52		
	$z_s$ (cm)			/			
	$z_b$ (cm)					/	
	$Z_{MI}$ (cm)	1.17					
	$Z_{pii,\alpha}$ (cm)	1.17					
	$f_{awf}$ (MHz)	5.61	6.48		6.49		5.10
Other Information	$p_{rr}$ (Hz)	6,341.00					
	$s_{rr}$ (Hz)	23.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ (W/cm <sup>2</sup> )	267.48					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	11.59					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ (mW/cm <sup>2</sup> )	18.25					
	$p_r$ at $Z_{pii}$ (MPa)	2.80					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	8.3cm	8.3cm		8.3cm		8.3cm
	B Focus Position	1.5cm	5.0cm		5.0cm		5.0cm
	Color Sampling Gate Position	1.5cm	5.0cm		5.0cm		5.0cm
	B Working Frequency	7.5	7.5		7.5		5
	C Working Frequency	6.6	6.6		6.6		5.7
	B PRF	3800	3039		3039		2807
	Color PRF	6341	5333		5333		4926

Transducer Model: 75L53EA

Imaging Mode: Color+B+PW-Mode/Power+B+PW-Mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.91	0.34		1.59		0.64
Index component value			0.34	0.31	0.51	1.59	
Acoustic Parameters	$p_{r,\alpha}$ at $z_{MI}$ (MPa)	2.03					
	$P$ (mW)		38.82		40.83		38.19
	$P_{1 \times 1}$ (mW)		12.34		21.36		
	$z_s$ (cm)			1.78			
	$z_b$ (cm)					1.08	
	$z_{MI}$ (cm)	1.08					
	$z_{pii,\alpha}$ (cm)	1.08					
	$f_{awf}$ (MHz)	5.01	6.61		5.19		6.60
Other Information	$p_{rr}$ (Hz)	4,311.00					
	$s_{rr}$ (Hz)	3.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $z_{pii,\alpha}$ (W/cm <sup>2</sup> )	195.85					
	$I_{spta,\alpha}$ at $z_{pii,\alpha}$ or $z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	621.14					
	$I_{spta}$ at $z_{pii}$ or $z_{sii}$ (mW/cm <sup>2</sup> )	901.58					
	$p_r$ at $z_{pii}$ (MPa)	2.45					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	8.3cm	8.3cm		8.3cm		8.3cm
	B Focus Position	1.0cm	5.0cm		1.0cm		5.0cm
	Color SG Position	1.0cm	5.0cm		1.0cm		5.0cm
	PW SV Position	1.0cm	5.0cm		1.0cm		5.0cm
	B Working Frequency	5	7.5		5		7.5
	C Working Frequency	5.7	6.6		5.7		6.6
	PW Working Frequency	5	5.7		5		5.7
	B PRF	1235	944		1235		944
	C PRF	941	779		941		779
	PW PRF	4311	4391		4311		4391
	PW SV	0.5mm	0.5mm		0.5mm		0.5mm

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Transducer Model: 75LT38EA

Imaging Mode: M-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.77	0.17		0.14		0.23
Index component value			0.17	0.14	0.11	0.14	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	1.93					
	$P$ (mW)		8.80		2.32		8.22
	$P_{1 \times 1}$ (mW)		5.73		2.32		
	$z_s$ (cm)			1.44			
	$z_b$ (cm)					2.23	
	$Z_{MI}$ (cm)	0.98					
	$Z_{pii,\alpha}$ (cm)	0.98					
	$f_{awf}$ (MHz)	6.22	6.35		5.13		6.12
Other Information	$p_{rr}$ (Hz)	1,999.00					
	$s_{rr}$ (Hz)	/					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ ( $W/cm^2$ )	214.50					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ ( $mW/cm^2$ )	81.71					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ ( $mW/cm^2$ )	124.46					
	$p_r$ at $Z_{pii}$ (MPa)	2.38					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	6.5cm	12.9cm		12.9cm		12.9cm
	Focus position	1.0cm	10.0cm		1.5cm		10.0cm
	Working Frequency	H10.0	H10.0		H10.0		H10.0
	PRF	1999	1999		1999		1999



Transducer Model: 75LT38EA

Imaging Mode: B-mode/Smart3D/iScape/Tissue Harmonic Imaging

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.91	0.12		0.32		0.32
Index component value			0.12	0.12	0.32	0.12	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	2.08					
	$P$ (mW)		18.00		18.00		18.00
	$P_{1 \times 1}$ (mW)		4.69		4.69		
	$Z_s$ (cm)			/			
	$Z_b$ (cm)					/	
	$Z_{MI}$ (cm)	1.46					
	$Z_{pii,\alpha}$ (cm)	1.46					
	$f_{awf}$ (MHz)	5.28	5.50		5.33		5.39
Other Information	$p_{rr}$ (Hz)	8,992.00					
	$s_{rr}$ (Hz)	36.00					
	$n_{pps}$	1.33					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ ( $W/cm^2$ )	173.52					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ ( $mW/cm^2$ )	4.34					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ ( $mW/cm^2$ )	7.40					
	$p_r$ at $Z_{pii}$ (MPa)	2.72					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	6.5cm	12.9cm		12.9cm		12.9cm
	Focus position	1.0cm	10.0cm		10.0cm		10.0cm
	Working Frequency	H10.0	H10.0		H10.0		H10.0
	PRF	8992	5094		5094		5094

Transducer Model: 75LT38EA

Imaging Mode: B+M-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.87	0.16		0.14		0.33
Index component value			0.16	0.15	0.12	0.14	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	2.13					
	$P$ (mW)		16.12		13.78		16.10
	$P_{1 \times 1}$ (mW)		5.81		4.91		
	$Z_s$ (cm)			1.44			
	$Z_b$ (cm)					2.04	
	$Z_{MI}$ (cm)	1.05					
	$Z_{pii,\alpha}$ (cm)	1.05					
	$f_{awf}$ (MHz)	6.08		6.01		5.31	5.85
Other Information	$prr$ (Hz)	2,000.00					
	$srr$ (Hz)	24.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ (W/cm <sup>2</sup> )	265.07					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	100.45					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ (mW/cm <sup>2</sup> )	156.32					
	$p_r$ at $Z_{pii}$ (MPa)	2.65					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	6.5cm	12.9cm		6.5cm		12.9cm
	B/M Focus position	1.0cm	10.0cm		1.0cm		10.0cm
	B/M Working Frequency	H10.0	H10.0		H10.0		H10.0
	B PRF	7000	4000		7000		4000
	M PRF	2000	1000		2000		1000

Transducer Model: 75LT38EA

Imaging Mode: PW-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.71	0.60		1.16		0.95
Index component value			0.60	0.52	0.81	1.16	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	1.65					
	$P$ (mW)		34.33		21.62		33.73
	$P_{1 \times 1}$ (mW)		22.35		21.62		
	$Z_s$ (cm)			1.44			
	$Z_b$ (cm)					2.11	
	$Z_{MI}$ (cm)	0.50					
	$Z_{pii,\alpha}$ (cm)	0.50					
	$f_{awf}$ (MHz)	5.44	5.63		5.64		5.59
Other Information	$p_{rr}$ (Hz)	699.00					
	$s_{rr}$ (Hz)	/					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ ( $W/cm^2$ )	95.06					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ ( $mW/cm^2$ )	38.60					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ ( $mW/cm^2$ )	47.35					
	$p_r$ at $Z_{pii}$ (MPa)	1.25					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	6.5cm	12.9cm		12.9cm		12.9cm
	SV Position	1.0cm	10.0cm		3.0cm		10.0cm
	Working Frequency	5.7	5.7		5.7		5.7
	PRF	699	6300		14000		6300
	SV	0.5mm	0.5mm		0.5mm		0.5mm

Transducer Model: 75LT38EA

Imaging Mode: B+PW-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.64	0.72		1.69		1.23
Index component value			0.72	0.65	0.75	1.69	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	1.49					
	$P$ (mW)		49.40		39.00		49.27
	$P_{1 \times 1}$ (mW)		25.91		31.61		
	$Z_s$ (cm)			1.44			
	$Z_b$ (cm)					2.00	
	$Z_{MI}$ (cm)	0.50					
	$Z_{pii,\alpha}$ (cm)	0.50					
	$f_{awf}$ (MHz)	5.44	7.21		5.08		7.17
Other Information	$p_{rr}$ (Hz)	699.00					
	$s_{rr}$ (Hz)	58.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ ( $W/cm^2$ )	78.42					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ ( $mW/cm^2$ )	31.79					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ ( $mW/cm^2$ )	40.53					
	$p_r$ at $Z_{pii}$ (MPa)	1.14					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	6.5cm	12.9cm		12.9cm		12.9cm
	B Focus Position	1.0cm	10.0cm		3.0cm		10.0cm
	SV Position	1.0cm	10.0cm		3.0cm		10.0cm
	B Working Frequency	7.5	7.5		5		7.5
	PW Working Frequency	5.7	5.7		5		5.7
	B PRF	7694	1276		1276		1276
	PW PRF	699	3594		3594		3594
	PW SV	0.5mm	0.5mm		0.5mm		0.5mm

Transducer Model: 75LT38EA

Imaging Mode: Color+B-Mode / Power+B-Mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.93	0.84		0.82		1.96
Index component value			0.84	0.84	0.82	0.82	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	2.23					
	$P$ (mW)		110.30		111.10		109.70
	$P_{1 \times 1}$ (mW)		28.72		28.93		
	$z_s$ (cm)			/			
	$z_b$ (cm)					/	
	$Z_{MI}$ (cm)	1.17					
	$Z_{pii,\alpha}$ (cm)	1.17					
	$f_{awf}$ (MHz)	5.74	7.34		6.57		5.40
Other Information	$p_{rr}$ (Hz)	6,346.00					
	$s_{rr}$ (Hz)	23.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ (W/cm <sup>2</sup> )	287.35					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	12.72					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ (mW/cm <sup>2</sup> )	20.24					
	$p_r$ at $Z_{pii}$ (MPa)	2.82					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	8.3cm	8.3cm		8.3cm		8.3cm
	B Focus Position	1.5cm	5.0cm		5.0cm		5.0cm
	Color Sampling Gate Position	1.5cm	5.0cm		5.0cm		5.0cm
	B Working Frequency	7.5	7.5		7.5		5
	C Working Frequency	5.7	5.7		5.7		5
	B PRF	3803	3041		3041		2809
	Color PRF	6346	5336		5336		4928

Transducer Model: 75LT38EA

Imaging Mode: Color+B+PW-Mode/Power+B+PW-Mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.81	1.34		1.60		2.48
Index component value			1.34	1.26	1.14	1.60	
Acoustic Parameters	$p_{r,\alpha}$ at $z_{MI}$ (MPa)	1.93					
	$P$ (mW)		150.54		151.77		129.53
	$P_{1 \times 1}$ (mW)		46.42		46.16		
	$z_s$ (cm)			1.33			
	$z_b$ (cm)					0.98	
	$z_{MI}$ (cm)	0.50					
	$z_{pii,\alpha}$ (cm)	0.50					
	$f_{awf}$ (MHz)	5.71		6.79		5.48	6.64
Other Information	$p_{rr}$ (Hz)	949.00					
	$s_{rr}$ (Hz)	3.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $z_{pii,\alpha}$ (W/cm <sup>2</sup> )	144.68					
	$I_{spta,\alpha}$ at $z_{pii,\alpha}$ or $z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	0.83					
	$I_{spta}$ at $z_{pii}$ or $z_{sii}$ (mW/cm <sup>2</sup> )	1.03					
	$p_r$ at $z_{pii}$ (MPa)	2.06					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	8.3cm	8.3cm		8.3cm		8.3cm
	B Focus Position	1.0cm	5.0cm		1.0cm		5.0cm
	Color SG Position	1.0cm	5.0cm		1.0cm		5.0cm
	PW SV Position	1.0cm	5.0cm		1.0cm		5.0cm
	B Working Frequency	7.5	7.5		5		7.5
	C Working Frequency	5.7	5.7		5		5.7
	PW Working Frequency	5	5.7		5		5.7
	B PRF	1246	944		1235		944
	C PRF	949	779		941		779
	PW PRF	4349	4391		4311		4391
	PW SV	0.5mm	0.5mm		0.5mm		0.5mm

# C.12 50L60EAV

Transducer Model: 50L60EAV

Imaging Mode: M-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		1.00	0.38		0.89		0.59
Index component value			0.38	0.29	0.62	0.89	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	2.04					
	$P$ (mW)		26.67		23.90		26.22
	$P_{1 \times 1}$ (mW)		22.22		23.90		
	$z_s$ (cm)			1.78			
	$z_b$ (cm)					3.11	
	$Z_{MI}$ (cm)	2.33					
	$Z_{pii,\alpha}$ (cm)	2.33					
	$f_{awf}$ (MHz)	4.16	3.60		3.66		3.59
Other Information	$p_{rr}$ (Hz)	1,000.00					
	$s_{rr}$ (Hz)	/					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ ( $W/cm^2$ )	138.98					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ ( $mW/cm^2$ )	43.72					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ ( $mW/cm^2$ )	87.66					
	$p_r$ at $Z_{pii}$ (MPa)	2.78					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	12.9cm	12.9cm		12.9cm		12.9cm
	Focus position	4.0cm	10.0cm		5.0cm		10.0cm
	Working Frequency	4	H6.0		H6.0		H6.0
	PRF	1000	1999		1999		1999

Transducer Model: 50L60EAV

Imaging Mode: B-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		1.07	0.18		0.69		0.63
Index component value			0.18	0.18	0.69	0.19	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	2.15					
	$P$ (mW)		62.00		68.00		62.00
	$P_{1 \times 1}$ (mW)		10.33		11.33		
	$Z_s$ (cm)			/			
	$Z_b$ (cm)					/	
	$Z_{MI}$ (cm)	3.11					
	$Z_{pii,\alpha}$ (cm)	3.11					
	$f_{awf}$ (MHz)	4.05	3.62		3.60		3.62
Other Information	$p_{rr}$ (Hz)	5,096.00					
	$s_{rr}$ (Hz)	41.00					
	$n_{pps}$	1.33					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ ( $W/cm^2$ )	179.96					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ ( $mW/cm^2$ )	7.95					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ ( $mW/cm^2$ )	20.09					
	$p_r$ at $Z_{pii}$ (MPa)	3.32					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	12.9cm	12.9cm		12.9cm		12.9cm
	Focus position	4.0cm	10.0cm		10.0cm		9.0cm
	Working Frequency	4	H6.0		H6.0		H6.0
	PRF	5096	5096		5096		5096



Transducer Model: 50L60EAV

Imaging Mode: B+M-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		1.05	0.38		0.75		0.99
Index component value			0.38	0.34	0.38	0.75	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	2.11					
	$P$ (mW)		79.27		61.89		60.19
	$P_{1 \times 1}$ (mW)		22.06		21.89		
	$Z_s$ (cm)			1.78			
	$Z_b$ (cm)					1.17	
	$Z_{MI}$ (cm)	2.78					
	$Z_{pii,\alpha}$ (cm)	2.78					
	$f_{awf}$ (MHz)	4.08		3.62	3.65		3.69
Other Information	$prr$ (Hz)	1,000.00					
	$srr$ (Hz)	32.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ (W/cm <sup>2</sup> )	181.36					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	57.64					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ (mW/cm <sup>2</sup> )	139.49					
	$p_r$ at $Z_{pii}$ (MPa)	3.13					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	12.9cm	12.9cm		6.5cm		6.5cm
	B/M Focus position	4.0cm	10.0cm		1.0cm		1.0cm
	B/M Working Frequency	4	H6.0		H6.0		H6.0
	B PRF	4000	4000		7000		7000
	M PRF	1000	1000		2000		2000

Transducer Model: 50L60EAV

Imaging Mode: PW-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		1.54	0.77		2.27		1.44
Index component value			0.61	0.77	1.52	2.27	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	2.92					
	$P$ (mW)		84.04		92.08		89.84
	$P_{1 \times 1}$ (mW)		35.02		40.92		
	$Z_s$ (cm)			2.56			
	$Z_b$ (cm)					5.67	
	$Z_{MI}$ (cm)	2.82					
	$Z_{pii,\alpha}$ (cm)	2.82					
	$f_{awf}$ (MHz)	3.62	3.66		3.67		3.65
Other Information	$p_{rr}$ (Hz)	699.00					
	$s_{rr}$ (Hz)	/					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ ( $W/cm^2$ )	569.14					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ ( $mW/cm^2$ )	430.33					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ ( $mW/cm^2$ )	879.63					
	$p_r$ at $Z_{pii}$ (MPa)	3.96					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	12.9cm	12.9cm		12.9cm		12.9cm
	SV Position	2.5cm	10.0cm		6.0cm		10.0cm
	Working Frequency	3.5	3.5		3.5		3.5
	PRF	699	6300		9300		6300
	SV	0.5mm	0.5mm		0.5mm		0.5mm

Transducer Model: 50L60EAV

Imaging Mode: B+PW-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		1.30	0.87		2.01		1.82
Index component value			0.74	0.87	0.78	2.01	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	2.46					
	$P$ (mW)		140.29		131.01		139.54
	$P_{1 \times 1}$ (mW)		40.46		42.67		
	$Z_s$ (cm)			2.56			
	$Z_b$ (cm)					5.56	
	$Z_{MI}$ (cm)	2.71					
	$Z_{pii,\alpha}$ (cm)	2.71					
	$f_{awf}$ (MHz)	3.59	4.28		4.44		4.16
Other Information	$p_{rr}$ (Hz)	699.00					
	$s_{rr}$ (Hz)	33.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ ( $W/cm^2$ )	359.42					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ ( $mW/cm^2$ )	267.74					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ ( $mW/cm^2$ )	526.53					
	$p_r$ at $Z_{pii}$ (MPa)	3.25					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	12.9cm	12.9cm		12.9cm		12.9cm
	B Focus Position	2.5cm	10.0cm		6.0cm		10.0cm
	SV Position	2.5cm	10.0cm		6.0cm		10.0cm
	B Working Frequency	4	4		4		4
	PW Working Frequency	3.5	3.5		3.5		3.5
	B PRF	4199	1276		1276		1258
	PW PRF	699	3595		3595		3595
	PW SV	0.5mm	0.5mm		0.5mm		0.5mm

Transducer Model: 50L60EAV

Imaging Mode: Color+B-Mode / Power+B-Mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.87	0.07		0.07		0.24
Index component value			0.07	0.07	0.07	0.07	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	1.65					
	$P$ (mW)		24.30		24.20		23.40
	$P_{1 \times 1}$ (mW)		4.05		4.03		
	$z_s$ (cm)			/			
	$z_b$ (cm)					/	
	$Z_{MI}$ (cm)	3.16					
	$Z_{pii,\alpha}$ (cm)	3.16					
	$f_{awf}$ (MHz)	3.60	4.12		4.12		4.12
Other Information	$p_{rr}$ (Hz)	631.00					
	$s_{rr}$ (Hz)	11.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ (W/cm <sup>2</sup> )	192.43					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	6.12					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ (mW/cm <sup>2</sup> )	13.46					
	$p_r$ at $Z_{pii}$ (MPa)	2.35					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	16.6cm	16.6cm		16.6cm		16.6cm
	B Focus Position	3.0cm	10.0cm		10.0cm		10.0cm
	Color Sampling Gate Position	3.0cm	10.0cm		10.0cm		10.0cm
	B Working Frequency	4	4		4		4
	C Working Frequency	3.5	3.5		3.5		3.5
	B PRF	2775	2775		2775		2775
	Color PRF	631	631		631		631

Transducer Model: 50L60EAV

Imaging Mode: Color+B+PW-Mode/Power+B+PW-Mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.43	0.23		0.62		0.43
Index component value			0.23	0.17	0.24	0.62	
Acoustic Parameters	$p_{r,\alpha}$ at $z_{MI}$ (MPa)	0.81					
	$P$ (mW)		19.73		20.63		20.93
	$P_{1 \times 1}$ (mW)		13.32		13.47		
	$z_s$ (cm)			1.35			
	$z_b$ (cm)					1.35	
	$z_{MI}$ (cm)	0.50					
	$z_{pii,\alpha}$ (cm)	0.50					
	$f_{awf}$ (MHz)	3.60	4.66		4.66		4.66
Other Information	$p_{rr}$ (Hz)	4,279.00					
	$s_{rr}$ (Hz)	5.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $z_{pii,\alpha}$ (W/cm <sup>2</sup> )	21.98					
	$I_{spta,\alpha}$ at $z_{pii,\alpha}$ or $z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	95.76					
	$I_{spta}$ at $z_{pii}$ or $z_{sii}$ (mW/cm <sup>2</sup> )	108.44					
	$p_r$ at $z_{pii}$ (MPa)	0.86					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	3.7cm	3.7cm		3.7cm		3.7cm
	B Focus Position	0.5cm	1.0cm		1.0cm		1.0cm
	Color SG Position	0.5cm	1.0cm		1.0cm		1.0cm
	PW SV Position	0.5cm	1.0cm		1.0cm		1.0cm
	B Working Frequency	5	4		4		4
	C Working Frequency	4	3.5		3.5		3.5
	PW Working Frequency	3.5	3.5		3.5		3.5
	B PRF	1669	1858		1858		1858
	C PRF	652	337		337		337
	PW PRF	4279	8257		8257		8257
	PW SV	0.5mm	0.5mm		0.5mm		0.5mm

# C.13 75L50EAV

Transducer Model: 75L50EAV

Imaging Mode: M-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.25	0.03		0.04		0.02
Index component value			0.03	0.02	0.02	0.04	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	0.63					
	$P$ (mW)		1.79		0.38		0.97
	$P_{1 \times 1}$ (mW)		1.07		0.38		
	$z_s$ (cm)			1.67			
	$z_b$ (cm)					1.46	
	$Z_{MI}$ (cm)	1.27					
	$Z_{pii,\alpha}$ (cm)	1.27					
	$f_{awf}$ (MHz)	6.17	5.26		5.22		5.20
Other Information	$p_{rr}$ (Hz)	1,000.00					
	$s_{rr}$ (Hz)	/					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ ( $W/cm^2$ )	8.59					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ ( $mW/cm^2$ )	1.65					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ ( $mW/cm^2$ )	3.54					
	$p_r$ at $Z_{pii}$ (MPa)	0.70					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	12.9cm	12.9cm		12.9cm		12.9cm
	Focus position	1.5cm	10.0cm		1.5cm		10.0cm
	Working Frequency	7.5	H10.0		H10.0		H10.0
	PRF	1000	1999		1999		1999

Transducer Model: 75L50EAV

Imaging Mode: B-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.97	0.13		0.31		0.14
Index component value			0.13	0.13	0.31	0.13	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	2.44					
	$P$ (mW)		22.00		22.00		10.00
	$P_{1 \times 1}$ (mW)		4.58		4.58		
	$Z_s$ (cm)			/			
	$Z_b$ (cm)					/	
	$Z_{MI}$ (cm)	1.17					
	$Z_{pii,\alpha}$ (cm)	1.17					
	$f_{awf}$ (MHz)	6.31	5.99		5.95		5.16
Other Information	$p_{rr}$ (Hz)	5,086.00					
	$s_{rr}$ (Hz)	41.00					
	$n_{pps}$	1.33					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ (W/cm <sup>2</sup> )	131.39					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	3.44					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ (mW/cm <sup>2</sup> )	5.72					
	$p_r$ at $Z_{pii}$ (MPa)	3.15					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	12.9cm	12.9cm		12.9cm		12.9cm
	Focus position	1.5cm	10.0cm		10.0cm		10.0cm
	Working Frequency	7.5	5		5		H10.0
	PRF	5086	5086		5086		5086

Transducer Model: 75L50EAV

Imaging Mode: B+M-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.27	0.14		0.10		0.37
Index component value			0.14	0.14	0.09	0.10	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	0.70					
	$P$ (mW)		26.20		18.08		26.12
	$P_{1 \times 1}$ (mW)		5.54		3.83		
	$Z_s$ (cm)			1.67			
	$Z_b$ (cm)					1.27	
	$Z_{MI}$ (cm)	1.56					
	$Z_{pii,\alpha}$ (cm)	1.56					
	$f_{awf}$ (MHz)	6.52	5.21		5.17		5.19
Other Information	$prr$ (Hz)	4,000.00					
	$srr$ (Hz)	32.00					
	$n_{pps}$	1.33					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ (W/cm <sup>2</sup> )	10.74					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	0.21					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ (mW/cm <sup>2</sup> )	0.45					
	$p_r$ at $Z_{pii}$ (MPa)	0.95					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	12.9cm	12.9cm		6.5cm		12.9cm
	B/M Focus position	1.5cm	10.0cm		1.0cm		10.0cm
	B/M Working Frequency	7.5	H10.0		H10.0		H10.0
	B PRF	4000	4000		7000		4000
	M PRF	1000	1000		2000		1000



Transducer Model: 75L50EAV

Imaging Mode: PW-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.21	0.00		0.02		0.01
Index component value			0.00	0.00	0.01	0.02	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	0.49					
	$P$ (mW)		0.35		0.21		0.54
	$P_{1 \times 1}$ (mW)		0.18		0.21		
	$Z_s$ (cm)			1.78			
	$Z_b$ (cm)					1.84	
	$Z_{MI}$ (cm)	1.75					
	$Z_{pii,\alpha}$ (cm)	1.75					
	$f_{awf}$ (MHz)	5.59	5.65		5.69		5.66
Other Information	$p_{rr}$ (Hz)	699.00					
	$s_{rr}$ (Hz)	/					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ ( $W/cm^2$ )	7.00					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ ( $mW/cm^2$ )	2.96					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ ( $mW/cm^2$ )	6.04					
	$p_r$ at $Z_{pii}$ (MPa)	0.65					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	12.9cm	12.9cm		12.9cm		12.9cm
	SV Position	1.5cm	10.0cm		1.5cm		10.0cm
	Working Frequency	5.7	5.7		5.7		5.7
	PRF	699	6300		20000		6300
	SV	0.5mm	0.5mm		0.5mm		0.5mm

Transducer Model: 75L50EAV

Imaging Mode: B+PW-mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.23	0.18		0.11		0.38
Index component value			0.18	0.18	0.10	0.11	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	0.55					
	$P$ (mW)		26.37		12.55		26.41
	$P_{1 \times 1}$ (mW)		5.61		3.05		
	$Z_s$ (cm)			1.78			
	$Z_b$ (cm)					2.23	
	$Z_{MI}$ (cm)	1.84					
	$Z_{pii,\alpha}$ (cm)	1.84					
	$f_{awf}$ (MHz)	5.60	6.73		6.80		6.61
Other Information	$p_{rr}$ (Hz)	699.00					
	$s_{rr}$ (Hz)	33.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ ( $W/cm^2$ )	9.77					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ ( $mW/cm^2$ )	4.48					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ ( $mW/cm^2$ )	9.14					
	$p_r$ at $Z_{pii}$ (MPa)	0.79					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	12.9cm	12.9cm		12.9cm		12.9cm
	B Focus Position	1.5cm	10.0cm		2.0cm		10.0cm
	SV Position	1.5cm	10.0cm		2.0cm		10.0cm
	B Working Frequency	7.5	7.5		7.5		7.5
	PW Working Frequency	5.7	5.7		5.7		5.7
	B PRF	4198	1258		1276		4198
	PW PRF	699	3594		3594		699
	PW SV	0.5mm	0.5mm		0.5mm		0.5mm

Transducer Model: 75L50EAV

Imaging Mode: Color+B-Mode / Power+B-Mode

Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		0.98	0.17		0.17		0.40
Index component value			0.17	0.17	0.17	0.17	
Acoustic Parameters	$p_{r,\alpha}$ at $Z_{MI}$ (MPa)	2.31					
	$P$ (mW)		28.00		28.00		28.00
	$P_{1 \times 1}$ (mW)		5.83		5.83		
	$z_s$ (cm)			/			
	$z_b$ (cm)					/	
	$Z_{MI}$ (cm)	1.18					
	$Z_{pii,\alpha}$ (cm)	1.18					
	$f_{awf}$ (MHz)	5.59	6.81		6.81		5.93
Other Information	$p_{rr}$ (Hz)	2,642.00					
	$s_{rr}$ (Hz)	47.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $Z_{pii,\alpha}$ (W/cm <sup>2</sup> )	209.16					
	$I_{spta,\alpha}$ at $Z_{pii,\alpha}$ or $Z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	18.95					
	$I_{spta}$ at $Z_{pii}$ or $Z_{sii}$ (mW/cm <sup>2</sup> )	29.90					
	$p_r$ at $Z_{pii}$ (MPa)	2.90					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	16.6cm	16.6cm		16.6cm		16.6cm
	B Focus Position	1.5cm	8.0cm		8.0cm		7.0cm
	Color Sampling Gate Position	1.5cm	8.0cm		8.0cm		7.0cm
	B Working Frequency	5	5		5		5
	C Working Frequency	5	5		5		5
	B PRF	802	1605		1605		1605
	Color PRF	2642	3498		3498		3498

Transducer Model: 75L50EAV

Imaging Mode: Color+B+PW-Mode/Power+B+PW-Mode


Index label		MI	TIS		TIB		TIC
			At surface	Below surface	At surface	Below surface	
Maximum index value		1.08	0.21		1.39		0.48
Index component value			0.21	0.20	0.38	1.39	
Acoustic Parameters	$p_{r,\alpha}$ at $z_{MI}$ (MPa)	2.42					
	$P$ (mW)		27.80		36.39		29.80
	$P_{1 \times 1}$ (mW)		7.21		14.22		
	$z_s$ (cm)			0.95			
	$z_b$ (cm)					1.10	
	$z_{MI}$ (cm)	1.03					
	$z_{pii,\alpha}$ (cm)	1.03					
	$f_{awf}$ (MHz)	5.05	7.09		5.97		7.09
Other Information	$p_{rr}$ (Hz)	12,767.00					
	$s_{rr}$ (Hz)	30.00					
	$n_{pps}$	/					
	$I_{pa,\alpha}$ at $z_{pii,\alpha}$ (W/cm <sup>2</sup> )	276.05					
	$I_{spta,\alpha}$ at $z_{pii,\alpha}$ or $z_{sii,\alpha}$ (mW/cm <sup>2</sup> )	18.23					
	$I_{spta}$ at $z_{pii}$ or $z_{sii}$ (mW/cm <sup>2</sup> )	26.45					
	$p_r$ at $z_{pii}$ (MPa)	2.76					
Operating control conditions	Acoustic power	100%	100%		100%		100%
	Display depth	3.7cm	3.7cm		3.7cm		3.7cm
	B Focus Position	0.5cm	0.5cm		1.0cm		0.5cm
	Color SG Position	0.5cm	0.5cm		1.0cm		0.5cm
	PW SV Position	0.5cm	0.5cm		1.0cm		0.5cm
	B Working Frequency	5	7.5		5		5
	C Working Frequency	5	5.7		5		5
	PW Working Frequency	5	5		5		5
	B PRF	4012	1677		1861		1677
	C PRF	12767	19572		337		19572
	PW PRF	699	699		8273		699
	PW SV	0.5mm	0.5mm		0.5mm		0.5mm

# Appendix D Printer Adapter

The printer adapter (LPA11) enables printers to be used with the Ultrasound system.

## D.1 Safety Precautions

Please observe the following precautions to ensure patient and operator safety when using this system.

 <b>WARNING:</b>	<ol style="list-style-type: none"><li>1. <b>Connect the power plug of this system to wall receptacles that meet the ratings indicated on the nameplate.</b></li><li>2. <b>Within 1.5 meters of the patient, connect Printer Adapter to an auxiliary power outlet through specified power adapter by an auxiliary power cable according to chapter 2.2 system connection which complies with IEC 60601-1: 2014 Chapter 16 or a power input of the same safety level.</b></li><li>3. <b>DO NOT use different power supplies to Printer Adapter, or directly connect power adapter to wall receptacles.</b></li><li>4. <b>When using Graph/text printer/ digital video printer which are not powered by the ultrasound system's auxiliary output, ensure these peripherals directly connect to wall receptacles. If peripherals other than those permitted by Mindray used within patient environment, user should ensure the overall leakage current of peripherals and the ultrasound system meets the requirement of the local medical device electrical regulations (e.g., the touch leakage current should be no more than 500uA as per IEC 60601-1: 2014 Chapter 16), and the responsibility is held by the user.</b></li><li>5. <b>Before cleaning the system, disconnect all the power cord from the outlet. Failure to do so may result in system failure and electric shock.</b></li><li>6. <b>Please perform periodical clean to the printer adapter. Do not drop or disassemble the printer adapter. Use the specified power input. Read the instructions for use.</b></li></ol>
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## D.2 Supported Printer Type

The printer adapter supports the following printers:

Type	Model
Graph/text printer	HP Officejet Pro 8100
	EPSON L130
	HP L1020PLUS
	EPSON L310
Video printer	SONY UP-D25MD

Type	Model
	SONY X898MD

